

A posteriori error control  
for transmission problems  
with sign changing coefficients  
using localization of dual norms

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Prague, February 23, 2015

# Outline

- 1 Setting
- 2 Localization of global (dual) norms
- 3 A posteriori error control
- 4 Numerical results
- 5 Conclusions and future directions

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# Sign changing coefficients

## Model problem

$$\begin{aligned} -\nabla \cdot (\underline{\Sigma} \nabla u) &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

- $\underline{\Sigma}$  **not positive definite** (and symmetric)
- $\Omega = \Omega_+ \cup \Omega_-$ ,  $\sigma_+ > 0$  and  $\sigma_- < 0$ ,

$$\underline{\Sigma}|_{\Omega_+} = \sigma_+ \mathbf{I}, \quad \underline{\Sigma}|_{\Omega_-} = \sigma_- \mathbf{I}$$

- specific application: electromagnetism for interfaces between dielectrics and (negative) metamaterials
- weak solution:  $u \in H_0^1(\Omega)$  such that

$$(\underline{\Sigma} \nabla u, \nabla v) = (f, v) \quad \forall v \in H_0^1(\Omega)$$

- conditions for well-posedness follow from the Banach–Nečas–Babuška theorem – Bonnet-Ben Dhia, Chesnel, Ciarlet Jr. (2012): **T-coercivity**
- numerical discretization: Chesnel and Ciarlet Jr. (2013)

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# Assumptions

## We suppose

- $\Omega \subset \mathbb{R}^d$ ,  $d \geq 2$ , an open polytope
- $\{\mathcal{T}_h\}_h$  is a family of shape-regular simplicial partitions;
- $\underline{\Sigma} \in [L^\infty(\Omega)]^{d \times d}$  is piecewise constant on each given  $\mathcal{T}_h$ ;
- $f \in L^2(\Omega)$ ;
- there exists a linear bijective operator  $T : H_0^1(\Omega) \rightarrow H_0^1(\Omega)$ :

$$\|\nabla(Tv)\| \leq \|T\| \|\nabla v\| \quad \forall v \in H_0^1(\Omega), \quad (\text{boundedness})$$

$$\underline{\alpha} \|\nabla v\|^2 \leq (\underline{\Sigma} \nabla v, \nabla(Tv)) \quad \forall v \in H_0^1(\Omega) \quad (\text{T-coercivity})$$



# In which norm to measure the error?

## Energy norm

- $\|v\|_{\text{en}}^2 := (\underline{\Sigma} \nabla v, \nabla v)$  for  $v \in H_0^1(\Omega)$
- **not well-defined**:  $(\underline{\Sigma} \nabla v, \nabla v) < 0$  may happen

## Intrinsic problem-dependent norm

- definition

$$\|v\|_{\#} := \sup_{\varphi \in H_0^1(\Omega); \|\nabla \varphi\|=1} (\underline{\Sigma} \nabla v, \nabla \varphi) \quad v \in H_0^1(\Omega)$$

- one choice in the sup & the Cauchy–Schwarz inequality:

$$\frac{(\underline{\Sigma} \nabla v, \nabla(Tv))}{\|\nabla(Tv)\|} \leq \|v\|_{\#} \leq \|\underline{\Sigma} \nabla v\| \quad \forall v \in H_0^1(\Omega)$$

- T-coercivity & boundedness of  $\underline{\Sigma}$  and T:

$$\frac{\alpha}{\|T\|} \|\nabla v\| \leq \|v\|_{\#} \leq \|\underline{\Sigma}\|_{\infty} \|\nabla v\| \quad \forall v \in H_0^1(\Omega)$$

- $\Rightarrow$  **equivalence of  $\|\nabla \cdot\|$  and  $\|\cdot\|_{\#}$**

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# Nonconforming discretizations

## Broken Sobolev space

$$H^1(\mathcal{T}_h) := \{v \in L^2(\Omega); v|_K \in H^1(K) \quad \forall K \in \mathcal{T}_h\}$$

Equality for  $\underline{\Sigma} = \underline{I}$ ,  $u_h \notin H_0^1(\Omega)$

$$\begin{aligned} \|\nabla(u - u_h)\|^2 = & \underbrace{\sup_{\varphi \in H_0^1(\Omega); \|\nabla\varphi\|=1} (\nabla(u - u_h), \nabla\varphi)^2}_{\text{dual norm of the residual}} \\ & + \underbrace{\inf_{s \in H_0^1(\Omega)} \|\nabla(u_h - s)\|^2}_{\text{distance to } H_0^1(\Omega)} \end{aligned}$$

