

Polynomial-degree-robust a posteriori error estimation for the curl-curl problem

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Outline

1 Introduction

2 Reminder on the H^1 -case

3 The $H(\text{curl})$ -case

4 $H(\text{curl})$ patchwise equilibration

5 Stable (broken) $H(\text{curl})$ polynomial extensions

6 Numerical experiments

7 Conclusions

The curl-curl problem (current density $\mathbf{j} \in \mathbf{H}_{0,\text{N}}(\text{div}, \Omega)$ with $\nabla \cdot \mathbf{j} = 0$)

The curl-curl problem

Find the magnetic vector potential $\mathbf{A} : \Omega \rightarrow \mathbb{R}^3$ such that

$$\nabla \times (\nabla \times \mathbf{A}) = \mathbf{j}, \quad \nabla \cdot \mathbf{A} = 0 \quad \text{in } \Omega,$$

$$\mathbf{A} \times \mathbf{n}_\Omega = \mathbf{0}, \quad \text{on } \Gamma_D,$$

$$(\nabla \times \mathbf{A}) \times \mathbf{n}_\Omega = \mathbf{0}, \quad \mathbf{A} \cdot \mathbf{n}_\Omega = 0 \quad \text{on } \Gamma_N.$$

Weak formulation (consequence)

$\mathbf{A} \in \mathbf{H}_{0,D}(\text{curl}, \Omega)$ satisfies

$$(\nabla \times \mathbf{A}, \nabla \times \mathbf{v}) = (\mathbf{j}, \mathbf{v}) \quad \forall \mathbf{v} \in \mathbf{H}_{0,D}(\text{curl}, \Omega).$$

Nédélec finite element discretization (consequence)

$\mathbf{V}_h := \mathcal{N}_p(\mathcal{T}_h) \cap \mathbf{H}_{0,D}(\text{curl}, \Omega)$, $p \geq 0$; $\mathbf{A}_h \in \mathbf{V}_h$ satisfies

$$(\nabla \times \mathbf{A}_h, \nabla \times \mathbf{v}_h) = (\mathbf{j}, \mathbf{v}_h) \quad \forall \mathbf{v}_h \in \mathbf{V}_h.$$

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Bibliography

Residual estimates

- Monk (1998)
- Beck, Hiptmair, Hoppe, & Wohlmuth (2000)
- Nicaise & Creusé (2003)

Functional estimates

- Repin (2007)
- Hannukainen (2008)
- Neittaanmäki & Repin (2010)

Equilibrated estimates

- Braess & Schöberl (2008): patchwise minimizations (lowest-order case $p = 0$)
- Licht (2019): a conceptual discussion
- Gedicke, Geevers, & Perugia (2020): equilibrated-residual-style construction
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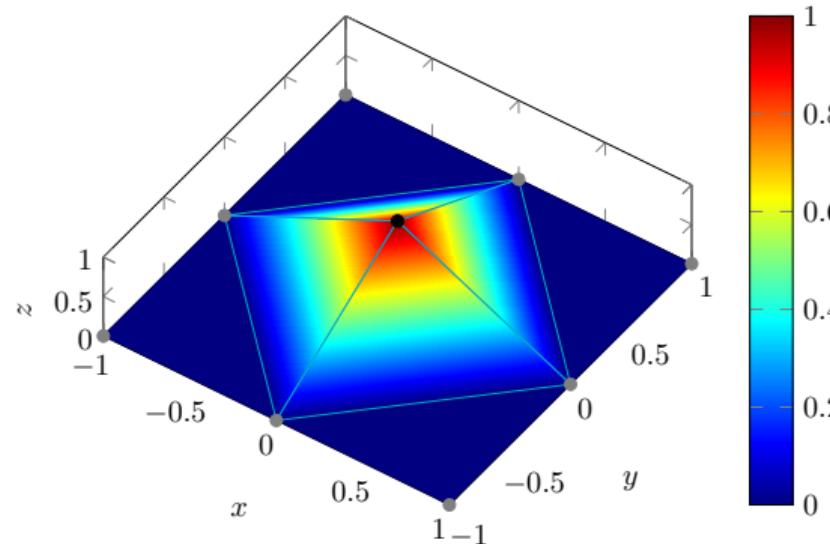
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The hat function and the partition of unity, $\Omega \subset \mathbb{R}^d$



The hat function ψ^a , $d = 2$

Partition of unity

$$\sum_{\mathbf{a} \in \mathcal{V}_h} \psi^{\mathbf{a}} = 1|_{\Omega}$$

The Laplacian $-\Delta u = f$ in Ω , $u = 0$ on $\partial\Omega$

Weak solution $u \in H_0^1(\Omega)$ is such that

$$(\nabla u, \nabla v) = (f, v) \quad \forall v \in H_0^1(\Omega)$$

Approximation $u_h \in H_0^1(\Omega)$ satisfies

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Residual $\mathcal{R}(u_h) \in H^{-1}(\Omega)$ is defined by

$$\langle \mathcal{R}(u_h), v \rangle := (f, v) - (\nabla u_h, \nabla v)$$

Norm characterization

$$\|\nabla(u - u_h)\| = \|\mathcal{R}(u_h)\|_{-1} = \sup_{\substack{v \in H_0^1(\Omega) \\ \|\nabla v\|=1}} \langle \mathcal{R}(u_h), v \rangle$$

$$H_*^1(\omega_\mathbf{a}) := \begin{cases} \{v \in H^1(\omega_\mathbf{a}); (v, 1)_{\omega_\mathbf{a}} = 0\} & \text{for interior vertex } \mathbf{a} \in \mathcal{V}_h^{\text{int}} \\ \{v \in H^1(\omega_\mathbf{a}); v = 0 \text{ on faces sharing } \mathbf{a}\} & \text{for boundary vertex } \mathbf{a} \in \mathcal{V}_h^{\text{ext}} \end{cases}$$

$\psi^\mathbf{a}$ -weighted residual on $H_*^1(\omega_\mathbf{a})'$

$$\|\nabla(u - u_h)\| \leq (d+1)^{1/2}$$

$$\left\{ \sum_{\mathbf{a} \in \mathcal{V}_h} \left[\sup_{\substack{v \in H_*^1(\omega_\mathbf{a}) \\ \|\nabla v\|_{\omega_\mathbf{a}}=1}} \langle \mathcal{R}(u_h), \psi^\mathbf{a} v \rangle \right]^2 \right\}^{1/2}$$

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$$\|\nabla(u - u_h)\| \leq (d+1)^{1/2} C_{\text{cont,PF}}$$

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Unweighted residual on $H_0^1(\omega_{\mathbf{a}})'$

$$\|\nabla(u - u_h)\| \leq (d+1)^{1/2} C_{\text{cont,PF}} \left\{ \sum_{\mathbf{a} \in \mathcal{V}_h} \left[\sup_{\substack{v \in H_0^1(\omega_{\mathbf{a}}) \\ \|\nabla v\|_{\omega_{\mathbf{a}}}=1}} \langle \mathcal{R}(u_h), v \rangle \right]^2 \right\}^{1/2}$$

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$$\|\nabla(u - u_h)\| \leq (d + 1)^{1/2} C_{\text{cont,PF}} \left\{ \sum_{\mathbf{a} \in \mathcal{V}_h} \left[\sup_{\substack{v \in H_0^1(\omega_{\mathbf{a}}) \\ \|\nabla v\|_{\omega_{\mathbf{a}}}=1}} \langle \mathcal{R}(u_h), v \rangle \right]^2 \right\}^{1/2}$$

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Unweighted residual on $H_0^1(\omega_{\mathbf{a}})'$

$$\|\nabla(u - u_h)\| \leq (d + 1)^{1/2} C_{\text{cont,PF}} \left\{ \sum_{\mathbf{a} \in \mathcal{V}_h} \left[\sup_{\substack{v \in H_0^1(\omega_{\mathbf{a}}) \\ \|\nabla v\|_{\omega_{\mathbf{a}}}=1}} \langle \mathcal{R}(u_h), v \rangle \right]^2 \right\}^{1/2}$$

Bound by $\psi^{\mathbf{a}}$ -weighted residuals on $H_*^1(\omega_{\mathbf{a}})'$

$v \in H_0^1(\Omega)$, $\|\nabla v\| = 1$:

$$\begin{aligned}
 \langle \mathcal{R}(u_h), v \rangle &\stackrel{\text{PU}}{=} \left\langle \mathcal{R}(u_h), \sum_{\mathbf{a} \in \mathcal{V}_h} (\psi^{\mathbf{a}} v) \right\rangle \stackrel{\text{GO}}{=} \sum_{\mathbf{a} \in \mathcal{V}_h} \langle \mathcal{R}(u_h), \psi^{\mathbf{a}}(v - \tilde{\Pi}_0 v) \rangle \\
 &= \sum_{\mathbf{a} \in \mathcal{V}_h} \frac{\langle \mathcal{R}(u_h), \psi^{\mathbf{a}}(v - \tilde{\Pi}_0 v) \rangle}{\|\nabla v\|_{\omega_{\mathbf{a}}}} \|\nabla v\|_{\omega_{\mathbf{a}}} \\
 &\stackrel{\text{CS}}{\leq} \left\{ \sum_{\mathbf{a} \in \mathcal{V}_h} \left[\sup_{\substack{w \in H_*^1(\omega_{\mathbf{a}}) \\ \|\nabla w\|_{\omega_{\mathbf{a}}} = 1}} \langle \mathcal{R}(u_h), \psi^{\mathbf{a}} w \rangle \right]^2 \right\}^{1/2} \left\{ \sum_{\mathbf{a} \in \mathcal{V}_h} \|\nabla v\|_{\omega_{\mathbf{a}}}^2 \right\}^{1/2} \\
 &\stackrel{\text{overlaps}}{\leq} (d+1)^{1/2} \left\{ \sum_{\mathbf{a} \in \mathcal{V}_h} \left[\sup_{\substack{w \in H_*^1(\omega_{\mathbf{a}}) \\ \|\nabla w\|_{\omega_{\mathbf{a}}} = 1}} \langle \mathcal{R}(u_h), \psi^{\mathbf{a}} w \rangle \right]^2 \right\}^{1/2}
 \end{aligned}$$

