

A posteriori error estimates: Laplace equation

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Outline

- 1 Introduction
- 2 A posteriori estimates based on potential & flux reconstruction
 - Guaranteed upper bound in a unified framework
 - Potential and flux reconstructions
 - Polynomial-degree-robust local efficiency
 - Applications
 - Numerical illustration
- 3 Algebraic estimates and stopping criteria for iterative solvers
 - Upper and lower bounds on the algebraic error
 - Bounds on the total error
 - Stopping criteria
 - Numerical illustration
- 4 Conclusions and outlook

Optimal a posteriori error estimate

Guaranteed upper bound

- $\|u - u_h\|_{?,\Omega}^2 \leq \sum_{K \in \mathcal{T}_h} \eta_K(u_h)^2$
- no undetermined constant: **error control**

Local efficiency

- $\eta_K(u_h) \leq C_{\text{eff}} \|u - u_h\|_{?, \text{neighbors of } K}$
- **local** error lower bound (optimal space mesh refinement)

Robustness

- C_{eff} independent of data, domain Ω , meshes, solution u , **polynomial degree** of u_h

Asymptotic exactness

- $\sum_{K \in \mathcal{T}_h} \eta_K(u_h)^2 / \|u - u_h\|_{?,\Omega}^2 \searrow 1$
- overestimation factor goes to one with meshes size

Small evaluation cost

- estimators $\eta_K(u_h)$ can be evaluated cheaply (locally)

Error components identification

- $\eta_K(u_h)$ can distinguish the different error components

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Laplace model problem

Model problem

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

- $\Omega \subset \mathbb{R}^d$, $d = 2, 3$ polygon/polyhedron
- $f \in L^2(\Omega)$

Weak formulation

Find $u \in H_0^1(\Omega)$ such that

$$(\nabla u, \nabla v) = (f, v) \quad \forall v \in H_0^1(\Omega)$$

Properties of the weak solution

- $u \in H_0^1(\Omega)$ (primal variable constraint)
- $\sigma := -\nabla u$ (constitutive relation)
- $\nabla \cdot \sigma = f$ (equilibrium)
- $\sigma \in \mathbf{H}(\text{div}, \Omega)$ (dual variable constraint)

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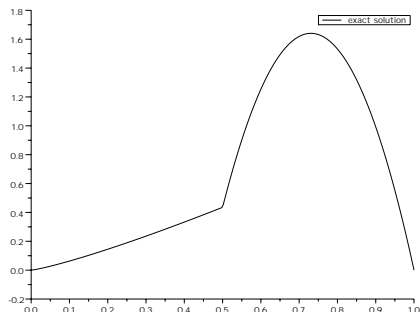
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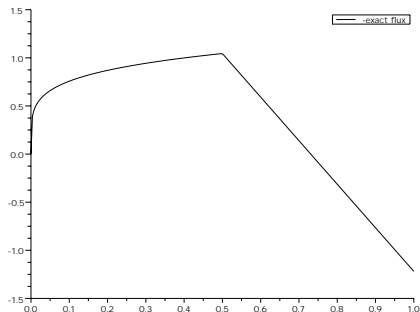
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Exact solution and flux

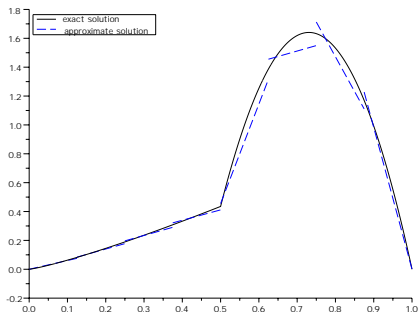


Solution u is continuous

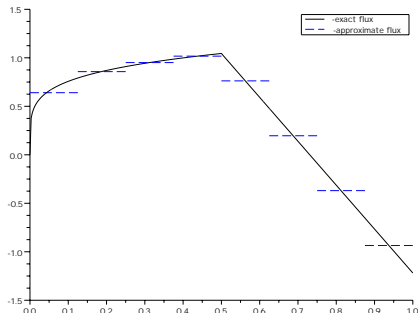


Flux $\sigma := -\underline{K}\nabla u$ is continuous

Approximate solution and flux

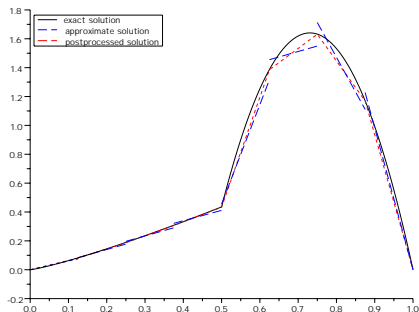


Approximate solution u_h is **not** necessarily continuous

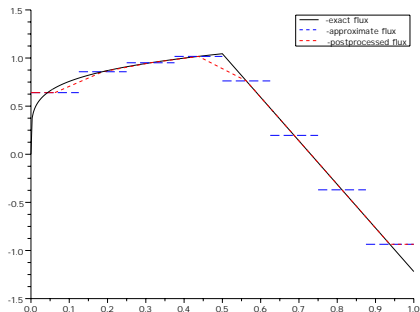


Approximate flux $-\mathbf{K}\nabla u_h$ is **not** necessarily continuous

Potential and flux reconstructions



Potential reconstruction



Flux reconstruction

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Theorem (A guaranteed a posteriori error estimate, Prager and Synge (1947), Ladevèze (1975), Dari, Durán, Padra, & Vampa (1996), Ainsworth (2005), Kim (2007), Vohralík (2007), ...)

- Let $u \in H_0^1(\Omega)$ be the weak solution;
- $u_h \in H^1(\mathcal{T}_h) := \{v \in L^2(\Omega), v|_K \in H^1(K) \forall K \in \mathcal{T}_h\}$ be arbitrary
- $s_h \in H_0^1(\Omega)$ and $\sigma_h \in \mathbf{H}(\text{div}, \Omega)$ be such that

$$(\nabla \cdot \sigma_h, 1)_K = (f, 1)_K \text{ for all } K \in \mathcal{T}_h.$$

Then

$$\begin{aligned} \|\nabla(u - u_h)\|^2 \leq & \sum_{K \in \mathcal{T}_h} \left(\underbrace{\|\nabla u_h + \sigma_h\|_K}_{\text{constitutive relation}} + \underbrace{\frac{h_K}{\pi} \|f - \nabla \cdot \sigma_h\|_K}_{\text{equilibrium}} \right)^2 \\ & + \sum_{K \in \mathcal{T}_h} \underbrace{\|\nabla(u_h - s_h)\|_K^2}_{\text{primal constraint}}. \end{aligned}$$

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Proof I

Proof.

- define $s \in H_0^1(\Omega)$ by

$$(\nabla s, \nabla v) = (\nabla u_h, \nabla v) \quad \forall v \in H_0^1(\Omega)$$

- develop (Pythagoras)

$$\|\nabla(u - u_h)\|^2 = \|\nabla(u - s)\|^2 + \|\nabla(s - u_h)\|^2$$

- projection definition of s :

$$\|\nabla(s - u_h)\| = \underbrace{\min_{v \in H_0^1(\Omega)} \|\nabla(v - u_h)\|}_{\text{distance of } u_h \text{ to } H_0^1(\Omega)}$$

- dual norm characterization, definition of s , definition of u :

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Proof II

Proof (continuation).

- nonconformity upper bound:

$$\min_{v \in H_0^1(\Omega)} \|\nabla(v - u_h)\| \leq \|\nabla(u_h - s_h)\|$$

- adding and subtracting equilibrated flux, Green theorem:

$$(f, \varphi) - (\nabla u_h, \nabla \varphi) = (f - \nabla \cdot \sigma_h, \varphi) - (\nabla u_h + \sigma_h, \nabla \varphi)$$

- Cauchy–Schwarz and Poincaré inequalities, equilibration:

$$- (\nabla u_h + \sigma_h, \nabla \varphi)$$

$$(f - \nabla \cdot \sigma_h, \varphi) = \sum_{K \in \mathcal{T}_h} (f - \nabla \cdot \sigma_h, \varphi)_K$$

$$\leq \sum_{K \in \mathcal{T}_h} \frac{h_K}{\pi} \|f - \nabla \cdot \sigma_h\|_K \|\nabla \varphi\|_K$$

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$$- (\nabla u_h + \sigma_h, \nabla \varphi) = - \sum_{K \in \mathcal{T}_h} (\nabla u_h + \sigma_h, \nabla \varphi)_K$$

$$(f - \nabla \cdot \sigma_h, \varphi) = \sum_{K \in \mathcal{T}_h} (f - \nabla \cdot \sigma_h, \varphi - \varphi_K)_K$$

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Proof (continuation).

- nonconformity upper bound:

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- 2 A posteriori estimates based on potential & flux reconstruction
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Global potential and flux reconstructions

Ideally

$$s_h := \arg \min_{\mathbf{v}_h \in \mathbf{V}_h} \|\nabla(u_h - \mathbf{v}_h)\|$$

$$\sigma_h := \arg \min_{\mathbf{v}_h \in \mathbf{V}_h, \nabla \cdot \mathbf{v}_h = \Pi_{Q_h} f} \|\nabla u_h + \mathbf{v}_h\|$$

- ✓ computable, discrete spaces $V_h \subset H_0^1(\Omega)$, $\mathbf{V}_h \subset \mathbf{H}(\text{div}, \Omega)$, $Q_h \subset L^2(\Omega)$
- ✗ too expensive, **global minimization** problems (the hypercircle method ...)