Intrinsic problem-dependent norm,  $u_h \in H^1(\mathcal{T}_h)$

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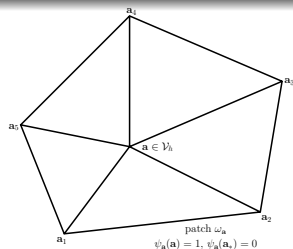
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# Localizations



## Dual norm of the residual

$$\|v\|_{\#, \omega_a} := \sup_{\varphi \in H_0^1(\omega_a); \|\nabla \varphi\|_{H_0^1(\omega_a)} = 1} (\underline{\Sigma} \nabla v, \nabla \varphi)_{\omega_a}$$

## Distance to $H_0^1(\Omega)$

$$\inf_{s^a \in H_{\#}^1(\omega_a)} \|\nabla(u_h - s^a)\|_{\omega_a},$$

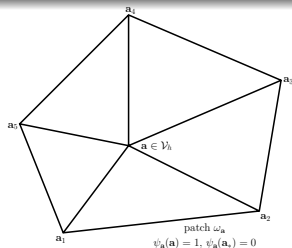
where

$$H_{\#}^1(\omega_a) := H^1(\omega_a),$$

$$\mathbf{a} \in \mathcal{V}_h^{\text{int}},$$

$$H_{\#}^1(\omega_a) := \{v \in H^1(\omega_a); v = 0 \text{ on } \partial\omega_a \cap \partial\Omega\}, \mathbf{a} \in \mathcal{V}_h^{\text{ext}}$$

# Localizations



## Dual norm of the residual

$$\|v\|_{\#, \omega_{\mathbf{a}}} := \sup_{\varphi \in H_0^1(\omega_{\mathbf{a}}); \|\nabla \varphi\|_{H_0^1(\omega_{\mathbf{a}})} = 1} (\underline{\Sigma} \nabla v, \nabla \varphi)_{\omega_{\mathbf{a}}}$$

## Distance to $H_0^1(\Omega)$

$$\inf_{s^{\mathbf{a}} \in H_{\#}^1(\omega_{\mathbf{a}})} \|\nabla(u_h - s^{\mathbf{a}})\|_{\omega_{\mathbf{a}}},$$

where

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# Dual norm of the residual

## Theorem

Let  $\xi \in [L^2(\Omega)]^d$  such that

$$(\xi, \nabla \psi_{\mathbf{a}})_{\omega_{\mathbf{a}}} = 0 \quad \forall \mathbf{a} \in \mathcal{V}_h^{\text{int}}$$

be arbitrary. Then

$$\sup_{\varphi \in H_0^1(\Omega); \|\nabla \varphi\|=1} (\xi, \nabla \varphi)^2 \leq (d+1) C_{\text{cont,PF}}^2 \sum_{\mathbf{a} \in \mathcal{V}_h} \sup_{\varphi \in H_0^1(\omega_{\mathbf{a}}); \|\nabla \varphi\|_{\omega_{\mathbf{a}}}=1} (\xi, \nabla \varphi)_{\omega_{\mathbf{a}}}^2,$$

$$\sum_{\mathbf{a} \in \mathcal{V}_h} \sup_{\varphi \in H_0^1(\omega_{\mathbf{a}}); \|\nabla \varphi\|_{\omega_{\mathbf{a}}}=1} (\xi, \nabla \varphi)_{\omega_{\mathbf{a}}}^2 \leq (d+1) \sup_{\varphi \in H_0^1(\Omega); \|\nabla \varphi\|=1} (\xi, \nabla \varphi)^2.$$

# Dual norm of the residual

## Corollary

Let  $u$  be the weak solution and let  $u_h \in H^1(\mathcal{T}_h)$  such that

$$(\underline{\Sigma} \nabla u_h, \nabla \psi_{\mathbf{a}})_{\omega_{\mathbf{a}}} = (f, \psi_{\mathbf{a}})_{\omega_{\mathbf{a}}} \quad \forall \mathbf{a} \in \mathcal{V}_h^{\text{int}}$$

be arbitrary. Then

$$\|u - u_h\|_{\#}^2 \leq (d+1) C_{\text{cont,PF}}^2 \sum_{\mathbf{a} \in \mathcal{V}_h} \|u - u_h\|_{\#, \omega_{\mathbf{a}}}^2,$$

$$\sum_{\mathbf{a} \in \mathcal{V}_h} \|u - u_h\|_{\#, \omega_{\mathbf{a}}}^2 \leq (d+1) \|u - u_h\|_{\#}^2.$$