Bound by unweighted residuals on $H_0^1(\omega_{\mathbf{a}})'$

for $v \in H_*^1(\omega_{\mathbf{a}})$:

$$\|\nabla(\psi^{\mathbf{a}} v)\|_{\omega_{\mathbf{a}}} \leq \|\nabla \psi^{\mathbf{a}} v\|_{\omega_{\mathbf{a}}} + \|\psi^{\mathbf{a}} \nabla v\|_{\omega_{\mathbf{a}}} \leq \underbrace{(1 + C_{\text{PF}} h_{\omega_{\mathbf{a}}} \|\nabla \psi^{\mathbf{a}}\|_{\infty, \omega_{\mathbf{a}}})}_{\leq C_{\text{cont,PF}}} \|\nabla v\|_{\omega_{\mathbf{a}}}$$

bound for the $\psi^{\mathbf{a}}$ -weighted residual on $H_*^1(\omega_{\mathbf{a}})'$, since $\psi^{\mathbf{a}} v \in H_0^1(\omega_{\mathbf{a}})$ for $v \in H_*^1(\omega_{\mathbf{a}})$:

$$\begin{aligned} \sup_{\substack{v \in H_*^1(\omega_{\mathbf{a}}) \\ \|\nabla v\|_{\omega_{\mathbf{a}}} = 1}} \langle \mathcal{R}(u_h), \psi^{\mathbf{a}} v \rangle &= \sup_{v \in H_*^1(\omega_{\mathbf{a}})} \frac{\langle \mathcal{R}(u_h), \psi^{\mathbf{a}} v \rangle}{\|\nabla v\|_{\omega_{\mathbf{a}}}} = \sup_{v \in H_*^1(\omega_{\mathbf{a}})} \frac{\langle \mathcal{R}(u_h), \psi^{\mathbf{a}} v \rangle}{\|\nabla(\psi^{\mathbf{a}} v)\|_{\omega_{\mathbf{a}}}} \frac{\|\nabla(\psi^{\mathbf{a}} v)\|_{\omega_{\mathbf{a}}}}{\|\nabla v\|_{\omega_{\mathbf{a}}}} \\ &\leq C_{\text{cont,PF}} \sup_{\substack{v \in H_0^1(\omega_{\mathbf{a}}) \\ \|\nabla v\|_{\omega_{\mathbf{a}}} = 1}} \langle \mathcal{R}(u_h), v \rangle \end{aligned}$$

Patchwise bounds by equilibrated fluxes

$\psi^{\mathbf{a}}$ -weighted residual on $H_*^1(\omega_{\mathbf{a}})'$

for $v \in H_*^1(\omega_{\mathbf{a}})$ with $\|\nabla v\|_{\omega_{\mathbf{a}}} = 1$ and
 $\sigma_h^{\mathbf{a}} \in H(\text{div}, \omega_{\mathbf{a}})$ with $\sigma_h^{\mathbf{a}} \cdot \mathbf{n}|_{\partial\omega_{\mathbf{a}}} = 0$ on $\partial\omega_{\mathbf{a}}$
and $\nabla \cdot \sigma_h^{\mathbf{a}} = f\psi^{\mathbf{a}} - \nabla u_h \cdot \nabla \psi^{\mathbf{a}}$,

$$\begin{aligned} & \langle \mathcal{R}(u_h), \psi^{\mathbf{a}} v \rangle \\ &= (f, \psi^{\mathbf{a}} v)_{\omega_{\mathbf{a}}} - (\nabla u_h, \nabla(\psi^{\mathbf{a}} v))_{\omega_{\mathbf{a}}} \\ &= (f\psi^{\mathbf{a}} - \nabla u_h \cdot \nabla \psi^{\mathbf{a}}, v)_{\omega_{\mathbf{a}}} - (\psi^{\mathbf{a}} \nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \\ &= (\nabla \cdot \sigma_h^{\mathbf{a}}, v)_{\omega_{\mathbf{a}}} - (\psi^{\mathbf{a}} \nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \end{aligned}$$

Green
 $\underline{=} -(\psi^{\mathbf{a}} \nabla u_h + \sigma_h^{\mathbf{a}}, \nabla v)_{\omega_{\mathbf{a}}}$

CS
 $\leq \|\psi^{\mathbf{a}} \nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}}$

$$\sup_{\substack{v \in H_*^1(\omega_{\mathbf{a}}) \\ \|\nabla v\|_{\omega_{\mathbf{a}}} = 1}} \langle \mathcal{R}(u_h), \psi^{\mathbf{a}} v \rangle \leq \|\psi^{\mathbf{a}} \nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}}$$

Unweighted residual on $H_0^1(\omega_{\mathbf{a}})'$

$$\begin{aligned} & \text{for } v \in H_0^1(\omega_{\mathbf{a}}) \text{ with } \|\nabla v\|_{\omega_{\mathbf{a}}} = 1 \text{ and} \\ & \sigma_h^{\mathbf{a}} \in H(\text{div}, \omega_{\mathbf{a}}) \text{ with } \boxed{\nabla \cdot \sigma_h^{\mathbf{a}} = f}, \\ & \langle \mathcal{R}(u_h), v \rangle = (f, v)_{\omega_{\mathbf{a}}} - (\nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \\ &= (\nabla \cdot \sigma_h^{\mathbf{a}}, v)_{\omega_{\mathbf{a}}} - (\nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \\ &\stackrel{\text{Green}}{=} -(\nabla u_h + \sigma_h^{\mathbf{a}}, \nabla v)_{\omega_{\mathbf{a}}} \\ &\stackrel{\text{CS}}{\leq} \|\nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}} \end{aligned}$$

$$\sup_{\substack{v \in H_0^1(\omega_{\mathbf{a}}) \\ \|\nabla v\|_{\omega_{\mathbf{a}}} = 1}} \langle \mathcal{R}(u_h), v \rangle \leq \|\nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}}$$

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and $\nabla \cdot \sigma_h^{\mathbf{a}} = f \psi^{\mathbf{a}} - \nabla u_h \cdot \nabla \psi^{\mathbf{a}}$,

$$\begin{aligned} & \langle \mathcal{R}(u_h), \psi^{\mathbf{a}} v \rangle \\ &= (f, \psi^{\mathbf{a}} v)_{\omega_{\mathbf{a}}} - (\nabla u_h, \nabla(\psi^{\mathbf{a}} v))_{\omega_{\mathbf{a}}} \\ &= (f \psi^{\mathbf{a}} - \nabla u_h \cdot \nabla \psi^{\mathbf{a}}, v)_{\omega_{\mathbf{a}}} - (\psi^{\mathbf{a}} \nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \\ &= (\nabla \cdot \sigma_h^{\mathbf{a}}, v)_{\omega_{\mathbf{a}}} - (\psi^{\mathbf{a}} \nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \end{aligned}$$

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$$\sup_{\substack{v \in H_*^1(\omega_{\mathbf{a}}) \\ \|\nabla v\|_{\omega_{\mathbf{a}}} = 1}} \langle \mathcal{R}(u_h), \psi^{\mathbf{a}} v \rangle \leq \|\psi^{\mathbf{a}} \nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}}$$

Unweighted residual on $H_0^1(\omega_{\mathbf{a}})'$

$$\begin{aligned} & \text{for } v \in H_0^1(\omega_{\mathbf{a}}) \text{ with } \|\nabla v\|_{\omega_{\mathbf{a}}} = 1 \text{ and} \\ & \sigma_h^{\mathbf{a}} \in \mathbf{H}(\text{div}, \omega_{\mathbf{a}}) \text{ with } \nabla \cdot \sigma_h^{\mathbf{a}} = f, \\ & \langle \mathcal{R}(u_h), v \rangle = (f, v)_{\omega_{\mathbf{a}}} - (\nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \\ &= (\nabla \cdot \sigma_h^{\mathbf{a}}, v)_{\omega_{\mathbf{a}}} - (\nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \\ &\stackrel{\text{Green}}{=} -(\nabla u_h + \sigma_h^{\mathbf{a}}, \nabla v)_{\omega_{\mathbf{a}}} \\ &\stackrel{\text{CS}}{\leq} \|\nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}} \end{aligned}$$

$$\sup_{\substack{v \in H_0^1(\omega_{\mathbf{a}}) \\ \|\nabla v\|_{\omega_{\mathbf{a}}} = 1}} \langle \mathcal{R}(u_h), v \rangle \leq \|\nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}}$$

Patchwise bounds by equilibrated fluxes

$\psi^{\mathbf{a}}$ -weighted residual on $H_*^1(\omega_{\mathbf{a}})'$

for $v \in H_*^1(\omega_{\mathbf{a}})$ with $\|\nabla v\|_{\omega_{\mathbf{a}}} = 1$ and
 $\sigma_h^{\mathbf{a}} \in \mathbf{H}(\text{div}, \omega_{\mathbf{a}})$ with $\sigma_h^{\mathbf{a}} \cdot \mathbf{n}|_{\partial\omega_{\mathbf{a}}} = 0$ on $\partial\omega_{\mathbf{a}}$
and $\nabla \cdot \sigma_h^{\mathbf{a}} = f \psi^{\mathbf{a}} - \nabla u_h \cdot \nabla \psi^{\mathbf{a}}$,

$$\begin{aligned} & \langle \mathcal{R}(u_h), \psi^{\mathbf{a}} v \rangle \\ &= (f, \psi^{\mathbf{a}} v)_{\omega_{\mathbf{a}}} - (\nabla u_h, \nabla(\psi^{\mathbf{a}} v))_{\omega_{\mathbf{a}}} \\ &= (f \psi^{\mathbf{a}} - \nabla u_h \cdot \nabla \psi^{\mathbf{a}}, v)_{\omega_{\mathbf{a}}} - (\psi^{\mathbf{a}} \nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \\ &= (\nabla \cdot \sigma_h^{\mathbf{a}}, v)_{\omega_{\mathbf{a}}} - (\psi^{\mathbf{a}} \nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \\ &\stackrel{\text{Green}}{=} -(\psi^{\mathbf{a}} \nabla u_h + \sigma_h^{\mathbf{a}}, \nabla v)_{\omega_{\mathbf{a}}} \\ &\stackrel{\text{CS}}{\leq} \|\psi^{\mathbf{a}} \nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}} \end{aligned}$$

$$\sup_{\substack{v \in H_*^1(\omega_{\mathbf{a}}) \\ \|\nabla v\|_{\omega_{\mathbf{a}}} = 1}} \langle \mathcal{R}(u_h), \psi^{\mathbf{a}} v \rangle \leq \|\psi^{\mathbf{a}} \nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}}$$

Unweighted residual on $H_0^1(\omega_{\mathbf{a}})'$

$$\begin{aligned} & \text{for } v \in H_0^1(\omega_{\mathbf{a}}) \text{ with } \|\nabla v\|_{\omega_{\mathbf{a}}} = 1 \text{ and} \\ & \sigma_h^{\mathbf{a}} \in \mathbf{H}(\text{div}, \omega_{\mathbf{a}}) \text{ with } \nabla \cdot \sigma_h^{\mathbf{a}} = f, \\ & \langle \mathcal{R}(u_h), v \rangle = (f, v)_{\omega_{\mathbf{a}}} - (\nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \\ &= (\nabla \cdot \sigma_h^{\mathbf{a}}, v)_{\omega_{\mathbf{a}}} - (\nabla u_h, \nabla v)_{\omega_{\mathbf{a}}} \\ &\stackrel{\text{Green}}{=} -(\nabla u_h + \sigma_h^{\mathbf{a}}, \nabla v)_{\omega_{\mathbf{a}}} \\ &\stackrel{\text{CS}}{\leq} \|\nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}} \end{aligned}$$

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Patchwise bounds by equilibrated fluxes

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Patchwise bounds by equilibrated fluxes

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Patchwise bounds by equilibrated fluxes