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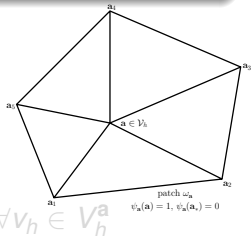
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Local potential reconstruction

Definition (Construction of s_h , \approx Carstensen and Merdon (2013), EV (2015))

For each $\mathbf{a} \in \mathcal{V}_h$, solve the **local conforming FE problem**

$$s_h^{\mathbf{a}} := \arg \min_{v_h \in V_h^{\mathbf{a}}} \|\nabla(\psi_{\mathbf{a}} u_h - v_h)\|_{\omega_{\mathbf{a}}}.$$



Equivalent form

Find $s_h^{\mathbf{a}} \in V_h^{\mathbf{a}}$ such that

$$(\nabla s_h^{\mathbf{a}}, \nabla v_h)_{\omega_{\mathbf{a}}} = (\nabla(\psi_{\mathbf{a}} u_h), \nabla v_h)_{\omega_{\mathbf{a}}}$$

Key ideas

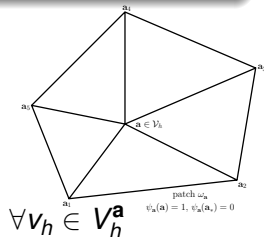
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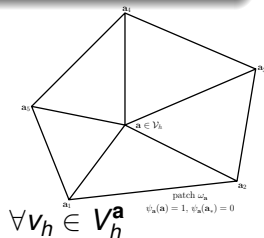
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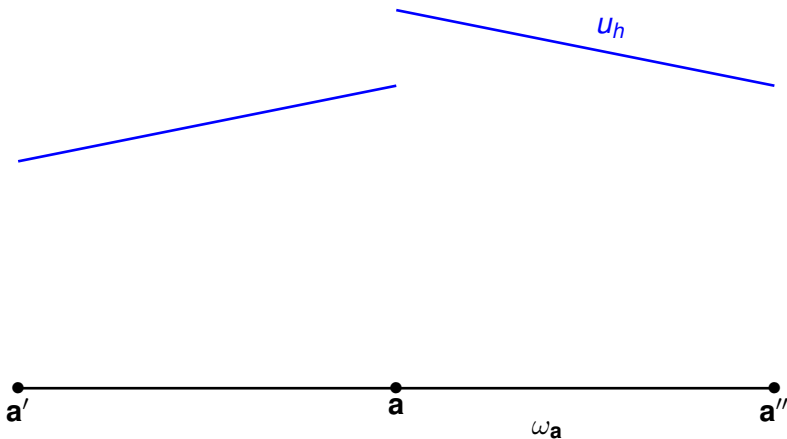
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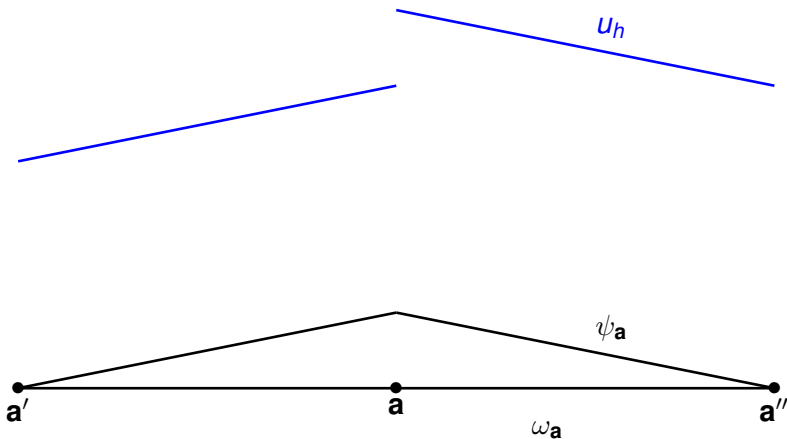
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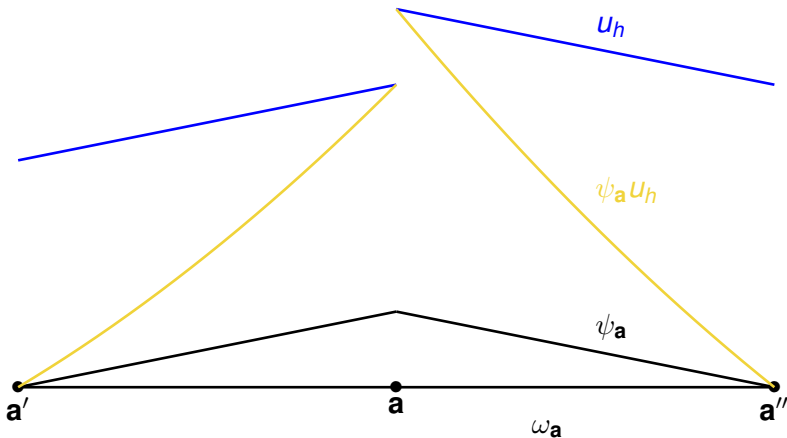
Potential reconstruction in 1D



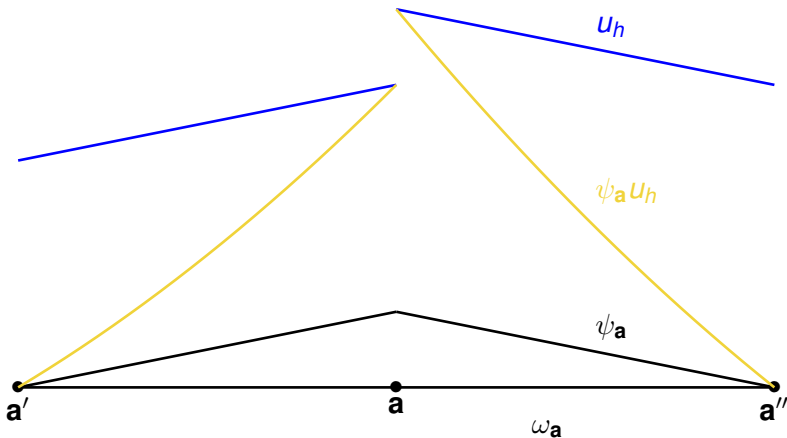
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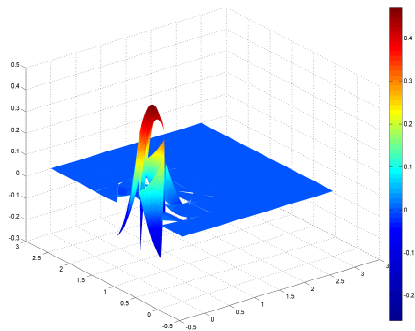
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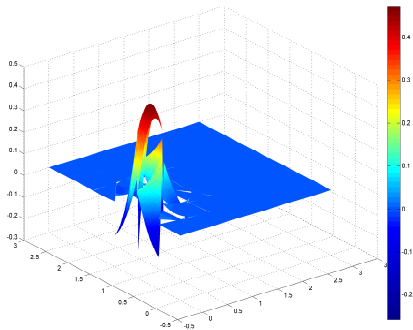


Potential reconstruction in 2D

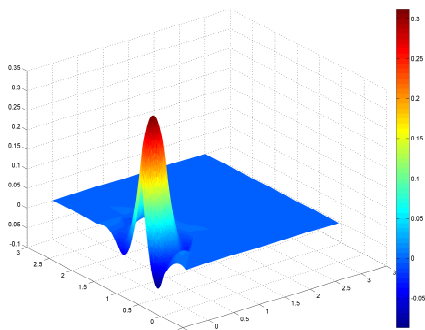


Potential u_h

Potential reconstruction in 2D



Potential u_h



Potential reconstruction s_h

Local flux reconstructions

Assumption A (Galerkin orthogonality wrt hat functions)

There holds

$$(\nabla u_h, \nabla \psi_{\mathbf{a}})_{\omega_{\mathbf{a}}} = (f, \psi_{\mathbf{a}})_{\omega_{\mathbf{a}}} \quad \forall \mathbf{a} \in \mathcal{V}_h^{\text{int}}.$$

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For each $\mathbf{a} \in \mathcal{V}_h$, solve the **local mixed FE problem**

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Neumann compatibility condition

- for $\mathbf{a} \in \mathcal{V}_h^{\operatorname{int}}$, one needs $(\psi_{\mathbf{a}} f - \nabla \psi_{\mathbf{a}} \cdot \nabla u_h, 1)_{\omega_{\mathbf{a}}} = 0 \Rightarrow$

Divergence

- Neumann compatibility condition gives

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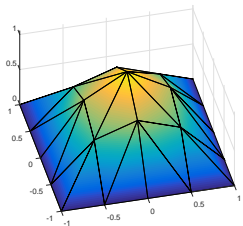
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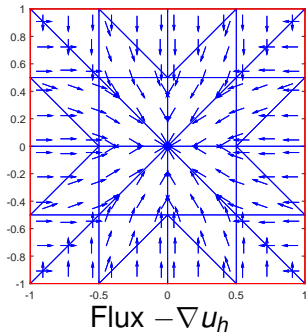
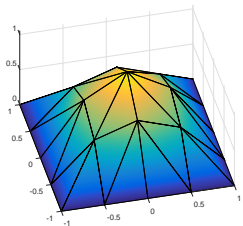
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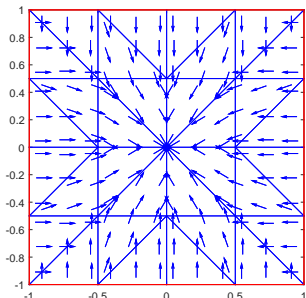
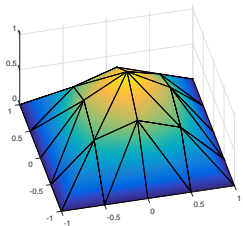
Equilibrated flux reconstruction



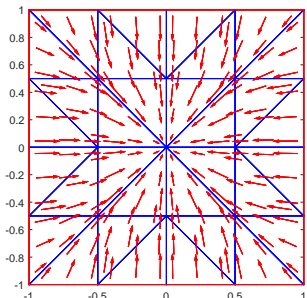
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Flux $-\nabla u_h$



Flux reconstruction σ_h

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Polynomial-degree-robust efficiency

Assumption B (Piecewise polynomials, data, and meshes)

The approximation u_h and the datum f are *piecewise polynomial*. The degrees of the MFE reconstructions σ_h and s_h are chosen correspondingly. The meshes \mathcal{T}_h are *shape-regular*.