# Distance to $H_0^1(\Omega)$

## Theorem

Let  $u \in H_0^1(\Omega)$  and  $u_h \in H^1(\mathcal{T}_h)$  satisfying

$$\langle \llbracket u_h \rrbracket, 1 \rangle_e = 0 \quad \forall e \in \mathcal{E}_h$$

be arbitrary. Then

$$\inf_{s \in H_0^1(\Omega)} \|\nabla(u_h - s)\|^2 \leq (d+1) C_{\text{cont,bPF}}^2 \sum_{\mathbf{a} \in \mathcal{V}_h} \inf_{s^{\mathbf{a}} \in H_{\#}^1(\omega_{\mathbf{a}})} \|\nabla(u_h - s^{\mathbf{a}})\|_{\omega_{\mathbf{a}}}^2,$$

$$\sum_{\mathbf{a} \in \mathcal{V}_h} \inf_{s^{\mathbf{a}} \in H_{\#}^1(\omega_{\mathbf{a}})} \|\nabla(u_h - s^{\mathbf{a}})\|_{\omega_{\mathbf{a}}}^2 \leq (d+1) \inf_{s \in H_0^1(\Omega)} \|\nabla(u_h - s)\|^2.$$

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## Upper bound on the error

## Theorem

Let  $u$  be the weak solution and let  $u_h \in H^1(\mathcal{T}_h)$  satisfying

$$(\underline{\Sigma} \nabla u_h, \nabla \psi_{\mathbf{a}})_{\omega_{\mathbf{a}}} = (f, \psi_{\mathbf{a}})_{\omega_{\mathbf{a}}} \quad \forall \mathbf{a} \in \mathcal{V}_h^{\text{int}}$$

be *arbitrary*. For any equilibrated flux reconstruction and any potential reconstruction,

$$\| \| u - u_h \| \|^2 \leq \sum_{K \in \mathcal{T}_h} (\| \underline{\Sigma} \nabla u_h + \sigma_h \|_K + \eta_{\text{osc}, K})^2 + \sum_{K \in \mathcal{T}_h} \| \nabla (u_h - s_h) \|_K^2.$$

# Lower bound on the error

## Theorem

Let  $u$  be the weak solution, let  $u_h$  be *piecewise polynomial*, and let  $d = 2$ . Then, for  $\sigma_h$  given by *mixed finite element solution of local Neumann problems*, for all  $K \in \mathcal{T}_h$ ,

$$\|\underline{\Sigma} \nabla u_h + \sigma_h\|_K \leq C_{\text{st}} C_{\text{cont,PF}} \sum_{\mathbf{a} \in \mathcal{V}_K} \|u - u_h\|_{\#, \omega_{\mathbf{a}}} + \eta_{\text{osc}, \omega_K},$$

$$\|\underline{\Sigma} \nabla u_h + \sigma_h\| \leq 3C_{\text{st}} C_{\text{cont,PF}} \|u - u_h\|_{\#} + 3C_{\text{st}} \eta_{\text{osc}},$$

and, for  $s_h$  given by *finite element solution of local Dirichlet problems*, for all  $K \in \mathcal{T}_h$ ,

$$\|\nabla(u_h - s_h)\|_K \leq C_{\text{st}} C_{\text{cont,bPF}} \sum_{\mathbf{a} \in \mathcal{V}_K} \inf_{s^{\mathbf{a}} \in H_{\#}^1(\omega_{\mathbf{a}})} \|\nabla(u_h - s^{\mathbf{a}})\|_{\omega_{\mathbf{a}}},$$

$$\|\nabla(u_h - s_h)\| \leq 3C_{\text{st}} C_{\text{cont,bPF}} \inf_{s \in H_0^1(\Omega)} \|\nabla(u_h - s)\|.$$

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# Numerics

## Setting

- $\mathbb{P}_1$  conforming finite element discretization
- estimate

$$\eta := \left\{ \sum_{K \in \mathcal{T}_h} (\|\underline{\Sigma} \nabla u_h + \sigma_h\|_K + \eta_{\text{osc},K})^2 \right\}^{1/2}$$

- effectivity index

$$\text{Eff} := \frac{\eta}{\|u - u_h\|_{\#}}$$

- computable effectivity bounds

$$\text{Eff}_+ := \frac{\eta}{\|\underline{\Sigma} \nabla (u - u_h)\|}, \quad \text{Eff}_- := \frac{\eta}{\frac{(\underline{\Sigma} \nabla (u - u_h), \nabla (T(u - u_h)))}{\|\nabla (T(u - u_h))\|}}$$



