

# Dense QR factorization and its error analysis

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## Direct methods of factorization

- QR factorization

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- Block QR factorization

## Direct methods of factorization

- QR factorization

- Block QR factorization

# The QR factorization

Given a matrix  $A \in \mathbb{R}^{m \times n}$ ,  $m \geq n$ , its QR factorization is

$$A = QR = (Q_1 \quad Q_2) \begin{pmatrix} R_1 \\ 0 \end{pmatrix} = Q_1 R_1$$

where  $Q \in \mathbb{R}^{m \times m}$  is orthogonal and  $R \in \mathbb{R}^{m \times n}$  is upper triangular.

If  $A$  has full rank, the factorization  $Q_1 R_1$  is essentially unique (modulo signs of diagonal elements of  $R$ ).

- $A^T A = R_1^T R_1$  is a Cholesky factorization and  $A = A R_1^{-1} R_1$  is a QR factorization.
- $A = Q_1 D \cdot D R_1$ ,  $D = \text{diag}(\pm 1)$  is a QR factorization.

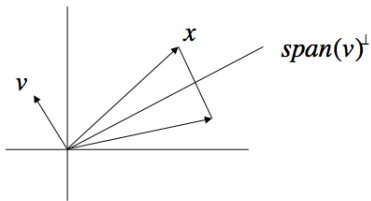
# Householder transformation

The Householder matrix

$$P = I - \frac{2}{v^T v} v v^T$$

has the following properties:

- is symmetric and orthogonal,  
 $P^2 = I$ ,
- is independent of the scaling of  $v$ ,
- it reflects  $x$  about the hyperplane  $\text{span}(v)^\perp$



$$Px = x - \frac{2v^T x}{v^T v} v = x - \alpha v$$

Presentation of Householder transformations and stability analysis from [N.J.Higham, 2002].

## Householder for the QR factorization

We look for a Householder matrix that allows to annihilate the elements of a vector  $x$ , except first one.

$$Px = y, \quad \|x\|_2 = \|y\|_2, \quad y = \sigma e_1, \quad \sigma = \pm \|x\|_2$$

With the choice of sign made to avoid cancellation when computing  $v_1 = x_1 - \sigma$ , we have

$$\begin{aligned}v &= x - y = x - \sigma e_1, \\ \sigma &= -\text{sign}(x_1) \|x\|_2, \quad v = x - \sigma e_1, \\ P &= I - \beta vv^T, \quad \beta = \frac{2}{v^T v}\end{aligned}$$

## Householder based QR factorization

$$A = \begin{pmatrix} x & x & x \\ x & x & x \\ x & x & x \end{pmatrix} = P_1 \begin{pmatrix} x & x & x \\ 0 & x & x \\ 0 & x & x \end{pmatrix} = P_1 \begin{pmatrix} 1 & & \\ & \tilde{P}_2 & \end{pmatrix} \begin{pmatrix} x & x & x \\ 0 & x & x \\ 0 & 0 & x \end{pmatrix} = R$$

So we have

$$\begin{aligned} Q^T A &= P_n P_{n-1} \dots P_1 A = R, \\ Q &= (I - \beta_1 v_1 v_1^T) \dots (I - \beta_{n-1} v_{n-1} v_{n-1}^T) (I - \beta_n v_n v_n^T) \end{aligned}$$

$$\#flops = 2n^2(m - n/3)$$

# Error analysis of Householder transformations

## Lemma (Lemma 19.1 in [N.J.Higham, 2002])

Consider the computation of  $P = I - \beta vv^T$ , where  $Px = \sigma e_1$ ,  $v \in \mathbb{R}^m$ , as

1:  $v = x$

2:  $s = \text{sign}(x_1)\|x\|_2$ ,  $\% \sigma = -s$

3:  $v_1 = v_1 + s$

4:  $\beta = 1/(sv_1)$

Then we have

$$\begin{aligned}\hat{v}(2:n) &= v(2:n) \\ \hat{\beta} &= \beta(1 + \tilde{\theta}_m), \quad \hat{v}_1 = v_1(1 + \tilde{\theta}_m), \quad \text{where } |\tilde{\theta}_m| \leq \tilde{\gamma}_m\end{aligned}$$

Proof based on the fact that  $fl(x^T x) = (1 + \theta_m)x^T x$ . The result can be re-written as

$$\hat{v} = v + \Delta v, \quad |\Delta v| \leq \tilde{\gamma}_m |v|$$

In the following results,  $v = \sqrt{\beta}v$ ,  $\beta = 1$ , and so  $\|v\|_2 = \sqrt{2}$ .