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$$\text{Green} \quad \equiv -(\psi^{\mathbf{a}} \nabla u_h + \sigma_h^{\mathbf{a}}, \nabla v)_{\omega_{\mathbf{a}}}$$

CS

$$\leq \|\psi^{\mathbf{a}} \nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}}$$

$$\sup_{\substack{v \in H_*^1(\omega_{\mathbf{a}}) \\ \|\nabla v\|_{\omega_{\mathbf{a}}} = 1}} \langle \mathcal{R}(u_h), \psi^{\mathbf{a}} v \rangle \leq \|\psi^{\mathbf{a}} \nabla u_h + \sigma_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}}$$

Unweighted residual on $H_0^1(\omega_{\mathbf{a}})'$

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Patchwise bounds by equilibrated fluxes

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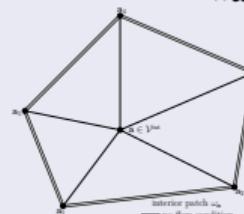
Discrete patchwise/broken patchwise equilibrated fluxes

Definition (Destuynder and Métivet (1999) & Braess and Schöberl (2008))

For each vertex $a \in \mathcal{V}_h$, solve the **local constrained minimization pb**

$$\sigma_h^a := \arg \min_{\substack{\mathbf{v}_h \in \mathcal{RT}_{p+1}(\mathcal{T}_a) \cap H_0(\text{div}, \omega_a) \\ \nabla \cdot \mathbf{v}_h = \Pi_{p+1}(f\psi^a - \nabla u_h \cdot \nabla \psi^a)}} \|\psi^a \nabla u_h + \mathbf{v}_h\|_{\omega_a}^2$$

and combine $\sigma_h := \sum_{a \in \mathcal{V}_h} \sigma_h^a$.



Key points

- homogeneous normal BC on $\partial \omega_a$:

$$\sigma_h \in \mathcal{RT}_{p+1}(\mathcal{T}_h) \cap H(\text{div}, \Omega)$$

- global equilibrium $\nabla \cdot \sigma_h = \sum_{a \in \mathcal{V}_h} \nabla \cdot \sigma_h^a$

$$= \sum_{a \in \mathcal{V}_h} \Pi_{p+1}(f\psi^a - \nabla u_h \cdot \nabla \psi^a) = \Pi_{p+1} f$$

• no BC on $\partial \omega_a$ (Dirichlet)

For each vertex $a \in \mathcal{V}_h$, solve the **local constrained minimization pb**

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Key points

- no BC on $\partial \omega_a$:

$$\sigma_h = \sum_{a \in \mathcal{V}_h} \sigma_h^a \notin H(\text{div}, \Omega)$$

- only local equilibrium $\nabla \cdot \sigma_h^a = \Pi_{p+1} f$

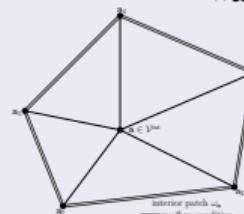
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Key points

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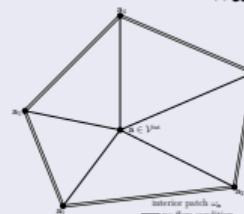
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Definition (Chaumont-Frelet, Ern, Vohralík (2021))

For each vertex $a \in \mathcal{V}_h$, solve the **local constrained minimization pb**

$$\sigma_h^a := \arg \min_{\mathbf{v}_h \in \mathcal{RT}_{p+1}(\mathcal{T}_a)} \|\nabla u_h + \mathbf{v}_h\|_{\omega_a}^2$$

$\nabla \cdot \mathbf{v}_h =$

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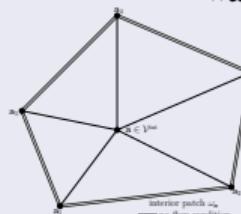
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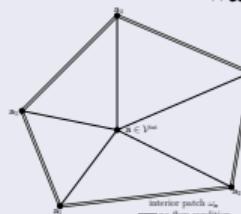
Definition ([Destuynder and Métivet \(1999\)](#) & [Braess and Schöberl \(2008\)](#))

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$$\boldsymbol{\sigma}_h^{\mathbf{a}} := \arg \min_{\mathbf{v}_h \in \mathcal{RT}_{p+1}(\mathcal{T}_{\mathbf{a}}) \cap \mathbf{H}_0(\text{div}, \omega_{\mathbf{a}})} \|\psi^{\mathbf{a}} \nabla u_h + \mathbf{v}_h\|_{\omega_{\mathbf{a}}}^2$$

$$\nabla \cdot \mathbf{v}_h = \Pi_{p+1}(f \psi^{\mathbf{a}} - \nabla u_h \cdot \nabla \psi^{\mathbf{a}})$$

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Key points

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- $\boldsymbol{\sigma}_h = \sum_{\mathbf{a} \in \mathcal{V}_h} \boldsymbol{\sigma}_h^{\mathbf{a}} \notin \mathbf{H}(\text{div}, \Omega)$
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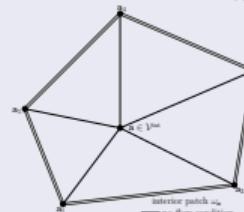
Discrete patchwise/broken patchwise equilibrated fluxes

Definition (Destuynder and Métivet (1999) & Braess and Schöberl (2008))

For each vertex $\mathbf{a} \in \mathcal{V}_h$, solve the **local constrained minimization pb**

$$\boldsymbol{\sigma}_h^{\mathbf{a}} := \arg \min_{\begin{array}{l} \mathbf{v}_h \in \mathcal{RT}_{p+1}(\mathcal{T}_h) \cap \mathbf{H}_0(\text{div}, \omega_{\mathbf{a}}) \\ \nabla \cdot \mathbf{v}_h = \Pi_{p+1}(f \psi^{\mathbf{a}} - \nabla u_h \cdot \nabla \psi^{\mathbf{a}}) \end{array}} \| \psi^{\mathbf{a}} \nabla u_h + \mathbf{v}_h \|_{\omega_{\mathbf{a}}}^2$$

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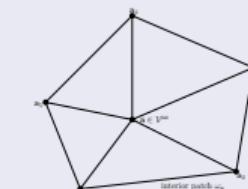
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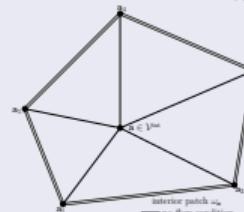
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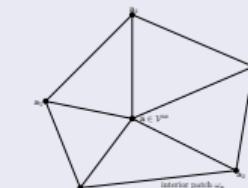
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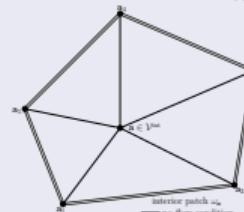
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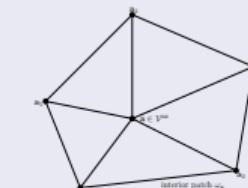
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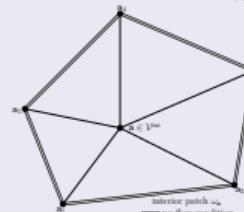
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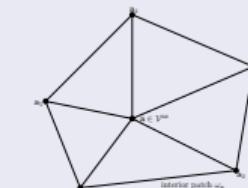
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The Laplacian $-\Delta u = f$ in Ω , $u = 0$ on $\partial\Omega$

Guaranteed upper bound

$$\underbrace{\|\nabla(u - u_h)\|}_{\text{unknown error}} \leq \underbrace{\|\nabla u_h + \sigma_h\|}_{\text{computable estimator}}$$

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Outline

- 1 Introduction
- 2 Reminder on the H^1 -case
- 3 The $\mathbf{H}(\text{curl})$ -case
- 4 $\mathbf{H}(\text{curl})$ patchwise equilibration
- 5 Stable (broken) $\mathbf{H}(\text{curl})$ polynomial extensions
- 6 Numerical experiments
- 7 Conclusions

The curl-curl problem (current density $\mathbf{j} \in H_{0,\text{N}}(\text{div}, \Omega)$ with $\nabla \cdot \mathbf{j} = 0$)

The curl-curl problem

Find the magnetic vector potential $\mathbf{A} : \Omega \rightarrow \mathbb{R}^3$ such that

$$\begin{aligned}\nabla \times (\nabla \times \mathbf{A}) &= \mathbf{j}, & \nabla \cdot \mathbf{A} &= 0 && \text{in } \Omega, \\ \mathbf{A} \times \mathbf{n}_\Omega &= \mathbf{0}, & & && \text{on } \Gamma_D, \\ (\nabla \times \mathbf{A}) \times \mathbf{n}_\Omega &= \mathbf{0}, & \mathbf{A} \cdot \mathbf{n}_\Omega &= 0 && \text{on } \Gamma_N.\end{aligned}$$

Weak formulation (consequence)

$\mathbf{A} \in H_{0,D}(\text{curl}, \Omega)$ satisfies

$$(\nabla \times \mathbf{A}, \nabla \times \mathbf{v}) = (\mathbf{j}, \mathbf{v}) \quad \forall \mathbf{v} \in H_{0,D}(\text{curl}, \Omega).$$

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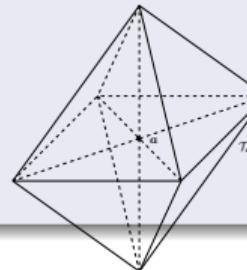
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Key points

- homogeneous tangential BC on $\partial \omega_{\mathbf{a}}$:

$$\mathbf{h}_h \in \mathcal{N}_{p+1}(\mathcal{T}_h) \cap H(\text{curl}, \Omega)$$

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$$\mathbf{h}_h^e := \arg \min_{\mathbf{v}_h \in \mathcal{N}_p(\mathcal{E}_h) \cap \mathcal{H}_0(\text{curl}, \omega_e)} \|\nabla \times \mathbf{v}_h\|_{\omega_e}^2$$

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Discrete patchwise/broken patchwise equilibrated fluxes