# Regular solution

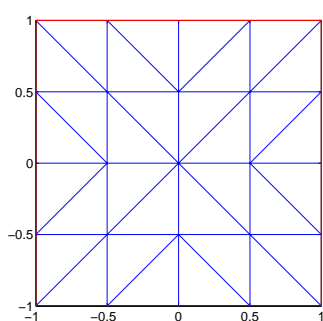
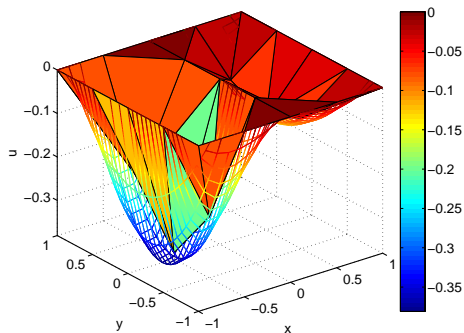
## Data

- $\Omega := (-1, 1) \times (-1, 1)$
- $\Omega_+ := (0, 1) \times (-1, 1)$ ,  $\Omega_- := (-1, 0) \times (-1, 1)$
- $\sigma_+ = 1$ ,  $\sigma_- < 0$
- exact solution

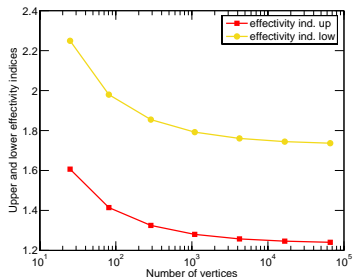
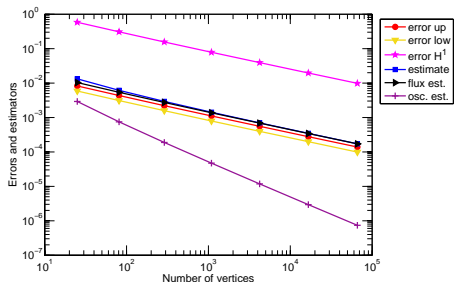
$$u(x, y) = \sigma_- x(x+1)(x-1)(y+1)(y-1) \text{ for } (x, y) \in \Omega_+,$$

$$u(x, y) = x(x+1)(x-1)(y+1)(y-1) \text{ for } (x, y) \in \Omega_-$$

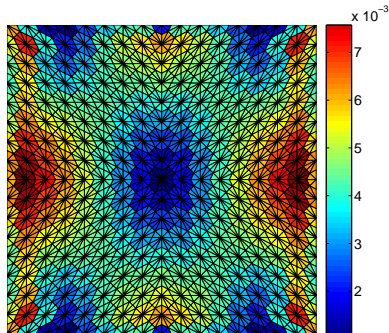
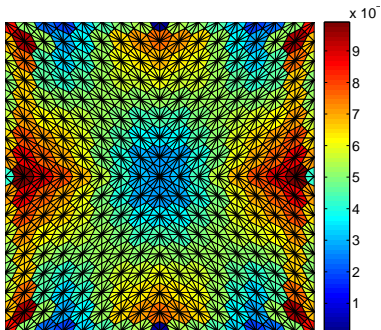
# Exact solution and mesh



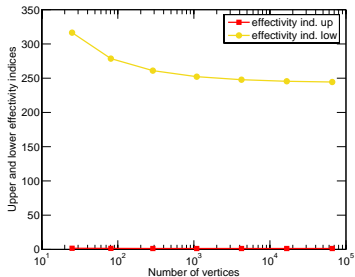
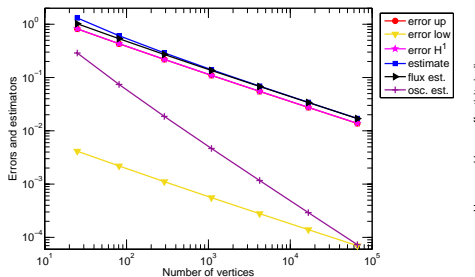
# Errors and estimators, $\sigma_- = -0.01$



# Errors and estimators, $\sigma_- = -1/3$



# Errors and estimators, $\sigma_- = -0.99$



# Singular solution

## Data

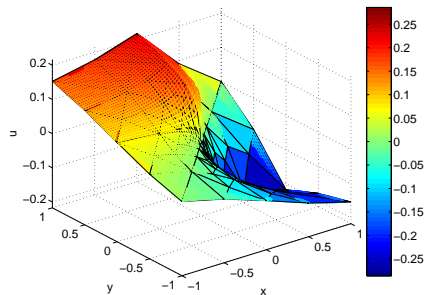
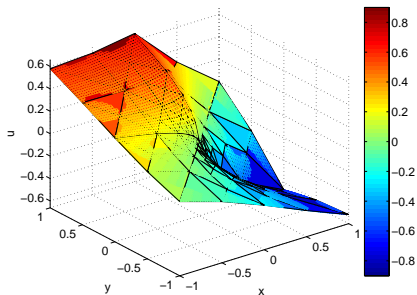
- $\Omega := (-1, 1) \times (-1, 1)$
- $\Omega_+ := (0, 1) \times (0, 1)$ ,  $\Omega_- := \Omega \setminus \overline{\Omega_+}$
- $\sigma_+ = 1$ ,  $\sigma_- < 0$
- exact solution