Theorem (Polynomial-degree-robust efficiency Braess, Pillwein, and Schöberl (2009); Costabel and McIntosh (2010); Demkowicz, Gopalakrishnan, and Schöberl (2012), EV (2015))

Let u be the weak solution and let *Assumptions A and B* hold. Then there exists constants $C_{\text{st}}, C_{\text{cont,PF}}, C_{\text{cont,bPF}} > 0$ only depending on the shape-regularity parameter $\kappa_{\mathcal{T}}$ such that

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$$\begin{aligned} \|\sigma_h^a + \psi_a \nabla u_h\|_{\omega_a} &\leq C_{\text{st}} C_{\text{cont,PF}} \|\nabla(u - u_h)\|_{\omega_a}, \\ \|\nabla(\psi_a u_h - s_h^a)\|_{\omega_a} &\leq C_{\text{st}} C_{\text{cont,bPF}} \|\nabla(u - u_h)\|_{\omega_a} + \text{jumps}. \end{aligned}$$

Remarks

- equivalence error–estimate
- maximal overestimation factor guaranteed

Existing results

Fundamental results on a reference tetrahedron

- Costabel & McIntosh (2010): bounded right inverse of the divergence operator for polynomial volume data
- Demkowicz, Gopalakrishnan, Schöberl (2009, 2012): polynomial extensions in H^1 and $\mathbf{H}(\text{div})$ for polynomial boundary data

Stable broken $\mathbf{H}(\text{div})$ polynomial extension on a patch

- Braess, Pillwein, & Schöberl (2009), 2D
- p -robustness of conforming finite elements

Stable broken H^1 polynomial extensions on a patch

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Potentials (any BCs, physical tetrahedron)

Lemma (H^1 polynomial extension on a tetrahedron)

Let $K \in \mathcal{T}_h$, $\mathcal{E}_K^D \subset \mathcal{E}_K$. Let $r \in \mathbb{P}_p(\mathcal{E}_K^D)$ be continuous on \mathcal{E}_K^D . Then for C only depending on the shape regularity of K ,

$$\min_{\substack{v_h \in \mathbb{P}_p(K) \\ v_h = r_e \text{ on all } e \in \mathcal{E}_K^D}} \|\nabla v_h\|_K \leq C \underbrace{\min_{\substack{v \in H^1(K) \\ v = r_e \text{ on all } e \in \mathcal{E}_K^D}} \|\nabla v\|_K}_{\|r\|_{H^{1/2}(\partial K)}} .$$

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Context

$$\begin{aligned} -\Delta \zeta_K &= 0 && \text{in } K, \\ \zeta_K &= r_e && \text{on all } e \in \mathcal{E}_K^D, \\ -\nabla \zeta_K \cdot \mathbf{n}_K &= 0 && \text{on all } e \in \mathcal{E}_K \setminus \mathcal{E}_K^D. \end{aligned}$$

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Let $K \in \mathcal{T}_h$, $\mathcal{E}_K^N \subset \mathcal{E}_K$. Let $r \in \mathbb{P}_p(\mathcal{E}_K^N) \times \mathbb{P}_p(K)$, satisfying $\sum_{e \in \mathcal{E}_K} (r_e, 1)_e = (r_K, 1)_K$ if $\mathcal{E}_K^N = \mathcal{E}_K$. Then for $C = C(\kappa_K) > 0$,

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A graph result for patch enumerations in 3D (shellability of polytopes, e.g. Ziegler, Lectures on Polytopes)

Two families of faces

- already visited faces: $\mathcal{E}_i^\# := \{e \in \mathcal{E}_a^{\text{int}}, e = \partial K_i \cap \partial K_j, j < i\}$
- yet unvisited faces: $\mathcal{E}_i^b := \mathcal{E}_a^{\text{int}} \cap \mathcal{E}_{K_i} \setminus \mathcal{E}_i^\#$
- $|\mathcal{E}_i^b| + |\mathcal{E}_i^\#| = 3$, $\mathcal{E}_1^\# = \emptyset$, and $\mathcal{E}_{|\mathcal{T}_a|}^b = \emptyset$

Lemma (Interior patch enumeration)

There exists an enumeration of the patch \mathcal{T}_a so that

- If $|\mathcal{E}_i^\#| \geq 2$ with $\{e_i^1, e_i^2\} \subset \mathcal{E}_i^\#$, then $K_j \in \mathcal{T}_{e_i^1 \cap e_i^2} \setminus \{K_i\}$ implies $j < i$.
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Extension to a patch

Potential case

$$r_e := \psi_{\mathbf{a}}[[u_h]]|_e,$$

Flux case

$$r_e := \psi_{\mathbf{a}}[[\nabla u_h \cdot \mathbf{n}_e]]|_e,$$

$$r_K := \psi_{\mathbf{a}}(f + \Delta u_h)|_K$$

Corollary (Best piecewise polynomial approximation on a patch)

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Outline

- 1 Introduction
- 2 A posteriori estimates based on potential & flux reconstruction
 - Guaranteed upper bound in a unified framework
 - Potential and flux reconstructions
 - Polynomial-degree-robust local efficiency
 - **Applications**
 - Numerical illustration
- 3 Algebraic estimates and stopping criteria for iterative solvers
 - Upper and lower bounds on the algebraic error
 - Bounds on the total error
 - Stopping criteria
 - Numerical illustration
- 4 Conclusions and outlook

Conforming finite elements

Conforming finite elements

Find $u_h \in V_h$ such that

$$(\nabla u_h, \nabla v_h) = (f, v_h) \quad \forall v_h \in V_h.$$

- $V_h := \mathbb{P}_p(\mathcal{T}_h) \cap H_0^1(\Omega)$, $p \geq 1$
- ✓ Assumption A: take $v_h = \psi_a$
- ✓ Assumption B: technical, always satisfied

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Find $u_h \in V_h$ such that

$$\sum_{K \in \mathcal{T}_h} (\nabla u_h, \nabla v_h)_K - \sum_{e \in \mathcal{E}_h} \{ \langle \{\{\nabla u_h\}\} \cdot \mathbf{n}_e, \llbracket v_h \rrbracket \rangle_e + \theta \langle \{\{\nabla v_h\}\} \cdot \mathbf{n}_e, \llbracket u_h \rrbracket \rangle_e \} \\ + \sum_{e \in \mathcal{E}_h} \langle \alpha h_e^{-1} \llbracket u_h \rrbracket, \llbracket v_h \rrbracket \rangle_e = (f, v_h) \quad \forall v_h \in V_h.$$

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 - estimates for the discrete gradient

$$\nabla_d u_h := \nabla u_h - \theta \sum_{e \in \mathcal{E}_h} \iota_e(\llbracket u_h \rrbracket)$$

- jumps lifting operator $\iota_e : L^2(e) \rightarrow [\mathbb{P}_0(\mathcal{T}_e)]^2$

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$$\nabla_d u_h := \nabla u_h - \theta \sum_{e \in \mathcal{E}_h} \iota_e(\llbracket u_h \rrbracket)$$

- jumps lifting operator $\iota_e : L^2(e) \rightarrow [\mathbb{P}_0(\mathcal{T}_e)]^2$

$$(\iota_e(\llbracket u_h \rrbracket), \mathbf{v}_h) = \langle \{\{\mathbf{v}_h\}\} \cdot \mathbf{n}_e, \llbracket u_h \rrbracket \rangle_e \quad \forall \mathbf{v}_h \in [\mathbb{P}_0(\mathcal{T}_e)]^2$$
- \Rightarrow modified Galerkin orthogonality

$$(\nabla_d u_h, \nabla \psi_{\mathbf{a}})_{\omega_{\mathbf{a}}} = (f, \psi_{\mathbf{a}})_{\omega_{\mathbf{a}}} \quad \forall \mathbf{a} \in \mathcal{T}_h$$

Mixed finite elements

Mixed finite elements

Find a couple $(\sigma_h, \bar{u}_h) \in \mathbf{V}_h \times Q_h$ such that

$$\begin{aligned} (\sigma_h, \mathbf{v}_h) - (\bar{u}_h, \nabla \cdot \mathbf{v}_h) &= 0 & \forall \mathbf{v}_h \in \mathbf{V}_h, \\ (\nabla \cdot \sigma_h, q_h) &= (f, q_h) & \forall q_h \in Q_h. \end{aligned}$$

- postprocessed solution $u_h \in V_h$, $V_h := \mathbb{P}_p(\mathcal{T}_h)$, $p \geq 1$;
 $v_h \in V_h$ satisfy

$$\langle \llbracket v_h \rrbracket, q_h \rangle_e = 0 \quad \forall q_h \in \mathbb{P}_{p'}(e), \forall e \in \mathcal{E}_h$$

- ✓ **Assumption A:** no need for flux reconstruction, σ_h comes from the discretization
- ✓ no jumps