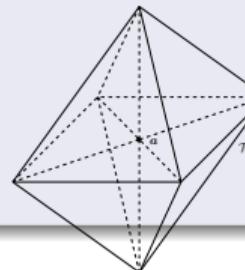
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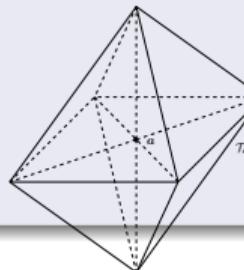
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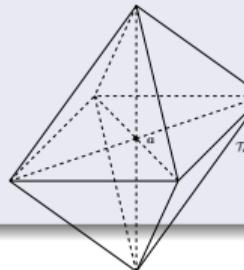
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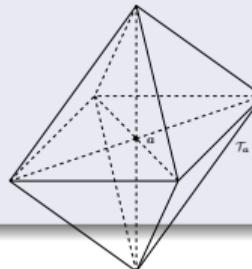
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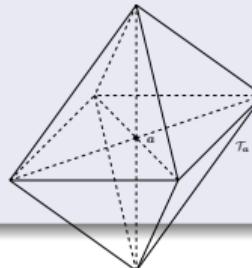
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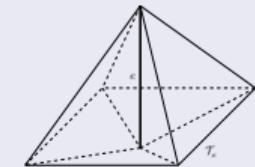
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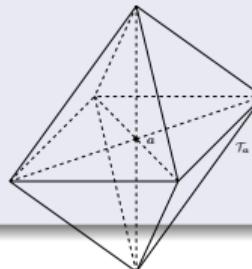
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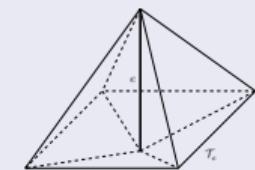
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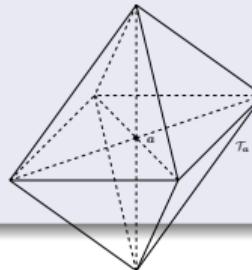
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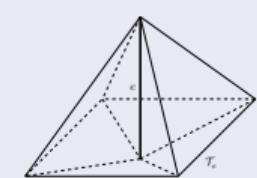
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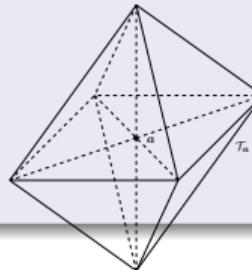
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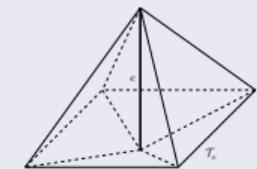
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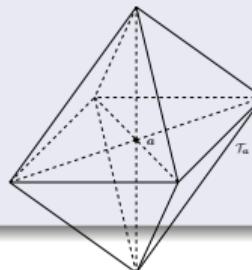
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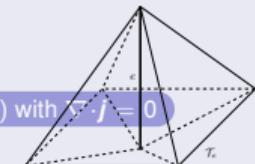
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• well-posed for $\mathbf{j}|_{\omega_e} \in \mathcal{RT}_p(\mathcal{T}_e) \cap \mathbf{H}(\text{div}, \omega_e)$ with $\nabla \cdot \mathbf{j} = 0$



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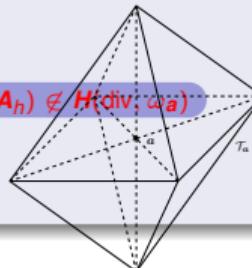
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► $\psi^\mathbf{a} \mathbf{j} \in \mathcal{RT}_{p+1}(\mathcal{T}_\mathbf{a}) \cap \mathbf{H}_0(\text{div}, \omega_\mathbf{a})$ but $\nabla \psi^\mathbf{a} \times (\nabla \times \mathbf{A}_h) \notin \mathbf{H}(\text{div}, \omega_\mathbf{a})$

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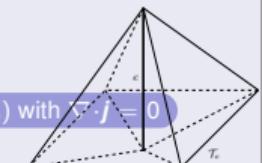
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$$\mathbf{h}_h^e := \arg \min_{\substack{\mathbf{v}_h \in \mathcal{N}_p(\mathcal{T}_e) \cap \mathbf{H}(\text{curl}, \omega_e) \\ \nabla \times \mathbf{v}_h = \mathbf{j}}} \|\nabla \times \mathbf{A}_h - \mathbf{v}_h\|_{\omega_e}^2$$

► **well-posed** for $\mathbf{j}|_{\omega_e} \in \mathcal{RT}_p(\mathcal{T}_e) \cap \mathbf{H}(\text{div}, \omega_e)$ with $\nabla \cdot \mathbf{j} = 0$



Key points

- **no BC** on $\partial \omega_e$:
 $\mathbf{h}_h = \sum_{e \in \mathcal{E}_h} \mathbf{h}_h^e \notin \mathbf{H}(\text{curl}, \Omega)$
- only **local equilibrium** $\nabla \times \mathbf{h}_h^e = \mathbf{j}$

Discrete patchwise/broken patchwise equilibrated fluxes

~~Definition~~ (Chaumont-Frelet, Vohralík (2021))

For each **vertex** $\mathbf{a} \in \mathcal{V}_h$, solve the **local constrained minimization pb**

$$\mathbf{h}_h^\mathbf{a} := \arg \min_{\begin{array}{l} \mathbf{v}_h \in \mathcal{N}_{p+1}(\mathcal{T}_\mathbf{a}) \cap \mathbf{H}_0(\text{curl}, \omega_\mathbf{a}) \\ \nabla \times \mathbf{v}_h = \psi^\mathbf{a} \mathbf{j} + \nabla \psi^\mathbf{a} \times (\nabla \times \mathbf{A}_h) \end{array}} \|\psi^\mathbf{a}(\nabla \times \mathbf{A}_h) - \mathbf{v}_h\|_{\omega_\mathbf{a}}^2$$

► $\psi^\mathbf{a} \mathbf{j} \in \mathcal{RT}_{p+1}(\mathcal{T}_\mathbf{a}) \cap \mathbf{H}_0(\text{div}, \omega_\mathbf{a})$ but $\nabla \psi^\mathbf{a} \times (\nabla \times \mathbf{A}_h) \notin \mathbf{H}(\text{div}, \omega_\mathbf{a})$

$$\mathbf{h}_h := \sum_{\mathbf{a} \in \mathcal{V}_h} \mathbf{h}_h^\mathbf{a}.$$

Key points

- **homogeneous tangential BC** on $\partial \omega_\mathbf{a}$:
 $\mathbf{h}_h \in \mathcal{N}_{p+1}(\mathcal{T}_h) \cap \mathbf{H}(\text{curl}, \Omega)$
- **global equilibrium** $\nabla \times \mathbf{h}_h = \sum_{\mathbf{a} \in \mathcal{V}_h} \nabla \times \mathbf{h}_h^\mathbf{a}$
 $= \sum_{\mathbf{a} \in \mathcal{V}_h} (\psi^\mathbf{a} \mathbf{j} + \nabla \psi^\mathbf{a} \times (\nabla \times \mathbf{A}_h)) = \mathbf{j}$

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Bottom line

Continuous case

- When there exist $\mathbf{v} \in \mathbf{H}(\text{curl}, \Omega)$ such that $\nabla \times \mathbf{v} = \mathbf{j}$?
- When $\mathbf{j} \in \mathbf{H}(\text{div}, \Omega)$ with $\nabla \cdot \mathbf{j} = 0$.

Discrete case

- When there exist $\mathbf{v}_h \in \mathcal{N}_p(\mathcal{T}_h) \cap \mathbf{H}(\text{curl}, \Omega)$ such that $\nabla \times \mathbf{v}_h = \mathbf{j}$?
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We suppose

- $\mathbf{j} \in H_{0,\Omega}(\text{div}, \Omega)$ with $\nabla \cdot \mathbf{j} = 0$
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The curl–curl case

Guaranteed upper bound

$$\underbrace{\|\nabla \times (\mathbf{A} - \mathbf{A}_h)\|}_{\text{unknown error}} \leq \underbrace{\|\nabla \times \mathbf{A}_h - \mathbf{h}_h\|}_{\text{computable estimator}}$$

$$\leq 2 \left\{ \sum_{\mathbf{a} \in \mathcal{V}_h} \|\psi^{\mathbf{a}}(\nabla \times \mathbf{A}_h) - \mathbf{h}_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}}^2 \right\}^{1/2}$$

p -robust local efficiency (Costabel & Mc-Intosh (2010);

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$$\|\psi^{\mathbf{a}}(\nabla \times \mathbf{A}_h) - \mathbf{h}_h^{\mathbf{a}}\|_{\omega_{\mathbf{a}}} \leq C_{\text{st}} \sup_{\substack{\mathbf{v} \in \mathbf{H}^*(\text{curl}, \omega_{\mathbf{a}}) \\ \|\nabla \times \mathbf{v}\|_{\omega_{\mathbf{a}}} = 1}} \langle \mathcal{R}(\mathbf{A}_h), \psi^{\mathbf{a}} \mathbf{v} \rangle$$

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$$\underbrace{\|\nabla \times (\mathbf{A} - \mathbf{A}_h)\|}_{\text{unknown error}} \leq \underbrace{C_L 6^{1/2} C_{\text{cont,PF}} \left\{ \sum_{e \in \mathcal{E}_h} \|\nabla \times \mathbf{A}_h - \mathbf{h}_h^e\|_{\omega_e}^2 \right\}^{1/2}}_{\text{computable estimator}}$$

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Patchwise/broken patchwise flux equilibration

Patchwise flux equilibration

- **globally equilibrated flux**
- Prager–Synge **constant-free** upper bound
- equilibration in several stages, more expensive
- additional layer for efficiency
- p -robust

Broken patchwise flux equilibration

- **locally equilibrated flux**
- $6^{1/2}$, $C_{\text{cont,PF}}$, and C_L in the upper bound
 $C_L = 1$ if Ω is convex and no mixed BCs
- equilibration in a single stage, cheaper, explicit for $p = 0$
- both estimator and efficiency on ω_p
- p -robust

Lift constant C_L such that for all $\mathbf{v} \in \mathbf{H}_{0,\text{D}}(\text{curl}, \Omega)$, there exists $\mathbf{w} \in \mathbf{H}^1(\Omega)$ such that $\mathbf{w} \in \mathbf{H}_{0,\text{D}}(\text{curl}, \Omega)$, $\nabla \times \mathbf{w} = \nabla \times \mathbf{v}$, and

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Patchwise/broken patchwise flux equilibration

Patchwise flux equilibration

- **globally equilibrated flux**
- *Prager–Synge constant-free upper bound*
- *equilibration in several stages, more expensive*
- *additional layer for efficiency*
- **p -robust**

Broken patchwise flux equilibration

- **locally equilibrated flux**
- $6^{1/2}$, $C_{\text{cont,PF}}$, and C_L in the upper bound; $C_L = 1$ if Ω is convex and no mixed BCs
- *equilibration in a single stage, cheaper, explicit for $p = 0$*
- *both estimator and efficiency on ω_e*
- **p -robust**

Lift constant C_L such that for all $\mathbf{v} \in \mathbf{H}_{0,D}(\text{curl}, \Omega)$, there exists $\mathbf{w} \in \mathbf{H}^1(\Omega)$ such that $\mathbf{w} \in \mathbf{H}_{0,D}(\text{curl}, \Omega)$, $\nabla \times \mathbf{w} = \nabla \times \mathbf{v}$, and

$$\|\nabla \mathbf{w}\| \leq C_L \|\nabla \times \mathbf{v}\|$$

Outline

- 1 Introduction
- 2 Reminder on the H^1 -case
- 3 The $H(\text{curl})$ -case
- 4 $H(\text{curl})$ patchwise equilibration
- 5 Stable (broken) $H(\text{curl})$ polynomial extensions
- 6 Numerical experiments
- 7 Conclusions

Stage 1: overconstrained Raviart–Thomas projection

Projection of $\nabla\psi^{\mathbf{a}} \times (\nabla \times \mathbf{A}_h)$ to a Raviart–Thomas space