# Error analysis of Householder transformations

Lemma (Lemma 19.2 in [N.J.Higham, 2002])

Consider the computation  $y = \hat{P}b = (I - \hat{v}\hat{v}^T)b$ , where  $b, \hat{v} \in \mathbb{R}^m$ . Then

$$\hat{y} = (P + \Delta P)b, \quad \|\Delta P\|_F \leq \tilde{\gamma}_m. \quad (1)$$

Proof.

$$\begin{aligned} \hat{w} &= fl(\hat{v}(\hat{v}^T b)) = (\hat{v} + \Delta\hat{v})(\hat{v}^T(b + \Delta b)), \quad |\Delta\hat{v}| \leq u|\hat{v}| \text{ and } |\Delta b| \leq \gamma_m|b| \\ &= (v + \Delta v + \Delta\hat{v})(v + \Delta v)^T(b + \Delta b) \end{aligned}$$

Hence

$$\hat{w} = v(v^T b) + \Delta w, \quad \text{where } |\Delta w| \leq \tilde{\gamma}_m|v||v^T||b|$$



## Error analysis of Householder transformations

Continued proof of the previous lemma. We obtain

$$\hat{y} = fl(b - \hat{w}) = b - v(v^T b) - \Delta w + \Delta y_1, \quad |\Delta y_1| \leq u|b - \hat{w}|$$

Since

$$|-\Delta w + \Delta y_1| \leq u|b| + \tilde{\gamma}_m |v| |v^T| |b|$$

we obtain

$$\hat{y} = Pb + \Delta y, \quad \|\Delta y\|_2 \leq \tilde{\gamma}_m \|b\|_2$$

Finally, with  $\Delta P = \Delta y b^T / b^T b$ , we have

$$\hat{y} = (P + \Delta P)b, \quad \|\Delta P\|_F = \|\Delta y\|_2 / \|b\|_2 \leq \tilde{\gamma}_m$$

# Error analysis of a sequence of transformations

Lemma ([N.J.Higham, 2002])

Let  $Q = P_r P_{r-1} \dots P_1$  and let  $A_{r+1} = Q^T A$ ,  $A \in \mathbb{R}^{m \times n}$ . We have

$$\hat{A}_{r+1} = Q^T(A + \Delta A), \quad \|\Delta a_j\|_2 \leq r \tilde{\gamma}_m \|a_j\|_2, \quad j = 1 : n$$

Sketch of the proof: Let  $a_j$  be the  $j$ -th column of  $A$ .

$$\hat{a}_j^{(r+1)} = (P_r + \Delta P_r) \dots (P_1 + \Delta P_1) a_j, \quad \|\Delta P_k\|_F \leq \tilde{\gamma}_m, \quad k = 1 : r$$

We obtain

$$\begin{aligned} \hat{a}_j^{(r+1)} &= Q^T(a_j + \Delta a_j), \\ \|\Delta a_j\|_2 &\leq ((1 + \tilde{\gamma}_m)^r - 1) \|a_j\|_2 \leq \frac{r \tilde{\gamma}_m}{1 - r \tilde{\gamma}_m} \|a_j\|_2 = r \tilde{\gamma}'_m \|a_j\|_2 \end{aligned}$$

