Drug resistance in cancer II: Perspectives in therapeutic control

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Nonlocal aspects in mathematical biology, Bedlewo, January 27, 2016









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A general framework to optimise cancer therapeutics: designing mathematical methods along 3 axes

- Modelling the behaviour of growing cell populations on which anticancer drugs act (the targeted cell populations): proliferating tumour and healthy cell populations, including representing functional (not necessarily molecular) targets for pharmacological control
- (When PK-PD models are available) Modelling the external control system, i.e., fate of drugs in the organism, at the level of functional targets (proliferation, death, differentiation) in cell populations by functional, rather than molecular, pharmacokinetics-pharmacodynamics (PK-PD)
- Optimising therapeutic controls: dynamically optimised control of theoretical drug delivery flows representing time-dependent objectives and constraints, making use of known or hypothesised differences between cancer and healthy cell populations

Choosing the constraint to be represented determines the model of proliferation used to optimise drug delivery, aiming to avoid the two main pitfalls of pharmacotherapy:

- Toxicity issues. Limiting toxic side effects to preserve healthy cell populations leads to representing proliferating cell populations by ordinary differential equations, or by age-structured models: physiologically structured partial differential equations
- Drug resistance issues. Limiting emergence of drug-resistant cell subpopulations in tumour tissues leads to using (evolutionary) phenotypic trait-structured proliferation: physiologically structured evolutionary integro-differential equations
- In fact, one should consider the two issues simultaneously, i.e., two similarly structured cell populations, healthy and cancer, with different characteristics w.r.t. to drug effects and to evolution towards resistance: phenotypic stability of healthy cell populations vs. plasticity of cancer cell populations

Modelling framework: structured population dynamics

- Description of evolution of a population in time t and in relevant trait x
- 'Structure variable' x: trait chosen as bearing the biological variability at stake
- Variable : n(x, t) population density of individuals bearing trait x at time t
- (1) Evolution in numbers of individuals constituting the population

$$t\mapsto
ho(t)=\int_0^1 n(x,t)\;dx \qquad ext{ (if, e.g., }x\in[0,1])$$

(2) Asymptotics of distribution of the trait in the population

$$x \mapsto \lim_{t \to +\infty} \frac{n(x,t)}{\rho(t)}$$

- Cancer cell populations: (1) tumour growth; (2) asymptotic distribution of trait
- Space is not necessarily a relevant structure variable when studying drug control



Drug effects on cell populations and their optimisation 1st IDE model, mutations, one cytotoxic drug: cancer cells

- \bullet x = level of expression of a drug resistance phenotype (to a given drug)
- $n_H(x,t)$, $n_C(x,t)$ densities of cell populations (H=healthy, C=tumour)

$$\frac{\partial}{\partial t} n_C(x,t) = \left[\underbrace{(1-\theta_C) r(x)}_{\text{grown}} - \underbrace{d(x)}_{\text{u(t)}} - \underbrace{u(t)\mu_C(x)}_{\text{u(t)}} \right] n_C(x,t)$$

 $+\theta_{C} \overbrace{\int r(y) M_{\sigma_{C}}(y,x) n_{C}(y,t) dy}^{\text{birth with mutation}}$

- r(x)= basic reproduction rate, d(x)= basic death rate; we assume $r(0)>d(0)>0, \qquad r'(\cdot)<0, \qquad r(+\infty)=0, \qquad d'(\cdot)>0,$
- $0 \le \theta_{H,C} < 1 \; (\theta_C > \theta_H)$ is the proportion of divisions with mutations,
- $\mu_{[H,C]}(x)$ (with $\mu_C'(\cdot) < 0$) represents the phenotype-dependent response to cytotoxic drug, with concentration u(t), designed to target cancer cells.
- Note: assumptions $r(\cdot)>0$, $\mu_C(\cdot)>0$, $\mu_C'(\cdot)<0$ and $r'(\cdot)<0$ (cost of resistance: the higher is x, the lower is proliferation) represent an *evolutionary double bind on resistant cancer cell populations, i.e., an evolutionary trade-off between growing (thus getting exposed) and keeping still (thus surviving)*