For all vertices $\mathbf{a} \in \mathcal{V}_h$, consider $p' := \min\{p, 1\}$ -degree patchwise minimizations:

$$\theta_h^{\mathbf{a}} := \arg \min_{\mathbf{v}_h \in \mathcal{RT}_{p'}(\mathcal{T}_{\mathbf{a}}) \cap \mathbf{H}_0(\text{div}, \omega_{\mathbf{a}})} \|\nabla\psi^{\mathbf{a}} \times (\nabla \times \mathbf{A}_h) - \mathbf{v}_h\|_{\omega_{\mathbf{a}}}^2.$$

$\nabla \cdot \mathbf{v}_h = -\nabla\psi^{\mathbf{a}} \cdot \mathbf{j}$

$(\mathbf{v}_h, \mathbf{r}_h)_K = (\nabla\psi^{\mathbf{a}} \times (\nabla \times \mathbf{A}_h), \mathbf{r}_h)_K \quad \forall \mathbf{r}_h \in [\mathcal{P}_0(K)]^3, \forall K \in \mathcal{T}_{\mathbf{a}}$

Comments

- $\nabla\psi^{\mathbf{a}} \times (\nabla \times \mathbf{A}_h) \notin \mathcal{RT}_{p'}(\mathcal{T}_{\mathbf{a}}) \cap \mathbf{H}_0(\text{div}, \omega_{\mathbf{a}})$

↳ additional compatibility constraints

↳ model for stage 2

↳ can proceed since the lowest-order Galerkin orthogonality of \mathbf{A}_h

↳ requires $\min\{p, 1\}$

↳ model for stage 3

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- $\nabla\psi^{\mathbf{a}} \times (\nabla \times \mathbf{A}_h) \notin \mathcal{RT}_{p'}(\mathcal{T}_{\mathbf{a}}) \cap \mathbf{H}_0(\text{div}, \omega_{\mathbf{a}})$
- additional orthogonality constraint
 - crucial for stage 2
 - only possible thanks the lowest-order Galerkin orthogonality of \mathbf{A}_h
 - requests $\min\{p, 1\}$
- remainder $\delta_h := \sum_{\mathbf{a} \in \mathcal{V}_h} \theta_h^{\mathbf{a}}$
 - should be zero (\sim partition of unity) but is not
 - $\delta_h \in \mathcal{RT}_{p'}(\mathcal{T}_h) \cap \mathbf{H}_{0,N}(\text{div}, \Omega)$ and $\nabla \cdot \delta_h = 0$

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Stage 2: divergence-free decomposition of the given divergence-free Raviart-Thomas piecewise polynomial δ_h

Divergence-free decomposition of δ_h

For all tetrahedra $K \in \mathcal{T}_h$, consider $(p+1)$ -degree elementwise minimizations:

$$\delta_h^{\mathbf{a}}|_K := \arg \min_{\substack{\mathbf{v}_h \in \mathcal{RT}_1(K) \\ \nabla \cdot \mathbf{v}_h = 0 \\ \mathbf{v}_h \cdot \mathbf{n}_K = \mathcal{I}_1^{\mathcal{RT}}(\psi^{\mathbf{a}} \delta_h) \cdot \mathbf{n}_K \text{ on } \partial K}} \|\mathbf{v}_h - \mathcal{I}_1^{\mathcal{RT}}(\psi^{\mathbf{a}} \delta_h)\|_K^2 \quad \forall \mathbf{a} \in \mathcal{V}_K \text{ when } p=0,$$

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Comments

- patchwise contributions

$$\delta_h^{\mathbf{a}} \in \mathcal{RT}_{p+1}(\mathcal{T}_{\mathbf{a}}) \cap \mathbf{H}_0(\text{div}, \omega_{\mathbf{a}}) \quad \text{and} \quad \nabla \cdot \delta_h^{\mathbf{a}} = 0 \quad \forall \mathbf{a} \in \mathcal{V}_h$$

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ψ, γ form a divergence-free decomposition of δ_h : $\delta_h = \sum_j \delta_j^{\mathbf{a}}$

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Stage 2: divergence-free decomposition of the given divergence-free current density \mathbf{j}

Divergence-free decomposition of the current density \mathbf{j}

Set

$$\mathbf{j}_h^{\mathbf{a}} := \psi^{\mathbf{a}} \mathbf{j} + \boldsymbol{\theta}_h^{\mathbf{a}} - \boldsymbol{\delta}_h^{\mathbf{a}}.$$

Then

$$\begin{aligned}\mathbf{j}_h^{\mathbf{a}} &\in \mathcal{RT}_{p+1}(\mathcal{T}_{\mathbf{a}}) \cap \mathbf{H}_0(\text{div}, \omega_{\mathbf{a}}), \\ \nabla \cdot \mathbf{j}_h^{\mathbf{a}} &= 0, \\ \sum_{\mathbf{a} \in \mathcal{V}_h} \mathbf{j}_h^{\mathbf{a}} &= \mathbf{j}.\end{aligned}$$

Stage 3: discrete patchwise equilibrated fluxes

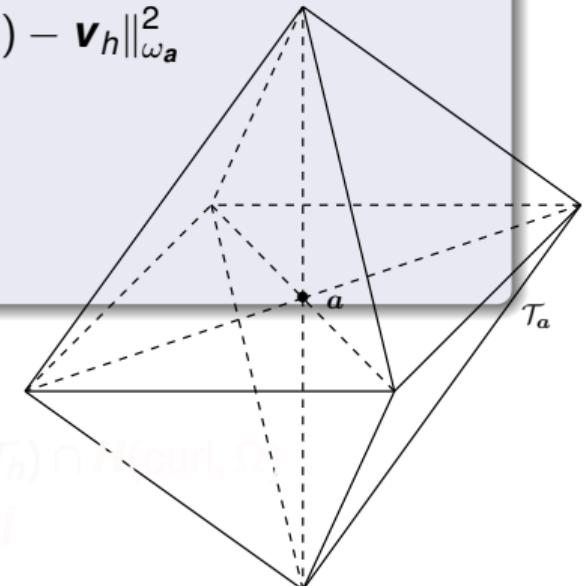
Definition (chaumont-Frelet, Vohralík (2021))

For each **vertex** $\mathbf{a} \in \mathcal{V}_h$, solve the **local constrained minimization problem**

$$\mathbf{h}_h^\mathbf{a} := \arg \min_{\begin{array}{l} \mathbf{v}_h \in \mathcal{N}_{p+1}(\mathcal{T}_a) \cap \mathcal{H}_0(\text{curl}, \omega_\mathbf{a}) \\ \nabla \times \mathbf{v}_h = \mathbf{j}_h^\mathbf{a} \end{array}} \|\psi^\mathbf{a}(\nabla \times \mathbf{A}_h) - \mathbf{v}_h\|_{\omega_\mathbf{a}}^2$$

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Key points

- homogeneous tangential BC on $\partial\omega_\mathbf{a}$: $\mathbf{h}_h \in \mathcal{N}_{p+1}(\mathcal{T}_h) \cap \mathcal{H}_0(\text{curl}, \omega_\mathbf{a})$
- global equilibrium $\nabla \times \mathbf{h}_h = \sum_{\mathbf{a} \in \mathcal{V}_h} \nabla \times \mathbf{h}_h^\mathbf{a} = \sum_{\mathbf{a} \in \mathcal{V}_h} \mathbf{j}_h^\mathbf{a} = \mathbf{j}_h$

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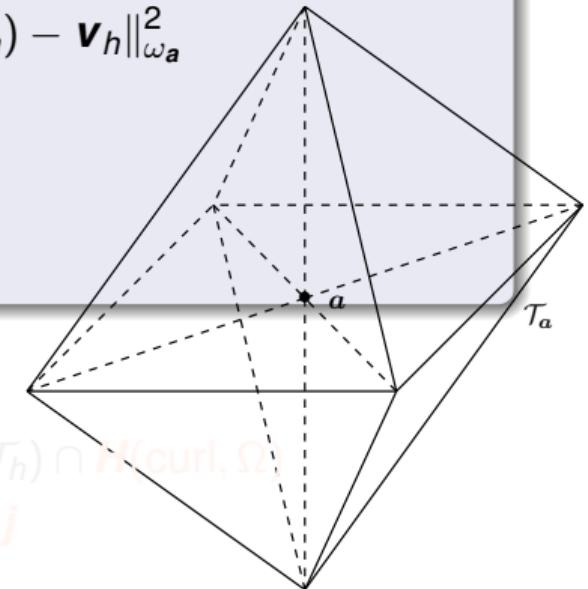
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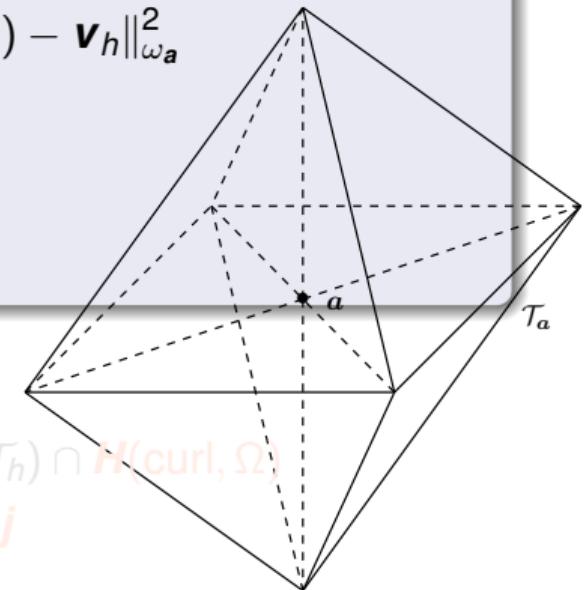
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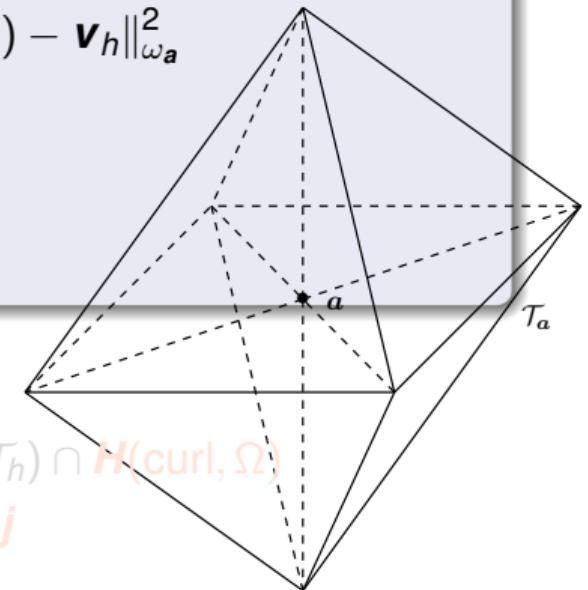
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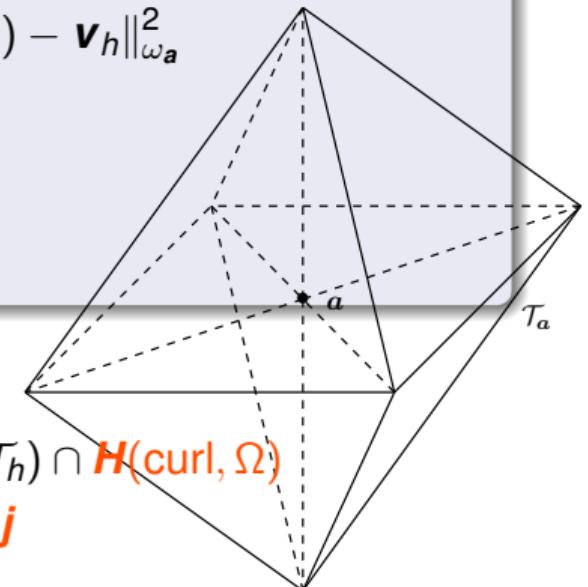
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$H(\text{curl})$ polynomial extension on a tetrahedron