# Error analysis of the QR factorization

The following result follows

## Theorem ([N.J.Higham, 2002])

Let  $\hat{R} \in \mathbb{R}^{m \times n}$  be the computed factor of  $A \in \mathbb{R}^{m \times n}$  obtained by using Householder transformations. Then there is an orthogonal  $Q \in \mathbb{R}^{m \times m}$  such that

$$A + \Delta A = Q\hat{R}, \text{ where } \|\Delta a_j\|_2 \leq \tilde{\gamma}_{mn} \|a_j\|_2, \quad j = 1 : n$$

# Householder-QR factorization

**Require:**  $A \in \mathbb{R}^{m \times n}$

1: Let  $R \in \mathbb{R}^{n \times n}$  be initialized with zero matrix

2: **for**  $k = 1$  to  $n$  **do**

3:  $\triangleright$  Compute Householder matrix  $P_k = I - \beta_k v_k v_k^T$  s.t.

$$P_k A(k:m, k) = \pm \|A(k:m, k)\|_2 e_1. \text{ Store } v_k \text{ in } Y(k) \text{ and } \beta_k \text{ in } \mathcal{T}(k)$$

4:  $R(k, k) = -\text{sgn}(A(k, k)) \cdot \|A(k:m, k)\|_2$

5:  $\mathcal{T}(k) = \frac{R(k, k) - A(k, k)}{R(k, k)}$

6:  $Y(k+1:m, k) = \frac{1}{R(k, k) - A(k, k)} \cdot A(k+1:m, k)$

7:  $\triangleright$  Update trailing matrix

8:  $A(k:m, k+1:n) = (I - Y(k+1:m, k)\mathcal{T}(k)Y(k+1:m, k)^T) \cdot A(k:m, k+1:n)$

9:  $R(k, k+1:n) = A(k, k+1:n)$

10: **end for**

**Assert:**  $A = QR$ , where  $Q = P_1 \dots P_n = (I - \beta_1 v_1 v_1^T) \dots (I - \beta_n v_n v_n^T)$ , the Householder vectors  $v_k$  are stored in  $Y$  and  $\mathcal{T}$  is an array of size  $n$ .

# Computational complexity

## ■ Flops per iterations

- Dot product  $w = v_k^T A(k : m, k + 1 : n) : 2(m - k)(n - k)$
- Outer product  $v_k w : (m - k)(n - k)$
- Subtraction  $A(k : m, k + 1 : n) - \dots : (m - k)(n - k)$

## ■ Flops of Householder-QR

$$\begin{aligned}\sum_{k=1}^n 4(m - k)(n - k) &= 4 \sum_{k=1}^n (mn - k(m + n) + k^2) \\ &\approx 4mn^2 - 4(m + n)n^2/2 + 4n^3/3 = 2mn^2 - 2n^3/3\end{aligned}$$

## Algebra of block QR

Storage efficient representation for Q [Schreiber and Loan, 1989]

$$Q = Q_1 Q_2 \dots Q_k = (I - \beta_1 v_1 v_1^T) \dots (I - \beta_k v_k v_k^T) = I - YTY^T$$

Example for  $k = 2$

$$Y = (v_1 | v_2), \quad T = \begin{pmatrix} \beta_1 & -\beta_1 v_1^T v_2 \beta_2 \\ 0 & \beta_2 \end{pmatrix}$$

Example for combining two compact representations

$$Q = (I - Y_1 T_1 Y_1^T)(I - Y_2 T_2 Y_2^T)$$
$$T = \begin{pmatrix} T_1 & -T_1 Y_1^T Y_2 T_2 \\ 0 & T_2 \end{pmatrix}$$

# Block algorithm for computing the QR factorization

Partitioning of matrix  $A$  of size  $m \times n$

$$A = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}$$

where  $A_{11}$  is of size  $b \times b$ ,  $A_{21}$  is of size  $(m - b) \times b$ ,  $A_{12}$  is of size  $b \times (n - b)$  and  $A_{22}$  is of size  $(m - b) \times (n - b)$ .

## Block QR algebra

The first step of the block QR factorization algorithm computes:

$$Q_1^T A = \begin{pmatrix} R_{11} & R_{12} \\ & A^1 \end{pmatrix}$$

The algorithm continues recursively on the trailing matrix  $A^1$ .