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Outline

- 1 Introduction
- 2 A posteriori estimates based on potential & flux reconstruction
 - Guaranteed upper bound in a unified framework
 - Potential and flux reconstructions
 - Polynomial-degree-robust local efficiency
 - Applications
 - Numerical illustration
- 3 Algebraic estimates and stopping criteria for iterative solvers
 - Upper and lower bounds on the algebraic error
 - Bounds on the total error
 - Stopping criteria
 - Numerical illustration
- 4 Conclusions and outlook

Numerics: smooth case

Model problem

$$\begin{aligned} -\Delta u &= f & \text{in } \Omega &:= (0, 1)^2, \\ u &= 0 & \text{on } \partial\Omega \end{aligned}$$

Exact solution

$$u(x, y) = \sin(2\pi x) \sin(2\pi y)$$

Discretization

- symmetric interior penalty discontinuous Galerkin method
- unstructured triangular grids
- uniform h refinement

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Uniform refinement: asymptotic exactness

h	p	$\ \nabla_d(u-u_h)\ $	$\ \nabla_d u_h + \sigma_h\ $	η_{osc}	$\ \nabla_d(u_h - S_h)\ $	η	ρ^{eff}
h_0	1	1.07E-00	1.12E-00	5.55E-02	4.16E-01	1.25E-00	1.17
$\approx h_0/2$		5.56E-01	5.71E-01	7.42E-03	1.82E-01	6.07E-01	1.09
$\approx h_0/4$		2.92E-01	2.96E-01	1.04E-03	8.77E-02	3.10E-01	1.06
$\approx h_0/8$		1.39E-01	1.40E-01	1.10E-04	3.85E-02	1.45E-01	1.04
h_0	2	1.54E-01	1.55E-01	5.10E-03	3.05E-02	1.63E-01	1.06
$\approx h_0/2$		4.07E-02	4.13E-02	3.53E-04	7.55E-03	4.23E-02	1.04
$\approx h_0/4$		1.10E-02	1.12E-02	2.51E-05	1.97E-03	1.14E-02	1.03
$\approx h_0/8$		2.50E-03	2.54E-03	1.30E-06	4.21E-04	2.57E-03	1.03
h_0	3	1.37E-02	1.37E-02	3.58E-04	1.74E-03	1.41E-02	1.03
$\approx h_0/2$		1.85E-03	1.85E-03	1.26E-05	2.10E-04	1.88E-03	1.01
$\approx h_0/4$		2.60E-04	2.60E-04	4.73E-07	2.54E-05	2.62E-04	1.01
$\approx h_0/8$		2.75E-05	2.75E-05	1.15E-08	2.55E-06	2.76E-05	1.01
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h_0	5	5.64E-05	5.63E-05	1.06E-06	4.50E-06	5.75E-05	1.02
$\approx h_0/2$		2.01E-06	2.01E-06	9.88E-09	1.46E-07	2.03E-06	1.01
$\approx h_0/4$		7.74E-08	7.73E-08	1.01E-10	4.35E-09	7.76E-08	1.00
$\approx h_0/8$		1.86E-09	1.86E-09	1.70E-12	1.00E-10	1.86E-09	1.00
h_0	6	2.85E-06	2.85E-06	4.70E-08	2.18E-07	2.90E-06	1.02
$\approx h_0/2$		5.42E-08	5.42E-08	2.40E-10	4.02E-09	5.46E-08	1.01
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Uniform refinement: asymptotic exactness

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Uniform refinement: asymptotic exactness

h	p	$\ \nabla_d(u-u_h)\ $	$\ u-u_h\ _{DG}$	$\ \nabla_d u_h + \sigma_h\ $	η_{osc}	$\ \nabla_d(u_h - S_h)\ $	η	η_{DG}	ρ^{eff}	ρ_{DG}^{eff}
h_0	1	1.07E-00	1.09E-00	1.12E-00	5.55E-02	4.16E-01	1.25E-00	1.26E-00	1.17	1.16
$\approx h_0/2$		5.56E-01	5.61E-01	5.71E-01	7.42E-03	1.82E-01	6.07E-01	6.11E-01	1.09	1.09
$\approx h_0/4$		2.92E-01	2.93E-01	2.96E-01	1.04E-03	8.77E-02	3.10E-01	3.11E-01	1.06	1.06
$\approx h_0/8$		1.39E-01	1.39E-01	1.40E-01	1.10E-04	3.85E-02	1.45E-01	1.45E-01	1.04	1.04
h_0	2	1.54E-01	1.55E-01	1.55E-01	5.10E-03	3.05E-02	1.63E-01	1.64E-01	1.06	1.06
$\approx h_0/2$		4.07E-02	4.09E-02	4.13E-02	3.53E-04	7.55E-03	4.23E-02	4.26E-02	1.04	1.04
$\approx h_0/4$		1.10E-02	1.11E-02	1.12E-02	2.51E-05	1.97E-03	1.14E-02	1.15E-02	1.03	1.03
$\approx h_0/8$		2.50E-03	2.52E-03	2.54E-03	1.30E-06	4.21E-04	2.57E-03	2.59E-03	1.03	1.03
h_0	3	1.37E-02	1.37E-02	1.37E-02	3.58E-04	1.74E-03	1.41E-02	1.41E-02	1.03	1.03
$\approx h_0/2$		1.85E-03	1.85E-03	1.85E-03	1.26E-05	2.10E-04	1.88E-03	1.88E-03	1.01	1.01
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$\approx h_0/8$		2.58E-07	2.59E-07	2.58E-07	8.96E-11	2.47E-08	2.60E-07	2.60E-07	1.01	1.01
h_0	5	5.64E-05	5.64E-05	5.63E-05	1.06E-06	4.50E-06	5.75E-05	5.75E-05	1.02	1.02
$\approx h_0/2$		2.01E-06	2.01E-06	2.01E-06	9.88E-09	1.46E-07	2.03E-06	2.03E-06	1.01	1.01
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Numerics: singular case

Model problem

$$\begin{aligned} -\Delta u &= 0 & \text{in } \Omega &:= (-1, 1)^2 \setminus [0, 1]^2, \\ u &= u_D & \text{on } \partial\Omega \end{aligned}$$

Exact solution

$$u(r, \phi) = r^{2/3} \sin(2\phi/3)$$

Discretization

- incomplete interior penalty discontinuous Galerkin method
- unstructured non-nested triangular grids
- *hp*-adaptive refinement

Numerics: singular case

Model problem

$$\begin{aligned} -\Delta u &= 0 & \text{in } \Omega &:= (-1, 1)^2 \setminus [0, 1]^2, \\ u &= u_D & \text{on } \partial\Omega \end{aligned}$$

Exact solution

$$u(r, \phi) = r^{2/3} \sin(2\phi/3)$$

Discretization

- incomplete interior penalty discontinuous Galerkin method
- unstructured non-nested triangular grids
- *hp*-adaptive refinement

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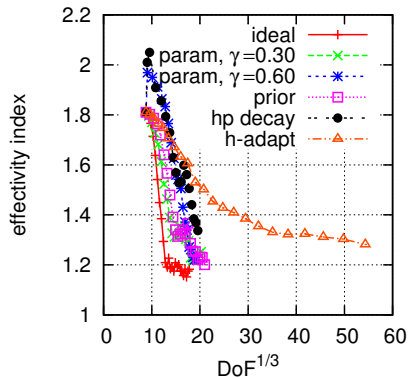
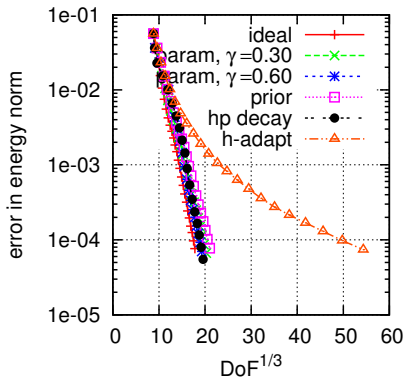
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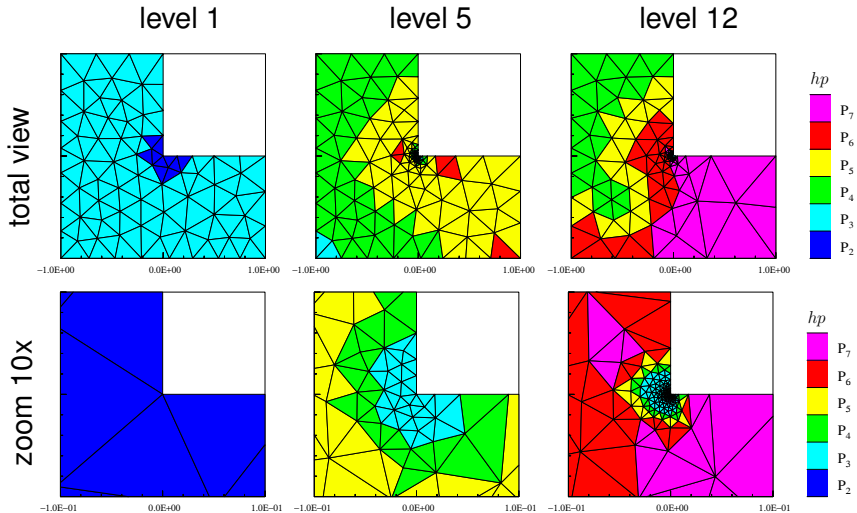
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hp-adaptive refinement: exponential convergence



hp-refinement grids



Outline

- 1 Introduction
- 2 A posteriori estimates based on potential & flux reconstruction
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- 3 Algebraic estimates and stopping criteria for iterative solvers
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- 4 Conclusions and outlook