1st IDE model, mutations, one cytotoxic drug: healthy cells

$$\frac{\partial}{\partial t} n_H(x,t) = \left[\begin{array}{c} \underbrace{\frac{1-\theta_H}{\left(1+\rho(t)\right)^\beta} r(x)} \\ + \underbrace{\frac{\theta_H}{\left(1+\rho(t)\right)^\beta}} \end{array} \right] n_H(x,t)$$
 birth with mutation
$$+ \frac{\theta_H}{\left(1+\rho(t)\right)^\beta} \int r(y) M_{\sigma_H}(y,x) n_H(y,t) dy,$$

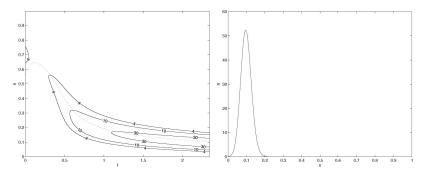
where the total population is defined as

$$\rho(t) = \rho_H(t) + \rho_C(t); \rho_H(t) = \int_{x=0}^{\infty} n_H(x, t) dx; \rho_C(t) = \int_{x=0}^{\infty} n_C(x, t) dx.$$

- ullet $\beta>0$ to impose healthy tissue homeostasis,
- u(t) denotes the instantaneous dose (concentration) of chemotherapy. We assume in this model that its effect is cytotoxic, i.e., on the death term only.

IDE model, mutations, one cytotoxic drug: illustrations (1)

[Sensitive cell population case: illustration of Gause's exclusion principle] Theorem: Monomorphic evolution towards drug sensitivity, illustrated here with $\theta_H=0$, (no mutations) and $\mu_H=0$ (no drug-induced resistance)



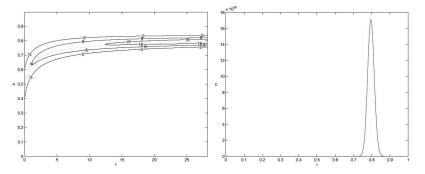
Left panel: starting from a medium phenotype x=0.5, level sets of a drug-sensitive population in the (t,x) plane. Right panel: asymptotic distribution of this drug-sensitive population according to the drug resistance phenotype x.

(Lorz et al., M2AN 2013)



IDE model, mutations, cytotoxic drug: illustrations (2)

[Resistant cell population case: Gause's exclusion principle again] Theorem: Monomorphic evolution towards drug-induced drug resistance, here with $\theta_C=0,\ \mu_C(\cdot)>0, r'(\cdot)<0, \mu'_C(\cdot)<0$ (costly drug-induced resistance)



Left panel: starting from a medium phenotype x=0.5, level sets of a drug-resistant population in the (t,x) plane. Right panel: asymptotic distribution of this drug-resistant population according to the drug resistance phenotype x.

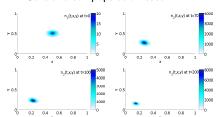
(Lorz et al., M2AN 2013)

IDE model, no mutations: phenotype-structured non-local Lotka-Volterra model with 2 drugs, cytotoxic $u_1(t)$, cytostatic $u_2(t)$, bidimensional resistance phenotype (x, y)

$$\frac{\partial}{\partial t} n_C(x, y, t) = \left[\frac{r_C(x, y)}{1 + k u_2(t)} - d_C(x, y) I_C(t) - u_1(t) \mu_C(x, y) \right] n_C(x, y, t)$$

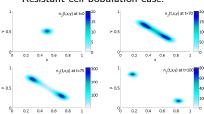
Environment: $I_C(t) = \alpha \int_0^1 \int_0^1 n_C(x, y, t) dx dy + \beta \int_0^1 \int_0^1 n_H(x, y, t) dx dy$

Sensitive cell population case:



Convergence toward total sensitivity

Resistant cell population case:



Convergence toward 2 resistant phenotypes

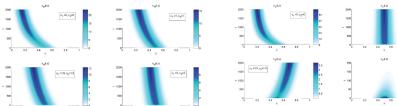
Same phenotype-structured non-local Lotka-Volterra model with 2 drugs and one (scalar) resistance phenotype x

$$\frac{\partial}{\partial t} n_H(x,t) = \left[\frac{r_H(x)}{1 + k_H u_2(t)} - d_H(x) I_H(t) - u_1(t) \mu_H(x) \right] n_H(x,t)$$

$$\frac{\partial}{\partial t} n_C(x,t) = \left[\frac{r_C(x)}{1 + k_C u_2(t)} - d_C(x) I_C(t) - u_1(t) \mu_C(x) \right] n_C(x,t)$$

Environment: $I_H(t) = a_{HH}.\rho_H(t) + a_{HC}.\rho_C(t), I_C(t) = a_{CH}.\rho_H(t) + a_{CC}.\rho_C(t),$ with $\rho_H(t) = \int_0^1 n_H(x,t) dx, \rho_C(t) = \int_0^1 n_C(x,t) dx, \frac{u_1}{u}$ cytotoxic, $\frac{u_2}{u}$ cytostatic drugs.

Simultaneous combinations of the 2 drugs, with increasing equal constant doses



Healthy cells: preserved

Cancer cells: eventually extinct

'Pedestrian's optimisation' (Lorz et al. M2AN 2013)

"What does not kill me strengthens me"

 Note that in the representation of the drug targets on cancer cell populations in the integro-differential equation, with the numerical values chosen for the target functions μ_C and r_C standing for the sensitivities to drugs u₁ and u₂, respectively

$$\left[\frac{r_{\mathcal{C}}(x)}{1+k_{\mathcal{C}}u_{2}(t)}-d_{\mathcal{C}}(x)I_{\mathcal{C}}(t)-u_{1}(t)\mu_{\mathcal{C}}(x)\right]n_{\mathcal{C}}(x,t),$$

the cytostatic drug ν_2 only slows down proliferation (softly slowing down velocity in the cell division cycle), but does not arrest it, at least at low doses...

- ... whereas the cytotoxic drug u₁ kills the cells by directly (additively) impinging
 on the death term, hence it is actually a direct life threat to the cell population,
 that defends itself by making its resistance phenotype x increase.
- This resistance-inducing killing effect should be avoided as long as possible. In summary: limit proliferation but do not try too hard to kill cells, lest the cell population should become resistant, but give cytotoxics only at high doses during a short interval of time (MTD), thus avoiding to trigger resistance.
- An alternative to such use of MTD (maximum tolerated dose) towards the end
 of the chemotherapy course is metronomics, that also prevents developing
 resistance by giving low doses of cytotoxics... expecting that the population,
 thwarted in its proliferation, will be kept in check by the immune system.
 However this has not been represented in an optimal control perspective thus far.

Optimal control algorithms to improve drug delivery in cancer cell populations (Emmanuel Trélat, LJLL, UPMC)

Same phenotype-structured non-local Lotka-Volterra model, but instead of a 'pedestrian's optimisation' (i.e., merely using grids), solving an optimal control problem: determining control functions u_1 and u_2 in $L^{\infty}(0,T)$, satisfying the constraints

$$0 \le u_1(t) \le u_1^{\max}, \qquad 0 \le u_2(t) \le u_2^{\max},$$
 (1)

and minimising the cost functional

$$C_T(u_1, u_2) = \int_0^1 n_C(x, T) dx + \gamma_1 \int_0^1 u_1(t) dt + \gamma_2 \int_0^1 u_2(t) dt, \qquad (2)$$

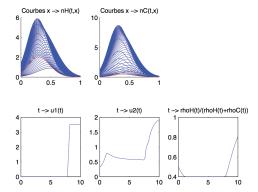
where $(n_C(\cdot,\cdot),n_H(\cdot,\cdot))$ is the unique solution of the system of PDEs corresponding to the controls $\underline{u_1}$ and $\underline{u_2}$, such that $n_H(0,\cdot)=n_H^0(\cdot)$ and $n_C(0,\cdot)=n_C^0(\cdot)$ and where the trajectory $t\mapsto (n_C(\cdot,t),n_H(\cdot,t))$ is subject to the dynamic state constraint

$$\frac{\rho_H(t)}{\rho_H(t) + \rho_C(t)} \ge \theta. \tag{3}$$

(in simulations, e.g., $\theta=0.4$) We use a direct approach, discretising the whole problem and then solving the resulting constrained optimisation problem with AMPL (automatic differentiation) combined with IPOPT (expert optimisation routine)