$u(x, y) = r^\lambda (c_1 \sin(\lambda\theta) + c_2 \sin(\lambda(\pi/2 - \theta)))$  for  $(x, y) \in \Omega_+$ ,

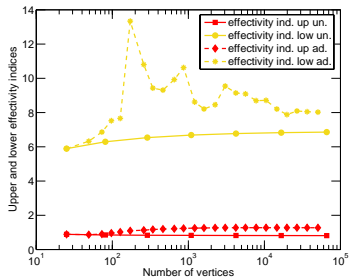
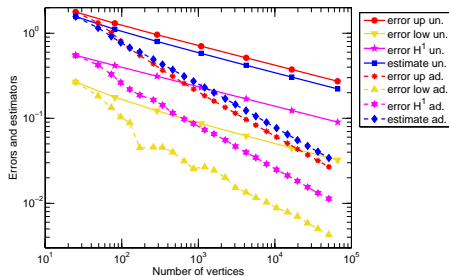
$u(x, y) = r^\lambda (d_1 \sin(\lambda(\theta - \pi/2)) + d_2 \sin(\lambda(2\pi - \theta)))$  for  $(x, y) \in \Omega_-$

- $u \in H^{1+\lambda}(\Omega)$
- $\sigma_- = -5$ :  $\lambda \approx 0.4601069123$
- $\sigma_- = -3.1$ :  $\lambda \approx 0.1391989493$

# Exact solutions

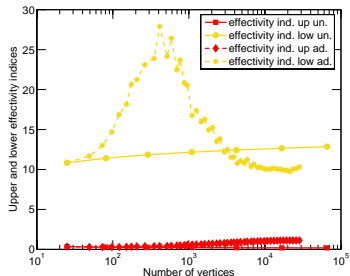
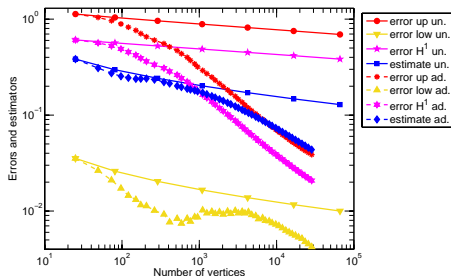


# Errors and estimators, $\sigma_- = -5$

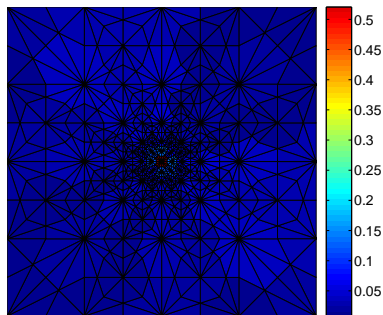
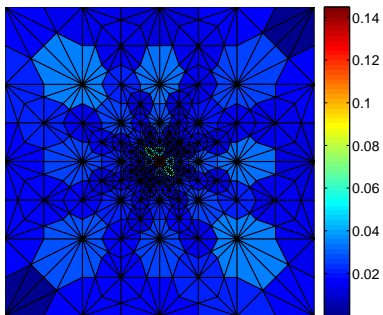




# Errors and estimators, $\sigma_- = 3.1$



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# Conclusions and future directions

## Conclusions

- **robust equivalence** between the intrinsic **dual norm** and computable a posteriori **estimators**
- **unified framework** covering all classical numerical methods
- **easily computable** upper and lower **bounds** for the **dual norm**  $\Rightarrow$  **loss** of robustness
- **cure: localization of the dual norms**

## Future directions

- extension to reaction–diffusion problems
- extensions to nonlinear problems

# Conclusions and future directions

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- unified framework covering all classical numerical methods
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# Bibliography

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- CIARLET JR. P., VOHRALÍK M., Robust a posteriori error control for transmission problems with sign changing coefficients using localization of dual norms, in preparation.
- ERN A., VOHRALÍK M., Polynomial-degree-robust a posteriori estimates in a unified setting for conforming, nonconforming, discontinuous Galerkin, and mixed discretizations, *SIAM J. Numer. Anal.*, to appear.

**Thank you for your attention!**