Setting

Laplace problem

Find $u \in H_0^1(\Omega)$ such that

$$(\nabla u, \nabla v) = (f, v) \quad \forall v \in H_0^1(\Omega)$$

Finite element approximation

Find $u_h \in V_h := \mathbb{P}_p(\mathcal{T}_h) \cap H_0^1(\Omega)$, $p \geq 1$, such that

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Linear algebraic system

Find $U_h \in \mathbb{R}^N$ such that

$$\mathbb{A}_h U_h = F_h$$

Algebraic solver (iterative)

On each iteration $i \geq 1$: approximate vector $U_h^i \in \mathbb{R}^N$ such that

$$\mathbb{A}_h U_h^i = F_h - R_h^i \quad (R_h^i := F_h - \mathbb{A}_h U_h^i)$$

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Goals

Algebraic error

$$\|\nabla(u_h - u_h^i)\|$$

Total error

$$\|\nabla(u - u_h^i)\|$$

Discretization error

$$\|\nabla(u - u_h)\|$$

Goals: find **a posteriori estimates** for any $i \geq 1$

Algebraic error

$$\underline{\eta}_{\text{alg}}^i \leq \|\nabla(u_h - u_h^i)\| \leq \eta_{\text{alg}}^i$$

Total error

$$\underline{\eta}_{\text{tot}}^i \leq \|\nabla(u - u_h^i)\| \leq \eta_{\text{tot}}^i$$

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Further goals

- estimate the **distribution** of the errors (local efficiency)
- design reliable (local) **stopping criteria**

The pathway

Algebraic residual representer

- $r_h^i \in \mathbb{P}_p(\mathcal{T}_h)$ represents R_h^i
- gives equivalent form of residual equation: $u_h^i \in V_h$ s.t.

$$(\nabla u_h^i, \nabla \psi_l) = (f, \psi_l) - (r_h^i, \psi_l) \quad \forall l = 1, \dots, N$$

- $(r_h^i, \psi_l) = (R_h^i)_l, l = 1, \dots, N$
- consequence of equations for u_h and u_h^i :

$$(\nabla(u_h - u_h^i), \nabla v_h) = (r_h^i, v_h) \quad \forall v_h \in V_h$$

Tools

- flux and potential reconstructions
- local Neumann MFE & local Dirichlet FE problems
- separate components for algebraic & discretization errors
- multilevel hierarchy (algebraic components)

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Algebraic error upper bound

Theorem (Upper bound via algebraic error flux reconstruction)

Let $\sigma_{h,\text{alg}}^i \in \mathbf{H}(\text{div}, \Omega)$ be such that $\nabla \cdot \sigma_{h,\text{alg}}^i = r_h^i$. Then

$$\underbrace{\|\nabla(u_h - u_h^i)\|}_{\text{algebraic error}} \leq \underbrace{\|\sigma_{h,\text{alg}}^i\|}_{\text{upper algebraic est.}}.$$

Proof.

$$\|\nabla(u_h - u_h^i)\| = \sup_{v_h \in V_h, \|\nabla v_h\|=1} (\nabla(u_h - u_h^i), \nabla v_h);$$

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Previous cheap constructions of $\sigma_{h,\text{alg}}^i$

- 1 sequential sweep through \mathcal{T}_h , local min. (JSV (2010))
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Algebraic error flux reconstruction, two-level setting

Definition (Coarse grid Riesz representer)

Find $\rho_{H,\text{alg}}^i \in V_H := \mathbb{P}_1(\mathcal{T}_H) \cap H_0^1(\Omega)$ such that

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- \mathbb{P}_1 FEs on \mathcal{T}_H (no need for multigrid w/o post-smoothing)
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Definition (Algebraic error flux reconstruction)

$$\sigma_{h,\text{alg}}^{\mathbf{a},i} := \arg \min_{\mathbf{v}_h \in \mathbf{V}_h, \nabla \cdot \mathbf{v}_h = \Pi_{Q_h^{\mathbf{a}}}(\psi_{\mathbf{a}} r_h^i - \nabla \psi_{\mathbf{a}} \cdot \nabla \rho_{H,\text{alg}}^i)} \|\mathbf{v}_h\|_{\omega_{\mathbf{a}}},$$

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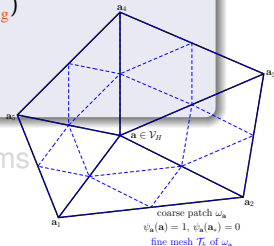
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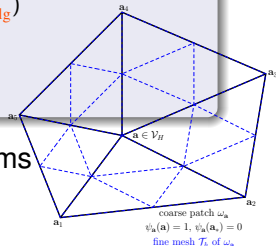
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Divergence of the algebraic error flux reconstruction

Lemma (Divergence of $\sigma_{h,\text{alg}}^i$)

There holds $\nabla \cdot \sigma_{h,\text{alg}}^i = r_h^i$.

Proof.

- every fine grid element $K \in \mathcal{T}_h$ lies exactly in $(d+1)$ coarse patches $\omega_{\mathbf{a}}$, $\mathbf{a} \in \mathcal{V}_H$
- partition of unity $\sum_{\mathbf{a} \in \mathcal{V}_H, K \subset \overline{\omega_{\mathbf{a}}}} \psi^{\mathbf{a}} = 1|_K$
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$$\begin{aligned} \nabla \cdot \sigma_{h,\text{alg}}^i|_K &= \sum_{\mathbf{a} \in \mathcal{V}_H, K \subset \overline{\omega_{\mathbf{a}}}} \nabla \cdot \sigma_{h,\text{alg}}^{\mathbf{a},i}|_K \\ &= \sum_{\mathbf{a} \in \mathcal{V}_H, K \subset \overline{\omega_{\mathbf{a}}}} \Pi_{Q_h}(\psi_{\mathbf{a}} r_h^i - \nabla \psi_{\mathbf{a}} \cdot \nabla \rho_{H,\text{alg}}^i)|_K = r_h^i|_K \end{aligned}$$

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Algebraic error lower bound

Theorem (Lower bound via algebraic residual liftings)

Let $\rho_{h,\text{alg}}^i \in V_h$ be *arbitrary*. Then

$$\underbrace{\|\nabla(u_h - u_h^i)\|}_{\text{algebraic error}} \geq \frac{(r_h^i, \rho_{h,\text{alg}}^i)}{\underbrace{\|\nabla \rho_{h,\text{alg}}^i\|}_{\text{lower algebraic est.}}} .$$

Proof.

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Algebraic residual lifting, two-level setting

Definition (Algebraic residual lifting, \approx Bank & Smith (1993), Oswald (1993), Růde (1993), ..., Ern & V. (2015))

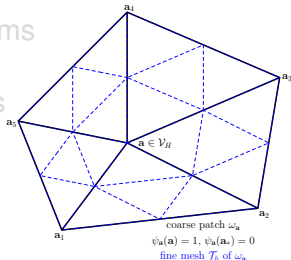
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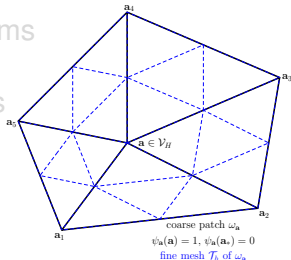
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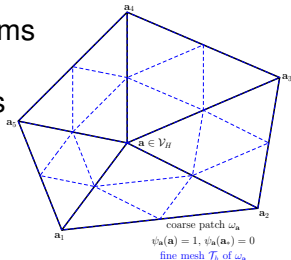
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Discretization flux reconstruction

Definition (Discretization flux reconstruction, Braes & Schöberl (2008), EV (2013))

$$\sigma_{h,\text{dis}}^{\mathbf{a},i} := \arg \min_{\mathbf{v}_h \in \mathbf{V}_h^{\mathbf{a}}, \nabla \cdot \mathbf{v}_h = \Pi_{Q_h^{\mathbf{a}}}(f\psi^{\mathbf{a}} - \nabla u_h^i \cdot \nabla \psi^{\mathbf{a}} - r_h^i \psi^{\mathbf{a}})} \|\psi^{\mathbf{a}} \nabla u_h^i + \mathbf{v}_h\|_{\omega_{\mathbf{a}}},$$

$$\sigma_{h,\text{dis}}^i := \sum_{\mathbf{a} \in \mathcal{V}_h} \sigma_{h,\text{dis}}^{\mathbf{a},i}$$

Neumann compatibility condition satisfied:

$$(\nabla u_h^i, \nabla \psi^{\mathbf{a}})_{\omega_{\mathbf{a}}} = (f, \psi^{\mathbf{a}})_{\omega_{\mathbf{a}}} - (r_h^i, \psi^{\mathbf{a}})_{\omega_{\mathbf{a}}} \quad \forall \mathbf{a} \in \mathcal{V}_h^{\text{int}}$$

Lemma (Divergence of $\sigma_{h,\text{dis}}^i$)

There holds

$$\nabla \cdot \sigma_{h,\text{dis}}^i = \Pi_{Q_h} f - r_h^i.$$

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Theorem (Total error upper bound)

On *each iteration* $i \geq 1$, there holds

$$\underbrace{\|\nabla(u - u_h^i)\|}_{\text{total error}} \leq \underbrace{\|\nabla u_h^i + \sigma_{h,\text{dis}}^i\|}_{\text{discretization est.}} + \underbrace{\|\sigma_{h,\text{alg}}^i\|}_{\text{algebraic est.}} + \underbrace{\left\{ \sum_{K \in \mathcal{T}_h} \frac{h_K^2}{\pi^2} \|f - \Pi_{Q_h} f\|_K^2 \right\}^{1/2}}_{\text{data osc. est.}}.$$

Proof.