# Algebra of block QR factorization

$$A = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} = Q_1 \begin{pmatrix} R_{11} & R_{12} \\ & A^1 \end{pmatrix}$$

## Block QR algebra

1. Compute the factorization

$$\begin{pmatrix} A_{11} \\ A_{12} \end{pmatrix} = Q_1 R_{11}$$

2. Compute the compact representation  $Q_1 = I - YTY^T$
3. Apply  $Q_1^T$  on the trailing matrix

$$(I - YTY^T) \begin{pmatrix} A_{12} \\ A_{22} \end{pmatrix} = \begin{pmatrix} A_{12} \\ A_{22} \end{pmatrix} - Y \left( T^T \left( Y^T \begin{pmatrix} A_{12} \\ A_{22} \end{pmatrix} \right) \right)$$

4. The algorithm continues recursively on the trailing matrix  $A^1$ .

# Parallel implementation of the QR factorization

QR factorization on a  $P = P_r \times P_c$  grid of processors

For  $ib = 1$  to  $n-1$  step  $b$

1. Compute panel factorization on  $P_r$  processors

$$\begin{pmatrix} A_{11} \\ A_{12} \end{pmatrix} = Q_1 R_{11} = (I - YTY^T)R_{11}$$

2. The  $P_r$  processors broadcast along the rows their parts of  $Y$  and  $T$
3. Apply  $Q_1^T$  on the trailing matrix:

- All processors compute their local part of

$$W_l = Y_l^T (A_{21l}; A_{22l})$$

- The processors owning block row  $ib$  compute the sum over  $W_l$ , that is

$$W = Y^T (A_{21}; A_{22})$$

and then compute  $W' = T^T W$

- The processors owning block row  $ib$  broadcast along the columns their part of  $W'$
4. All processors compute

$$(A_{21}^1; A_{22}^1) = (A_{21}; A_{22}) - (A_{21}; A_{22}) * W'$$

## Cost of parallel QR factorization

$$\begin{aligned} & \gamma \cdot \left( \frac{6mnb - 3n^2b}{2p_r} + \frac{n^2b}{2p_c} + \frac{2mn^2 - 2n^3/3}{p} \right) \\ + & \beta \cdot \left( nb \log p_r + \frac{2mn - n^2}{p_r} + \frac{n^2}{p_c} \right) \\ + & \alpha \cdot \left( 2n \log p_r + \frac{2n}{b} \log p_c \right). \end{aligned}$$

## Solving least squares problems

Given matrix  $A \in \mathbb{R}^{m \times n}$ ,  $\text{rank}(A) = n$ , vector  $b \in \mathbb{R}^{m \times 1}$ , the unique solution to  $\min_x \|Ax - b\|_2$  is

$$x = A^+ b, \quad A^+ = (A^T A)^{-1} A^T$$

Using the QR factorization of  $A$

$$A = QR = \begin{pmatrix} Q_1 & Q_2 \end{pmatrix} \begin{pmatrix} R_1 \\ 0 \end{pmatrix} \quad (2)$$

We obtain




$$\begin{aligned} \|r\|_2^2 &= \|b - Ax\|_2^2 = \|b - \begin{pmatrix} Q_1 & Q_2 \end{pmatrix} \begin{pmatrix} R_1 \\ 0 \end{pmatrix} x\|_2^2 \\ &= \left\| \begin{pmatrix} Q_1^T \\ Q_2^T \end{pmatrix} b - \begin{pmatrix} R_1 \\ 0 \end{pmatrix} x \right\|_2^2 = \left\| \begin{pmatrix} Q_1^T b - R_1 x \\ Q_2^T b \end{pmatrix} \right\|_2^2 \\ &= \|Q_1^T b - R_1 x\|_2^2 + \|Q_2^T b\|_2^2 \end{aligned}$$

Solve  $R_1 x = Q_1^T b$  to minimize  $\|r\|_2$ .

# Acknowledgement

- Stability analysis results presented from [N.J.Higham, 2002]
- Some of the examples taken from [Golub and Van Loan, 1996]

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