Theorem ($H(\text{curl})$) polynomial extension on a tetrahedron Costabel & Mc-Intosh (2010); Demkowicz, Gopalakrishnan, & Schöberl (2009); Chaumont-Frelet, Ern, & V. (2020)

Let $\emptyset \subseteq \mathcal{F} \subseteq \mathcal{F}_K$ be a (sub)set of faces of a tetrahedron K . Then, for every polynomial degree $p \geq 0$, for all $\mathbf{r}_K \in \mathcal{RT}_p(K)$ such that $\nabla \cdot \mathbf{r}_K = 0$, and for all $\mathbf{r}_{\mathcal{F}} \in \mathcal{N}_p^{\tau}(\Gamma_{\mathcal{F}})$ such that $\mathbf{r}_K \cdot \mathbf{n}_F = \text{curl}_F(\mathbf{r}_F)$ for all $F \in \mathcal{F}$, there holds

$$\min_{\substack{\mathbf{v}_p \in \mathcal{N}_p(K) \\ \nabla \times \mathbf{v}_p = \mathbf{r}_K \\ \mathbf{v}_p|_{\mathcal{F}} = \mathbf{r}_{\mathcal{F}}}} \|\mathbf{v}_p\|_K \leq C_{\text{st}} \min_{\substack{\mathbf{v} \in H(\text{curl}, K) \\ \nabla \times \mathbf{v} = \mathbf{r}_K \\ \mathbf{v}|_{\mathcal{F}} = \mathbf{r}_{\mathcal{F}}}} \|\mathbf{v}\|_K.$$

Comments

- C_{st} only depends on the shape-regularity of K
- for (pw) p -polynomial data $\mathbf{r}_K, \mathbf{r}_{\mathcal{F}}$, minimization over $\mathcal{N}_p(K)$ is up to C_{st} as good as minimization over the entire $H(\text{curl}, K)$
- extension to an edge patch: Chaumont-Frelet, Ern, & V. (2021)
- extension to a vertex patch: conjecture

$H(\text{curl})$ polynomial extension on a tetrahedron

Theorem ($H(\text{curl})$) polynomial extension on a tetrahedron Costabel & Mc-Intosh (2010); Demkowicz, Gopalakrishnan, & Schöberl (2009); Chaumont-Frelet, Ern, & V. (2020)

Let $\emptyset \subseteq \mathcal{F} \subseteq \mathcal{F}_K$ be a (sub)set of faces of a tetrahedron K . Then, for every polynomial degree $p \geq 0$, for all $\mathbf{r}_K \in \mathcal{RT}_p(K)$ such that $\nabla \cdot \mathbf{r}_K = 0$, and for all $\mathbf{r}_{\mathcal{F}} \in \mathcal{N}_p^{\tau}(\Gamma_{\mathcal{F}})$ such that $\mathbf{r}_K \cdot \mathbf{n}_F = \text{curl}_F(\mathbf{r}_F)$ for all $F \in \mathcal{F}$, there holds

$$\min_{\substack{\mathbf{v}_p \in \mathcal{N}_p(K) \\ \nabla \times \mathbf{v}_p = \mathbf{r}_K \\ \mathbf{v}_p|_{\mathcal{F}} = \mathbf{r}_{\mathcal{F}}}} \|\mathbf{v}_p\|_K \leq C_{\text{st}} \min_{\substack{\mathbf{v} \in \mathbf{H}(\text{curl}, K) \\ \nabla \times \mathbf{v} = \mathbf{r}_K \\ \mathbf{v}|_{\mathcal{F}} = \mathbf{r}_{\mathcal{F}}}} \|\mathbf{v}\|_K.$$

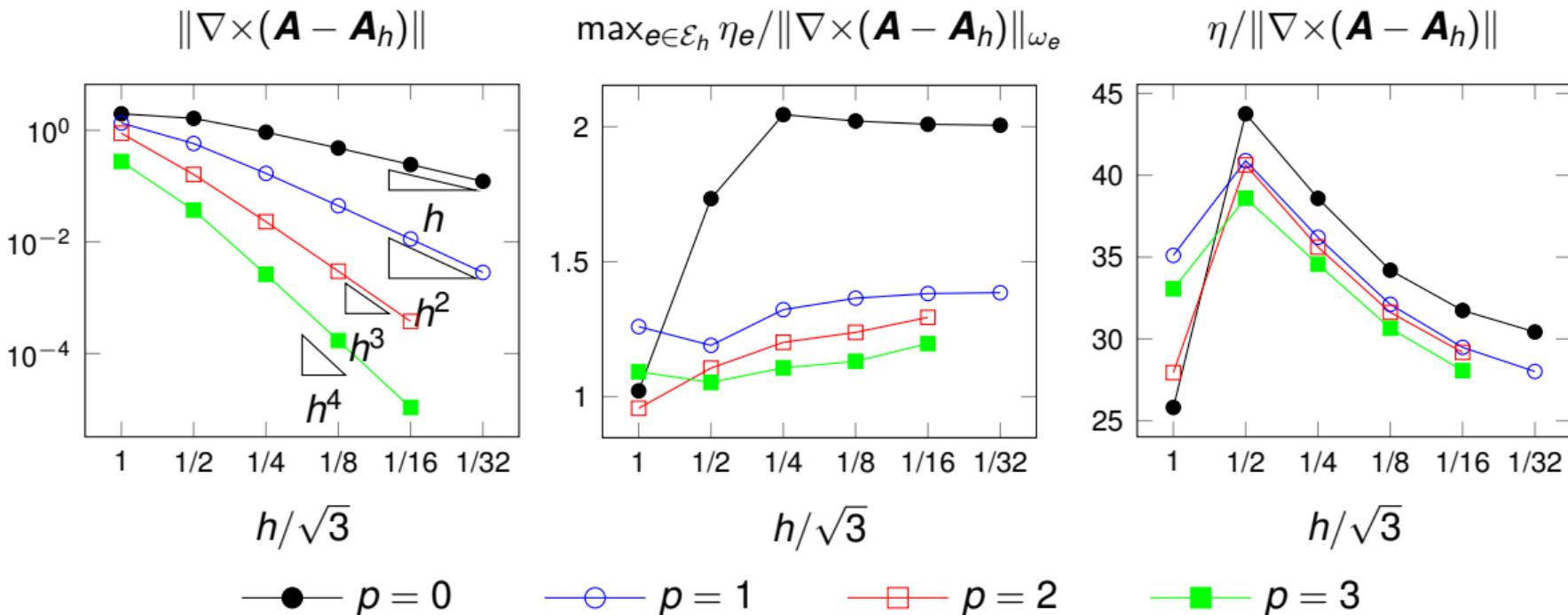
Comments

- C_{st} only depends on the shape-regularity of K
- for (pw) p -polynomial data \mathbf{r}_K , $\mathbf{r}_{\mathcal{F}}$, minimization over $\mathcal{N}_p(K)$ is up to C_{st} as good as minimization over the entire $\mathbf{H}(\text{curl}, K)$
- extension to an edge patch: Chaumont-Frelet, Ern, & V. (2021)
- extension to a vertex patch: conjecture

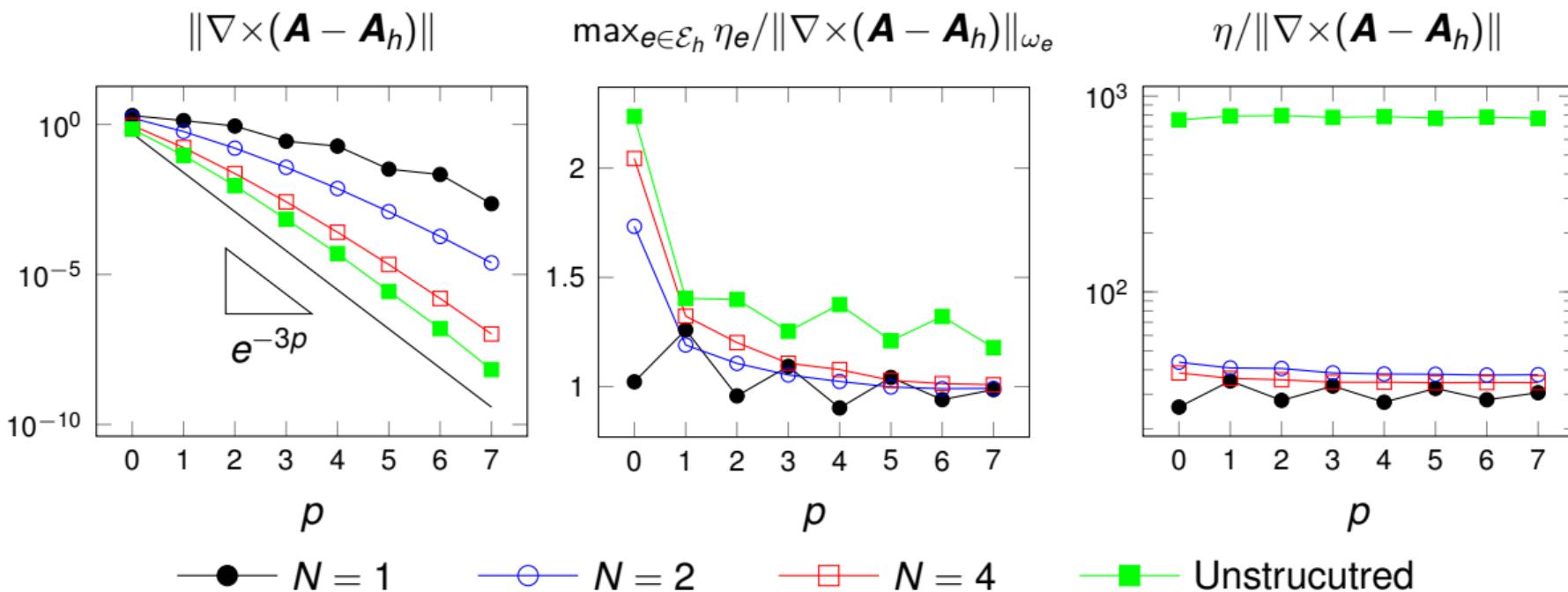
Outline

- 1 Introduction
- 2 Reminder on the H^1 -case
- 3 The $H(\text{curl})$ -case
- 4 $H(\text{curl})$ patchwise equilibration
- 5 Stable (broken) $H(\text{curl})$ polynomial extensions
- 6 Numerical experiments
- 7 Conclusions