$$\|\nabla(u - u_h^i)\| = \sup_{v \in H_0^1(\Omega), \|\nabla v\|=1} (\nabla(u - u_h^i), \nabla v)$$

$$\begin{aligned} (\nabla(u - u_h^i), \nabla v) &= (f, v) - (\nabla u_h^i, \nabla v) = (f - \overbrace{\nabla \cdot (\sigma_{h,\text{alg}}^i + \sigma_{h,\text{dis}}^i)}^{\text{algebraic error}}, v) \\ &\quad - (\sigma_{h,\text{alg}}^i + \sigma_{h,\text{dis}}^i + \nabla u_h^i, \nabla v) \end{aligned}$$

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Lower bound on the total error

Definition (Total residual lifting, \approx Babuška and Strouboulis (2001), Repin (2008))

Find $\rho_{h,\text{tot}}^{\mathbf{a},i} \in X_h^{\mathbf{a}} := \mathbb{P}_p(\mathcal{T}_h) \cap H^1(\omega_{\mathbf{a}})$ (together with mean value or value on $\partial\Omega$ zero) such that

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- local homogeneous Neumann FE problems

Theorem (Lower bound on the total error)

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$$\underbrace{\|\nabla(u - u_h^i)\|}_{\text{total error}} \geq \frac{\sum_{\mathbf{a} \in \mathcal{V}_h} \|\nabla \rho_{h,\text{tot}}^{\mathbf{a},i}\|_{\omega_{\mathbf{a}}}^2}{\underbrace{\|\nabla \rho_{h,\text{tot}}^i\|}_{\text{lower total est.}}}$$

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Stopping criteria

Galerkin orthogonality

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Safe stopping criterion ($\gamma_{\text{alg}} \approx 0.1$)

$$\text{algebraic error} \leq \gamma_{\text{alg}} \text{ discretization error}$$

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Numerical illustration

Peak $\Omega = (0, 1) \times (0, 1),$
 $u(x, y) = x(x - 1)y(y - 1)e^{-100(x-0.5)^2 - 100(y-117/1000)^2}$

L-shape $\Omega = (-1, 1) \times (-1, 1) \setminus [0, 1] \times [-1, 0],$
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- conforming finite elements, $p = 1, \dots, 4$
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- 4 uniform refinements

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Peak problem, multigrid

p	iter	alg. error	eff. UB	eff. LB	tot. error	eff. UB	eff. LB	disc. error	eff. UB	eff. LB
1 (2.55×10^3)	1	8.1×10^{-3}	1.14	1.10^{-1}	1.0×10^{-2}	1.63	1.19^{-1}	6.1×10^{-3}	2.42	—
	2	4.3×10^{-4}	1.13	1.12^{-1}	6.1×10^{-3}	1.13	1.05^{-1}		1.13	1.06^{-1}
2 (1.03×10^4)	1	8.8×10^{-3}	1.17	1.08^{-1}	8.8×10^{-3}	1.72	1.18^{-1}	3.9×10^{-4}	3.28×10^1	—
	2	6.1×10^{-4}	1.19	1.03^{-1}	7.2×10^{-4}	1.75	1.12^{-1}		2.89	—
	3	2.0×10^{-5}	1.19	1.03^{-1}	3.9×10^{-4}	1.08	1.04^{-1}		1.08	1.04^{-1}
3 (2.34×10^4)	1	4.9×10^{-3}	1.14	1.06^{-1}	4.9×10^{-3}	1.59	1.26^{-1}	1.9×10^{-5}	3.33×10^2	—
	3	2.7×10^{-5}	1.17	1.04^{-1}	3.3×10^{-5}	1.69	1.17^{-1}		2.60	—
	5	1.6×10^{-7}	1.15	1.04^{-1}	1.9×10^{-5}	1.02	1.09^{-1}		1.02	1.09^{-1}
4 (4.17×10^4)	1	5.8×10^{-3}	1.22	1.05^{-1}	5.8×10^{-3}	1.83	1.17^{-1}	8.1×10^{-7}	1.12×10^4	—
	3	1.0×10^{-4}	1.16	1.03^{-1}	1.0×10^{-4}	1.71	1.08^{-1}		1.76×10^2	—
	5	2.4×10^{-6}	1.14	1.03^{-1}	2.5×10^{-6}	1.62	1.10^{-1}		4.12	—
	7	6.7×10^{-8}	1.13	1.03^{-1}	8.2×10^{-7}	1.10	1.16^{-1}		1.10	1.16^{-1}
5 (6.52×10^4)	1	4.8×10^{-3}	1.19	1.04^{-1}	4.8×10^{-3}	1.74	1.19^{-1}	3.1×10^{-8}	2.21×10^5	—
	3	2.1×10^{-4}	1.14	1.03^{-1}	2.1×10^{-4}	1.63	1.09^{-1}		8.78×10^3	—
	5	1.5×10^{-5}	1.11	1.02^{-1}	1.5×10^{-5}	1.55	1.07^{-1}		5.57×10^2	—
	7	1.4×10^{-6}	1.12	1.02^{-1}	1.4×10^{-6}	1.57	1.05^{-1}		5.34×10^1	—
	9	1.4×10^{-7}	1.14	1.01^{-1}	1.4×10^{-7}	1.65	1.06^{-1}		6.06	—
	11	1.3×10^{-8}	1.16	1.01^{-1}	3.4×10^{-8}	1.41	1.38^{-1}		1.47	1.62^{-1}
	13	1.2×10^{-9}	1.16	1.01^{-1}	3.1×10^{-8}	1.05	1.21^{-1}		1.05	1.21^{-1}

Peak problem, multigrid

p	iter	alg. error	eff. UB	eff. LB	tot. error	eff. UB	eff. LB	disc. error	eff. UB	eff. LB
1 (2.55×10^3)	1	8.1×10^{-3}	1.14	1.10^{-1}	1.0×10^{-2}	1.63	1.19^{-1}	6.1×10^{-3}	2.42	—
	2	4.3×10^{-4}	1.13	1.12^{-1}	6.1×10^{-3}	1.13	1.05^{-1}		1.13	1.06^{-1}
2 (1.03×10^4)	1	8.8×10^{-3}	1.17	1.08^{-1}	8.8×10^{-3}	1.72	1.18^{-1}	3.9×10^{-4}	3.28×10^1	—
	2	6.1×10^{-4}	1.19	1.03^{-1}	7.2×10^{-4}	1.75	1.12^{-1}		2.89	—
	3	2.0×10^{-5}	1.19	1.03^{-1}	3.9×10^{-4}	1.08	1.04^{-1}		1.08	1.04^{-1}
3 (2.34×10^4)	1	4.9×10^{-3}	1.14	1.06^{-1}	4.9×10^{-3}	1.59	1.26^{-1}	1.9×10^{-5}	3.33×10^2	—
	3	2.7×10^{-5}	1.17	1.04^{-1}	3.3×10^{-5}	1.69	1.17^{-1}		2.60	—
	5	1.6×10^{-7}	1.15	1.04^{-1}	1.9×10^{-5}	1.02	1.09^{-1}		1.02	1.09^{-1}
4 (4.17×10^4)	1	5.8×10^{-3}	1.22	1.05^{-1}	5.8×10^{-3}	1.83	1.17^{-1}	8.1×10^{-7}	1.12×10^4	—
	3	1.0×10^{-4}	1.16	1.03^{-1}	1.0×10^{-4}	1.71	1.08^{-1}		1.76×10^2	—
	5	2.4×10^{-6}	1.14	1.03^{-1}	2.5×10^{-6}	1.62	1.10^{-1}		4.12	—
	7	6.7×10^{-8}	1.13	1.03^{-1}	8.2×10^{-7}	1.10	1.16^{-1}		1.10	1.16^{-1}
5 (6.52×10^4)	1	4.8×10^{-3}	1.19	1.04^{-1}	4.8×10^{-3}	1.74	1.19^{-1}	3.1×10^{-8}	2.21×10^5	—
	3	2.1×10^{-4}	1.14	1.03^{-1}	2.1×10^{-4}	1.63	1.09^{-1}		8.78×10^3	—
	5	1.5×10^{-5}	1.11	1.02^{-1}	1.5×10^{-5}	1.55	1.07^{-1}		5.57×10^2	—
	7	1.4×10^{-6}	1.12	1.02^{-1}	1.4×10^{-6}	1.57	1.05^{-1}		5.34×10^1	—
	9	1.4×10^{-7}	1.14	1.01^{-1}	1.4×10^{-7}	1.65	1.06^{-1}		6.06	—
	11	1.3×10^{-8}	1.16	1.01^{-1}	3.4×10^{-8}	1.41	1.38^{-1}		1.47	1.62^{-1}
	13	1.2×10^{-9}	1.16	1.01^{-1}	3.1×10^{-8}	1.05	1.21^{-1}		1.05	1.21^{-1}