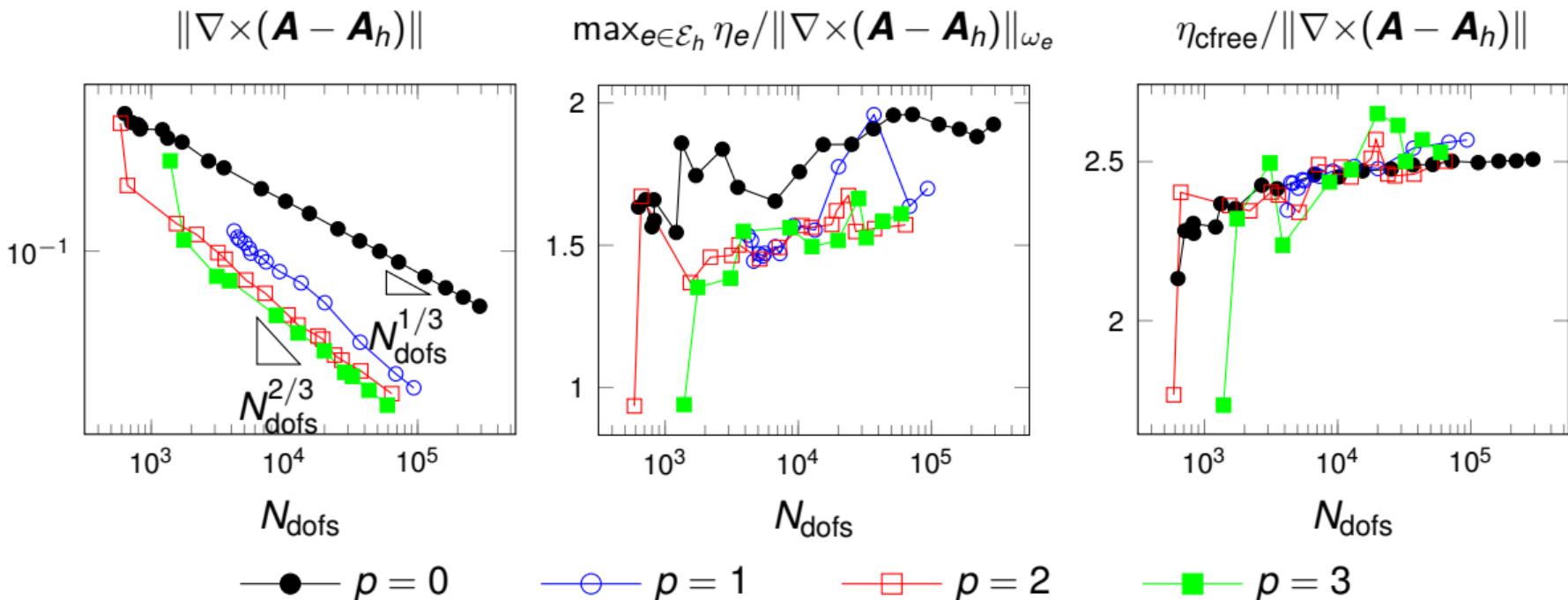
Broken patchwise equilibration, **smooth solution**, h -refinement

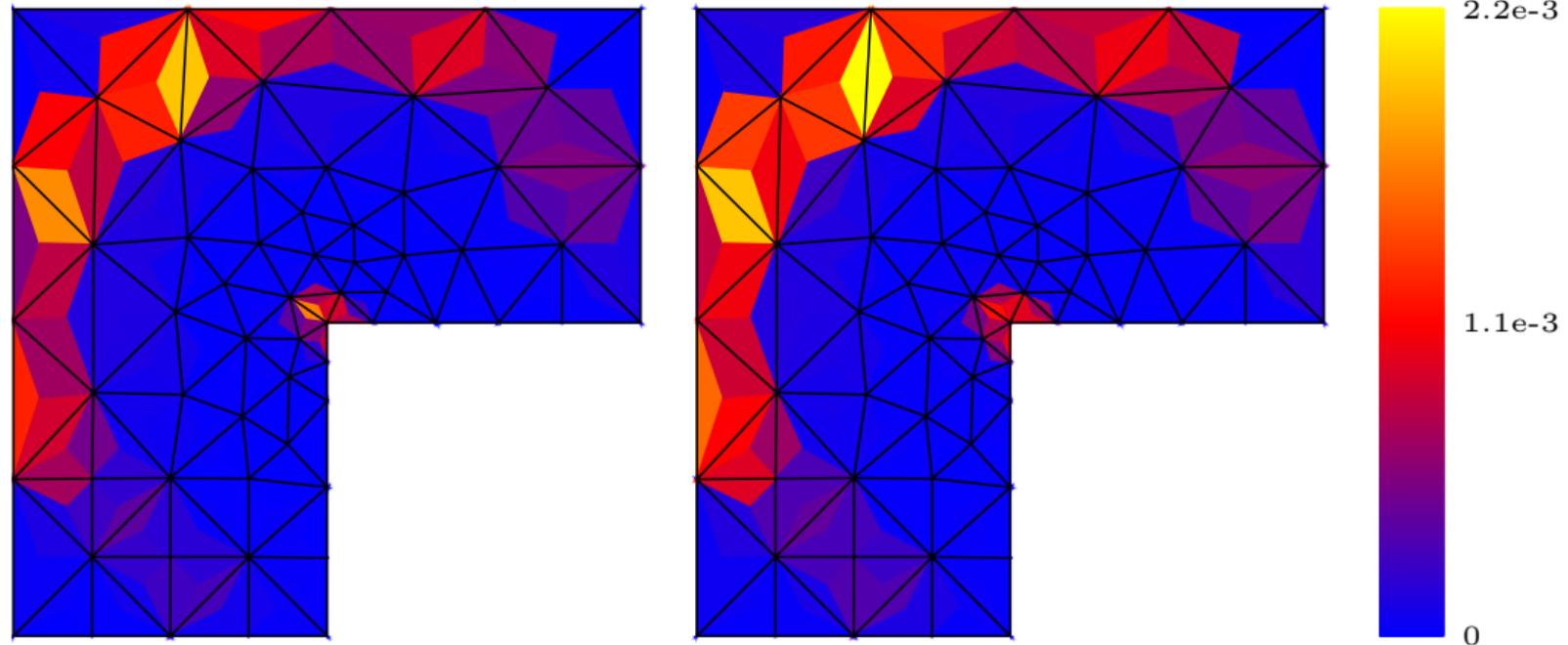


Broken patchwise equilibration, **smooth solution**, p -refinement



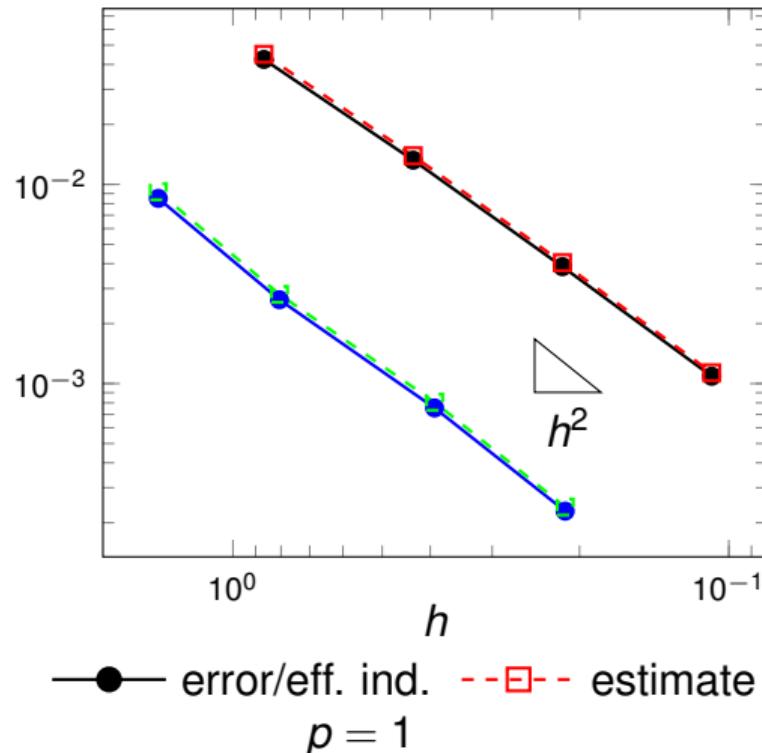
Broken patchwise equilibration, **singular solution**, adap. refinement



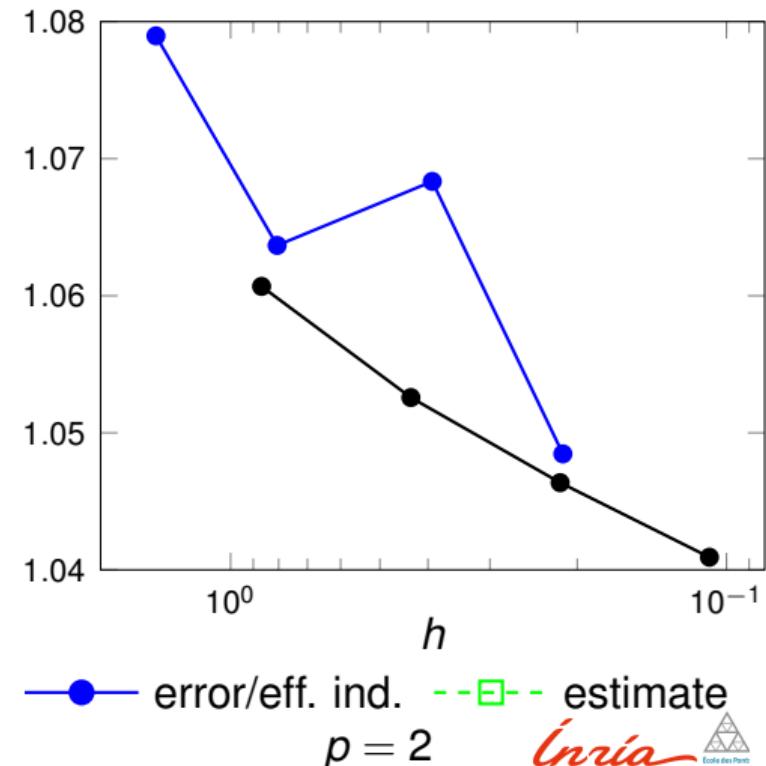
Broken patchwise equilibration, **singular solution, adap.** refinementEstimated (left) and actual error (right), $p = 3$

Patchwise equilibration, H^3 solution, h -refinement

$$\|\nabla \times (\mathbf{A} - \mathbf{A}_h)\|$$

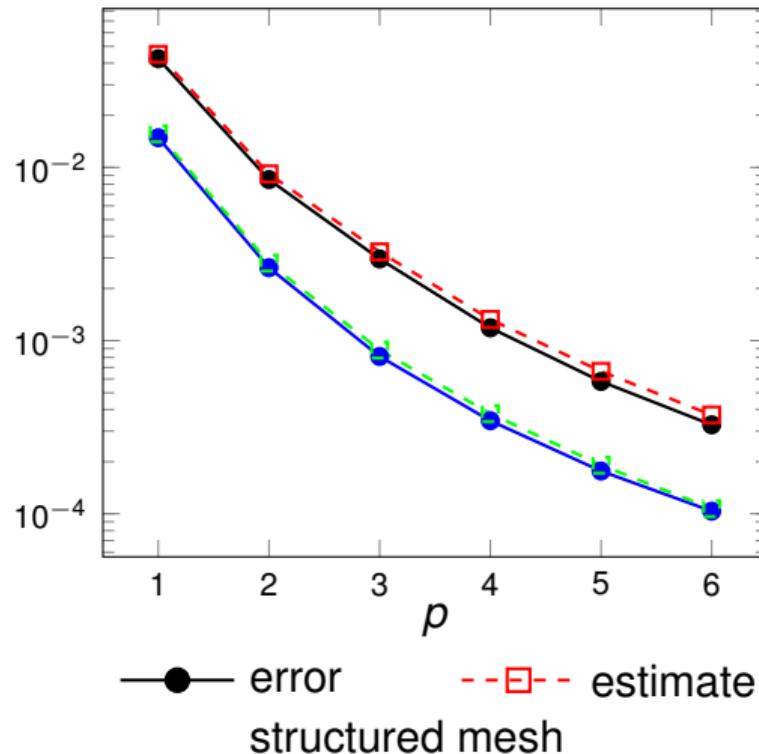


$$\text{Effectivity index } \eta / \|\nabla \times (\mathbf{A} - \mathbf{A}_h)\|$$

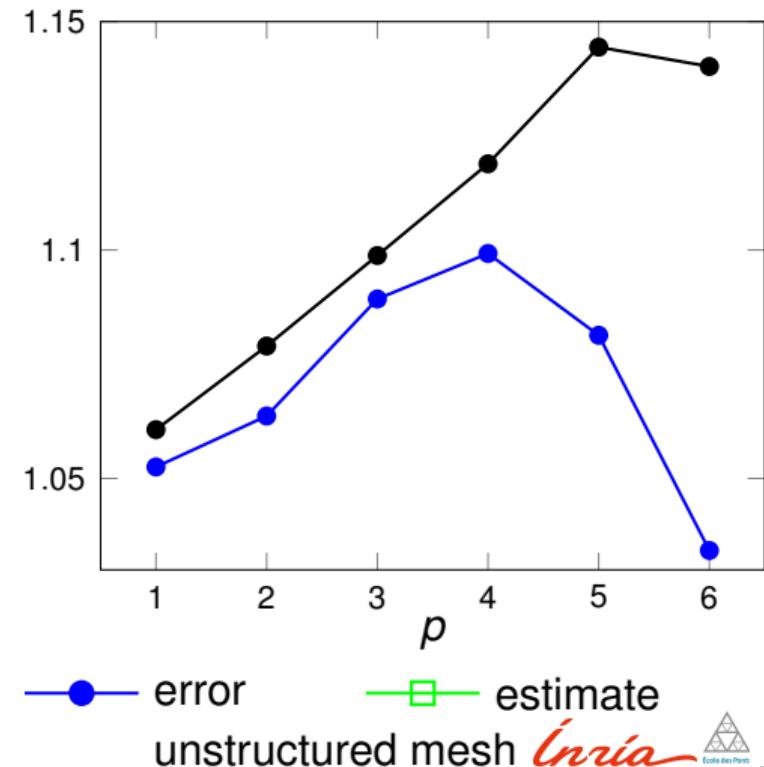


Patchwise equilibration, H^3 solution, p -refinement

$$\|\nabla \times (\mathbf{A} - \mathbf{A}_h)\|$$

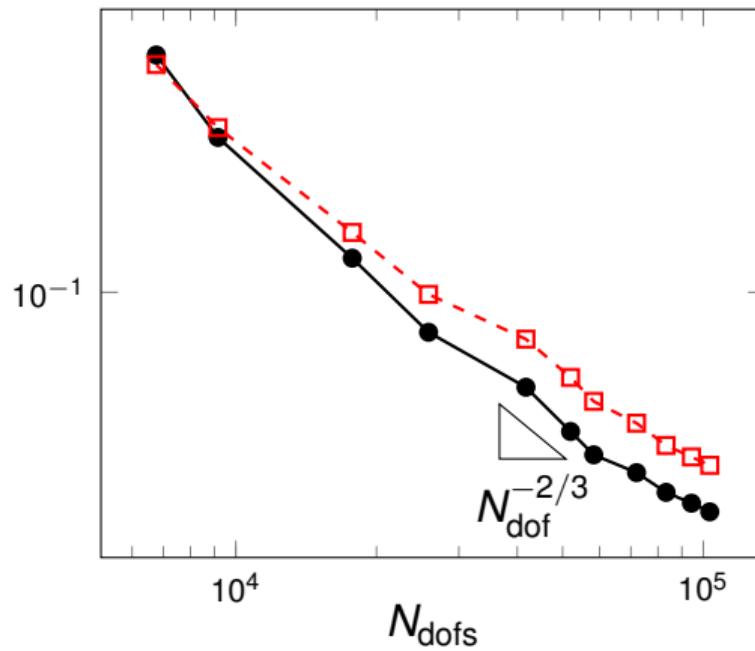


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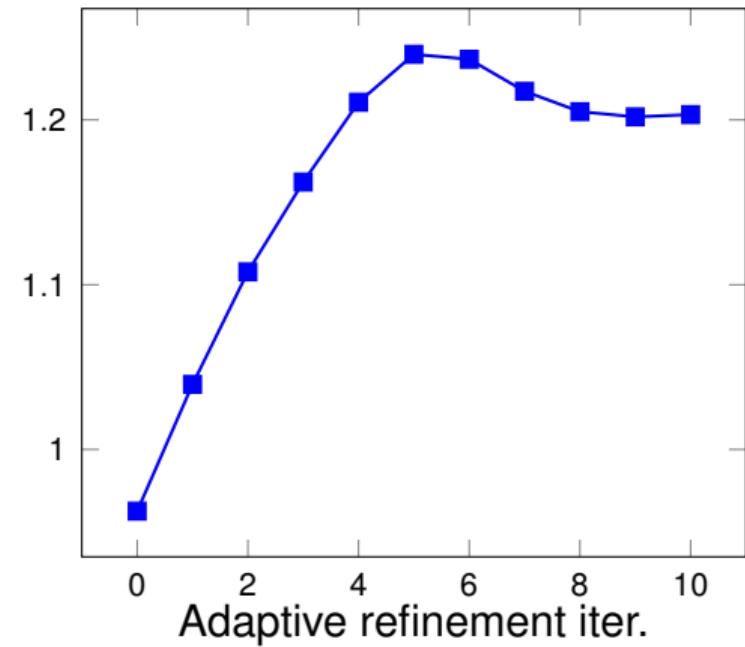


Patchwise equilibration, singular solution, adap. refinement ($p = 2$)

$$\|\nabla \times (\mathbf{A} - \mathbf{A}_h)\|$$

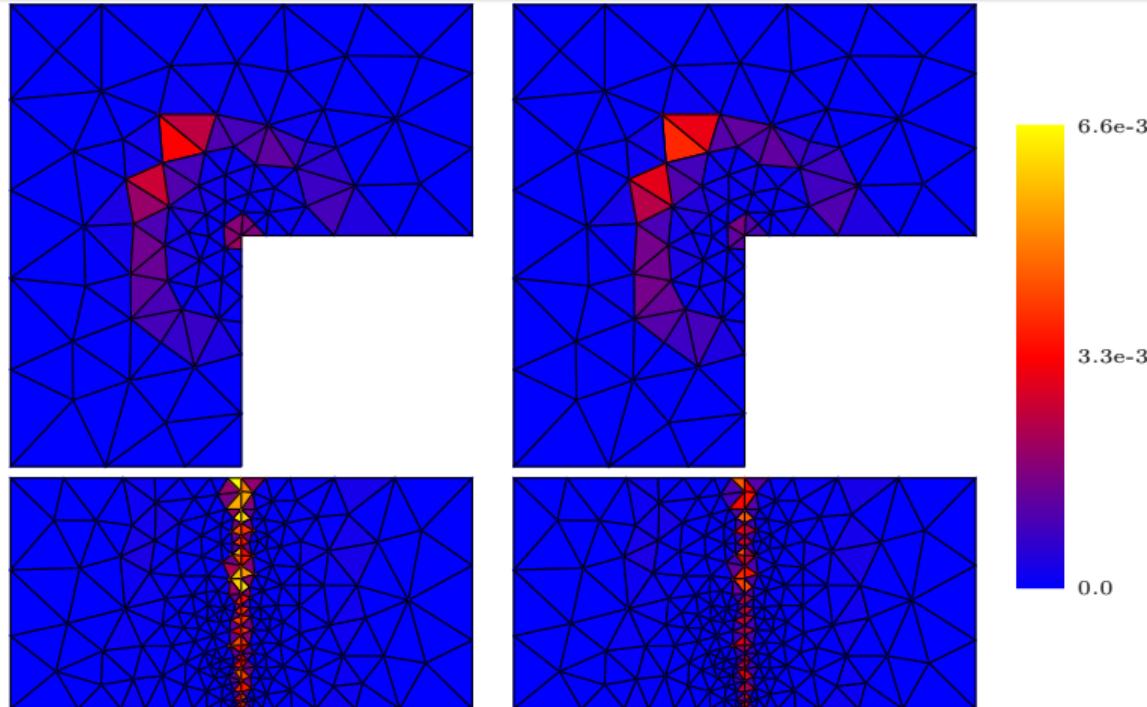


$$\text{Effectivity index } \eta / \|\nabla \times (\mathbf{A} - \mathbf{A}_h)\|$$



—●— error —□— estimate

—■— effectivity index

Patchwise equilibration, singular solution, adap. refinement ($p = 2$)

Estimated (left) and actual error (right), adaptive mesh refinement iteration #10.
Top view (top) and side view (bottom)

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- CHAUMONT-FRELET T., ERN A., VOHRALÍK M., Polynomial-degree-robust $H(\text{curl})$ -stability of discrete minimization in a tetrahedron, *C. R. Math. Acad. Sci. Paris* **358** (2020), 1101–1110.
- CHAUMONT-FRELET T., ERN A., VOHRALÍK M., Stable broken $H(\text{curl})$ polynomial extensions and p -robust a posteriori error estimates by broken patchwise equilibration for the curl–curl problem, *Math. Comp.* (2021), accepted for publication.
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Thank you for your attention!

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