Peak problem, multigrid

p	iter	alg. error	eff. UB	eff. LB	tot. error	eff. UB	eff. LB	disc. error	eff. UB	eff. LB
1 (2.55×10^3)	1	8.1×10^{-3}	1.14	1.10^{-1}	1.0×10^{-2}	1.63	1.19^{-1}	6.1×10^{-3}	2.42	—
	2	4.3×10^{-4}	1.13	1.12^{-1}	6.1×10^{-3}	1.13	1.05^{-1}		1.13	1.06^{-1}
2 (1.03×10^4)	1	8.8×10^{-3}	1.17	1.08^{-1}	8.8×10^{-3}	1.72	1.18^{-1}	3.9×10^{-4}	3.28×10^1	—
	2	6.1×10^{-4}	1.19	1.03^{-1}	7.2×10^{-4}	1.75	1.12^{-1}		2.89	—
	3	2.0×10^{-5}	1.19	1.03^{-1}	3.9×10^{-4}	1.08	1.04^{-1}		1.08	1.04^{-1}
3 (2.34×10^4)	1	4.9×10^{-3}	1.14	1.06^{-1}	4.9×10^{-3}	1.59	1.26^{-1}	1.9×10^{-5}	3.33×10^2	—
	3	2.7×10^{-5}	1.17	1.04^{-1}	3.3×10^{-5}	1.69	1.17^{-1}		2.60	—
	5	1.6×10^{-7}	1.15	1.04^{-1}	1.9×10^{-5}	1.02	1.09^{-1}		1.02	1.09^{-1}
4 (4.17×10^4)	1	5.8×10^{-3}	1.22	1.05^{-1}	5.8×10^{-3}	1.83	1.17^{-1}	8.1×10^{-7}	1.12×10^4	—
	3	1.0×10^{-4}	1.16	1.03^{-1}	1.0×10^{-4}	1.71	1.08^{-1}		1.76×10^2	—
	5	2.4×10^{-6}	1.14	1.03^{-1}	2.5×10^{-6}	1.62	1.10^{-1}		4.12	—
	7	6.7×10^{-8}	1.13	1.03^{-1}	8.2×10^{-7}	1.10	1.16^{-1}		1.10	1.16^{-1}
5 (6.52×10^4)	1	4.8×10^{-3}	1.19	1.04^{-1}	4.8×10^{-3}	1.74	1.19^{-1}	3.1×10^{-8}	2.21×10^5	—
	3	2.1×10^{-4}	1.14	1.03^{-1}	2.1×10^{-4}	1.63	1.09^{-1}		8.78×10^3	—
	5	1.5×10^{-5}	1.11	1.02^{-1}	1.5×10^{-5}	1.55	1.07^{-1}		5.57×10^2	—
	7	1.4×10^{-6}	1.12	1.02^{-1}	1.4×10^{-6}	1.57	1.05^{-1}		5.34×10^1	—
	9	1.4×10^{-7}	1.14	1.01^{-1}	1.4×10^{-7}	1.65	1.06^{-1}		6.06	—
	11	1.3×10^{-8}	1.16	1.01^{-1}	3.4×10^{-8}	1.41	1.38^{-1}		1.47	1.62^{-1}
	13	1.2×10^{-9}	1.16	1.01^{-1}	3.1×10^{-8}	1.05	1.21^{-1}		1.05	1.21^{-1}

Peak problem, multigrid

ρ	iter	alg. error	eff. UB	eff. LB	tot. error	eff. UB	eff. LB	disc. error	eff. UB	eff. LB
1 (2.55×10^3)	1	8.1×10^{-3}	1.14	1.10^{-1}	1.0×10^{-2}	1.63	1.19^{-1}	6.1×10^{-3}	2.42	—
	2	4.3×10^{-4}	1.13	1.12^{-1}	6.1×10^{-3}	1.13	1.05^{-1}		1.13	1.06^{-1}
2 (1.03×10^4)	1	8.8×10^{-3}	1.17	1.08^{-1}	8.8×10^{-3}	1.72	1.18^{-1}	3.9×10^{-4}	3.28×10^1	—
	2	6.1×10^{-4}	1.19	1.03^{-1}	7.2×10^{-4}	1.75	1.12^{-1}		2.89	—
	3	2.0×10^{-5}	1.19	1.03^{-1}	3.9×10^{-4}	1.08	1.04^{-1}		1.08	1.04^{-1}
3 (2.34×10^4)	1	4.9×10^{-3}	1.14	1.06^{-1}	4.9×10^{-3}	1.59	1.26^{-1}	1.9×10^{-5}	3.33×10^2	—
	3	2.7×10^{-5}	1.17	1.04^{-1}	3.3×10^{-5}	1.69	1.17^{-1}		2.60	—
	5	1.6×10^{-7}	1.15	1.04^{-1}	1.9×10^{-5}	1.02	1.09^{-1}		1.02	1.09^{-1}
4 (4.17×10^4)	1	5.8×10^{-3}	1.22	1.05^{-1}	5.8×10^{-3}	1.83	1.17^{-1}	8.1×10^{-7}	1.12×10^4	—
	3	1.0×10^{-4}	1.16	1.03^{-1}	1.0×10^{-4}	1.71	1.08^{-1}		1.76×10^2	—
	5	2.4×10^{-6}	1.14	1.03^{-1}	2.5×10^{-6}	1.62	1.10^{-1}		4.12	—
	7	6.7×10^{-8}	1.13	1.03^{-1}	8.2×10^{-7}	1.10	1.16^{-1}		1.10	1.16^{-1}
5 (6.52×10^4)	1	4.8×10^{-3}	1.19	1.04^{-1}	4.8×10^{-3}	1.74	1.19^{-1}	3.1×10^{-8}	2.21×10^5	—
	3	2.1×10^{-4}	1.14	1.03^{-1}	2.1×10^{-4}	1.63	1.09^{-1}		8.78×10^3	—
	5	1.5×10^{-5}	1.11	1.02^{-1}	1.5×10^{-5}	1.55	1.07^{-1}		5.57×10^2	—
	7	1.4×10^{-6}	1.12	1.02^{-1}	1.4×10^{-6}	1.57	1.05^{-1}		5.34×10^1	—
	9	1.4×10^{-7}	1.14	1.01^{-1}	1.4×10^{-7}	1.65	1.06^{-1}		6.06	—
	11	1.3×10^{-8}	1.16	1.01^{-1}	3.4×10^{-8}	1.41	1.38^{-1}		1.47	1.62^{-1}
	13	1.2×10^{-9}	1.16	1.01^{-1}	3.1×10^{-8}	1.05	1.21^{-1}		1.05	1.21^{-1}

L-shape problem, PCG

p	iter	alg. error	eff. UB	eff. LB	tot. error	eff. UB	eff. LB	disc. error	eff. UB	eff. LB
1 (7.97×10^3)	2	2.9×10^{-1}	1.25	4.08^{-1}	2.9×10^{-1}	1.38	6.15^{-1}	3.6×10^{-2}	1.11×10^1	—
	4	1.2×10^{-3}	1.24	4.17^{-1}	3.6×10^{-2}	1.24	1.12^{-1}		1.24	1.12^{-1}
2 (3.22×10^4)	3	2.1×10^{-1}	1.14	3.62^{-1}	2.1×10^{-1}	1.26	6.03^{-1}	1.4×10^{-2}	1.76×10^1	—
	6	2.5×10^{-3}	1.18	3.17^{-1}	1.5×10^{-2}	1.47	1.32^{-1}		1.49	1.35^{-1}
	9	9.2×10^{-6}	1.17	3.53^{-1}	1.4×10^{-2}	1.29	1.30^{-1}		1.29	1.30^{-1}
3 (7.27×10^4)	4	1.3	1.06	4.53^{-1}	1.3	1.10	$1.08 \times 10^{1-1}$	8.6×10^{-3}	1.58×10^2	—
	8	9.9×10^{-2}	1.10	3.55^{-1}	10.0×10^{-2}	1.24	6.02^{-1}		1.41×10^1	—
	12	1.2×10^{-2}	1.10	3.58^{-1}	1.5×10^{-2}	1.71	2.67^{-1}		2.99	—
	16	8.2×10^{-4}	1.10	3.55^{-1}	8.6×10^{-3}	1.51	1.42^{-1}		1.52	1.43^{-1}
4 (1.29×10^5)	5	1.7×10^{-1}	1.24	2.34^{-1}	1.7×10^{-1}	1.42	3.35^{-1}	6.2×10^{-3}	3.66×10^1	—
	10	2.4×10^{-3}	1.22	2.79^{-1}	6.6×10^{-3}	1.78	1.83^{-1}		1.90	2.93^{-1}
	15	2.3×10^{-5}	1.27	2.33^{-1}	6.2×10^{-3}	1.44	1.62^{-1}		1.44	1.62^{-1}
5 (2.02×10^5)	6	1.1	1.09	4.14^{-1}	1.1	1.16	7.42^{-1}	4.7×10^{-3}	2.71×10^2	—
	12	8.5×10^{-2}	1.11	3.75^{-1}	8.5×10^{-2}	1.23	5.77^{-1}		2.19×10^1	—
	18	7.5×10^{-3}	1.15	3.12^{-1}	8.9×10^{-3}	1.76	3.43^{-1}		3.31	—
	24	3.9×10^{-4}	1.15	3.17^{-1}	4.7×10^{-3}	1.56	1.80^{-1}		1.57	1.82^{-1}

L-shape problem, PCG

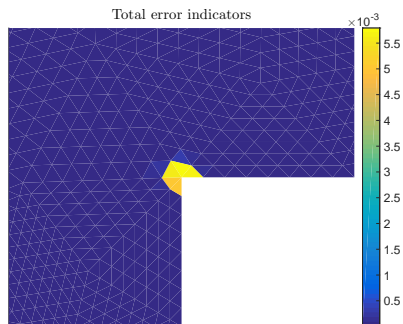
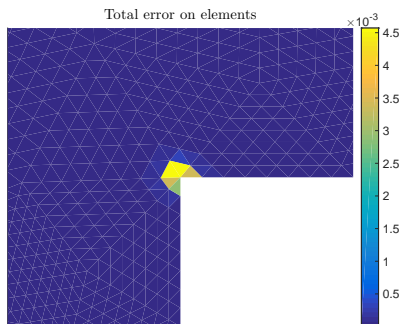
p	iter	alg. error	eff. UB	eff. LB	tot. error	eff. UB	eff. LB	disc. error	eff. UB	eff. LB
1 (7.97×10^3)	2	2.9×10^{-1}	1.25	4.08^{-1}	2.9×10^{-1}	1.38	6.15^{-1}	3.6×10^{-2}	1.11×10^1	—
	4	1.2×10^{-3}	1.24	4.17^{-1}	3.6×10^{-2}	1.24	1.12^{-1}		1.24	1.12^{-1}
2 (3.22×10^4)	3	2.1×10^{-1}	1.14	3.62^{-1}	2.1×10^{-1}	1.26	6.03^{-1}	1.4×10^{-2}	1.76×10^1	—
	6	2.5×10^{-3}	1.18	3.17^{-1}	1.5×10^{-2}	1.47	1.32^{-1}		1.49	1.35^{-1}
	9	9.2×10^{-6}	1.17	3.53^{-1}	1.4×10^{-2}	1.29	1.30^{-1}		1.29	1.30^{-1}
3 (7.27×10^4)	4	1.3	1.06	4.53^{-1}	1.3	1.10	$1.08 \times 10^{1-1}$	8.6×10^{-3}	1.58×10^2	—
	8	9.9×10^{-2}	1.10	3.55^{-1}	10.0×10^{-2}	1.24	6.02^{-1}		1.41×10^1	—
	12	1.2×10^{-2}	1.10	3.58^{-1}	1.5×10^{-2}	1.71	2.67^{-1}		2.99	—
	16	8.2×10^{-4}	1.10	3.55^{-1}	8.6×10^{-3}	1.51	1.42^{-1}		1.52	1.43^{-1}
4 (1.29×10^5)	5	1.7×10^{-1}	1.24	2.34^{-1}	1.7×10^{-1}	1.42	3.35^{-1}	6.2×10^{-3}	3.66×10^1	—
	10	2.4×10^{-3}	1.22	2.79^{-1}	6.6×10^{-3}	1.78	1.83^{-1}		1.90	2.93^{-1}
	15	2.3×10^{-5}	1.27	2.33^{-1}	6.2×10^{-3}	1.44	1.62^{-1}		1.44	1.62^{-1}
5 (2.02×10^5)	6	1.1	1.09	4.14^{-1}	1.1	1.16	7.42^{-1}	4.7×10^{-3}	2.71×10^2	—
	12	8.5×10^{-2}	1.11	3.75^{-1}	8.5×10^{-2}	1.23	5.77^{-1}		2.19×10^1	—
	18	7.5×10^{-3}	1.15	3.12^{-1}	8.9×10^{-3}	1.76	3.43^{-1}		3.31	—
	24	3.9×10^{-4}	1.15	3.17^{-1}	4.7×10^{-3}	1.56	1.80^{-1}		1.57	1.82^{-1}

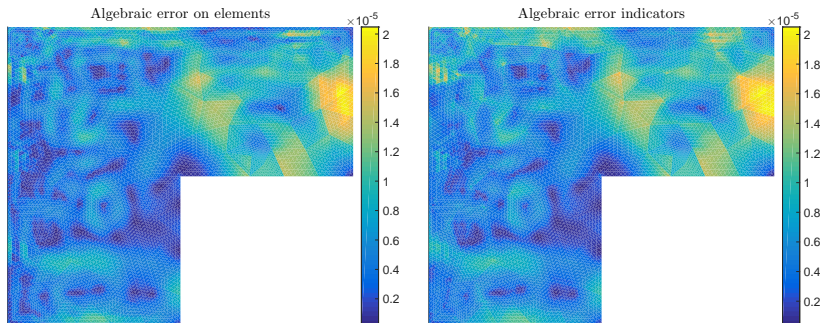
L-shape problem, PCG

p	iter	alg. error	eff. UB	eff. LB	tot. error	eff. UB	eff. LB	disc. error	eff. UB	eff. LB
1 (7.97×10^3)	2	2.9×10^{-1}	1.25	4.08^{-1}	2.9×10^{-1}	1.38	6.15^{-1}	3.6×10^{-2}	1.11×10^1	—
	4	1.2×10^{-3}	1.24	4.17^{-1}	3.6×10^{-2}	1.24	1.12^{-1}		1.24	1.12^{-1}
2 (3.22×10^4)	3	2.1×10^{-1}	1.14	3.62^{-1}	2.1×10^{-1}	1.26	6.03^{-1}	1.4×10^{-2}	1.76×10^1	—
	6	2.5×10^{-3}	1.18	3.17^{-1}	1.5×10^{-2}	1.47	1.32^{-1}		1.49	1.35^{-1}
	9	9.2×10^{-6}	1.17	3.53^{-1}	1.4×10^{-2}	1.29	1.30^{-1}		1.29	1.30^{-1}
3 (7.27×10^4)	4	1.3	1.06	4.53^{-1}	1.3	1.10	$1.08 \times 10^{1-1}$	8.6×10^{-3}	1.58×10^2	—
	8	9.9×10^{-2}	1.10	3.55^{-1}	10.0×10^{-2}	1.24	6.02^{-1}		1.41×10^1	—
	12	1.2×10^{-2}	1.10	3.58^{-1}	1.5×10^{-2}	1.71	2.67^{-1}		2.99	—
	16	8.2×10^{-4}	1.10	3.55^{-1}	8.6×10^{-3}	1.51	1.42^{-1}		1.52	1.43^{-1}
4 (1.29×10^5)	5	1.7×10^{-1}	1.24	2.34^{-1}	1.7×10^{-1}	1.42	3.35^{-1}	6.2×10^{-3}	3.66×10^1	—
	10	2.4×10^{-3}	1.22	2.79^{-1}	6.6×10^{-3}	1.78	1.83^{-1}		1.90	2.93^{-1}
	15	2.3×10^{-5}	1.27	2.33^{-1}	6.2×10^{-3}	1.44	1.62^{-1}		1.44	1.62^{-1}
5 (2.02×10^5)	6	1.1	1.09	4.14^{-1}	1.1	1.16	7.42^{-1}	4.7×10^{-3}	2.71×10^2	—
	12	8.5×10^{-2}	1.11	3.75^{-1}	8.5×10^{-2}	1.23	5.77^{-1}		2.19×10^1	—
	18	7.5×10^{-3}	1.15	3.12^{-1}	8.9×10^{-3}	1.76	3.43^{-1}		3.31	—
	24	3.9×10^{-4}	1.15	3.17^{-1}	4.7×10^{-3}	1.56	1.80^{-1}		1.57	1.82^{-1}

L-shape problem, PCG

p	iter	alg. error	eff. UB	eff. LB	tot. error	eff. UB	eff. LB	disc. error	eff. UB	eff. LB
1 (7.97×10^3)	2	2.9×10^{-1}	1.25	4.08^{-1}	2.9×10^{-1}	1.38	6.15^{-1}	3.6×10^{-2}	1.11×10^1	—
	4	1.2×10^{-3}	1.24	4.17^{-1}	3.6×10^{-2}	1.24	1.12^{-1}		1.24	1.12^{-1}
2 (3.22×10^4)	3	2.1×10^{-1}	1.14	3.62^{-1}	2.1×10^{-1}	1.26	6.03^{-1}	1.4×10^{-2}	1.76×10^1	—
	6	2.5×10^{-3}	1.18	3.17^{-1}	1.5×10^{-2}	1.47	1.32^{-1}		1.49	1.35^{-1}
	9	9.2×10^{-6}	1.17	3.53^{-1}	1.4×10^{-2}	1.29	1.30^{-1}		1.29	1.30^{-1}
3 (7.27×10^4)	4	1.3	1.06	4.53^{-1}	1.3	1.10	$1.08 \times 10^{1-1}$	8.6×10^{-3}	1.58×10^2	—
	8	9.9×10^{-2}	1.10	3.55^{-1}	10.0×10^{-2}	1.24	6.02^{-1}		1.41×10^1	—
	12	1.2×10^{-2}	1.10	3.58^{-1}	1.5×10^{-2}	1.71	2.67^{-1}		2.99	—
	16	8.2×10^{-4}	1.10	3.55^{-1}	8.6×10^{-3}	1.51	1.42^{-1}		1.52	1.43^{-1}
4 (1.29×10^5)	5	1.7×10^{-1}	1.24	2.34^{-1}	1.7×10^{-1}	1.42	3.35^{-1}	6.2×10^{-3}	3.66×10^1	—
	10	2.4×10^{-3}	1.22	2.79^{-1}	6.6×10^{-3}	1.78	1.83^{-1}		1.90	2.93^{-1}
	15	2.3×10^{-5}	1.27	2.33^{-1}	6.2×10^{-3}	1.44	1.62^{-1}		1.44	1.62^{-1}
5 (2.02×10^5)	6	1.1	1.09	4.14^{-1}	1.1	1.16	7.42^{-1}	4.7×10^{-3}	2.71×10^2	—
	12	8.5×10^{-2}	1.11	3.75^{-1}	8.5×10^{-2}	1.23	5.77^{-1}		2.19×10^1	—
	18	7.5×10^{-3}	1.15	3.12^{-1}	8.9×10^{-3}	1.76	3.43^{-1}		3.31	—
	24	3.9×10^{-4}	1.15	3.17^{-1}	4.7×10^{-3}	1.56	1.80^{-1}		1.57	1.82^{-1}

L-shape problem, $p = 3$, total error, 16th PCG iteration

L-shape problem, $p = 3$, alg. error, 16th PCG iteration

Outline

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 - Polynomial-degree-robust local efficiency
 - Applications
 - Numerical illustration
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 - Upper and lower bounds on the algebraic error
 - Bounds on the total error
 - Stopping criteria
 - Numerical illustration
- 4 Conclusions and outlook

Conclusions and outlook

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- **robustness** (polynomial degree)
- **unified framework** for all classical numerical schemes

Ongoing work

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Thank you for your attention!