Numerical solution to this first optimal control problem

Distribution of populations according to phenotype (black: initial; red: final; blue: intermediate steps of the optimisation algorithm)



Left and centre panels: optimal drug flows for $u_1(t)$ (cytotoxic) and $u_2(t)$ (cytostatic) Right panel: satisfaction of dynamic constraint

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Introducing 'adaptive therapy', following Robert Gatenby

OPINION

- Principle: keep alive an objective ally in the enemy place
- Relies on competition for resources between resistant (weakly proliferative) and sensitive cancer cells in the tumour
- Aim: avoid extinction of sensitive tumour cells, that are able to outcompete resistant tumour cells provided that not too high doses of a drug are delivered
- Method: deliver relatively low doses of the drug to prevent thriving of too many sensitive cells and limit emergence of too many (unbeatable) resistant cells
- Objective: controlling total (sensitive + resistant) tumour cell population

 Caveat: not necessarily applicable in the case of fast growing tumours (e.g., acute myeloblastic leukaemia)

ESSAY

A change of strategy in the war on cancer

Patients and politicians anxiously await and increasingly demand a 'cure' for cancer. But trying to control the disease may prove a better plan than striving to cure it, says Robert A. Gatenby.



Second optimal control problem, same IDE model (1)

Environment:
$$I_H(t) = a_{HH}.\rho_H(t) + a_{HC}.\rho_C(t), I_C(t) = a_{CH}.\rho_H(t) + a_{CC}.\rho_C(t),$$
 with $\rho_H(t) = \int_0^1 n_H(x,t) \, dx, \rho_C(t) = \int_0^1 n_C(x,t) \, dx.$

Same IDE model with evolution in phenotype x due to effects of cytotoxic drug $u_1(t)$

$$\frac{\partial}{\partial t} n_H(x,t) = \left(\frac{r_H(x)}{1 + \alpha_H u_2(t)} - d_H(x) I_H(t) - u_1(t) \mu_H(x)\right) n_H(x,t)$$

$$\frac{\partial}{\partial t} n_C(x,t) = \left(\frac{r_C(x)}{1 + \alpha_C u_2(t)} - d_C(x) I_C(t) - u_1(t) \mu_C(x)\right) n_C(x,t)$$

$$0 \le u_1(t) \le u_1^{\max}, \qquad 0 \le u_2(t) \le u_2^{\max}$$

$$\min C_T(u_1, u_2) = \rho_C(T) = \int_0^1 n_C(x, T) dx$$

under the additional constraints

$$\frac{\rho_H(t)}{\rho_H(t) + \rho_C(t)} \ge \theta_H, \qquad \rho_H(t) \ge \rho_H(0)$$

Second optimal control problem, same IDE model (2)

Furthermore, we may add the "adaptive" constraint

$$\frac{
ho_{CS}(t)}{
ho_{C}(t)} \geq heta_{CS}, \text{ where }$$

$$\rho_{CS}(t) = \int_0^1 (1-x)n_C(t,x) dx$$

may be seen as the total number at time t of tumour cells that are sensitive, and

$$\rho_{CR}(t) = \int_0^1 x n_C(t, x) \, dx$$

as the total number at time t of tumour cells that are resistant

... but this newly added constraint does not in fact change anything to the results of simulations...

Second optimal control problem: theoretical results

Theorem

Under these conditions, the optimal trajectory in large time T>0 consists of 3 arcs:

- 1. A first transient **short-time** arc, consisting of reaching the boundary $\frac{\rho_H(t)}{\rho_H(t) + \rho_C(t)} = \theta_H$, with $u_1 = 0$ and with an appropriate control u_2 .
- 2. A middle long-time arc: $u_1=0,\ u_2\simeq\mathrm{Cst},$ this constant being tuned so that

$$\frac{\rho_H(t)}{\rho_H(t) + \rho_C(t)} = \theta_H.$$

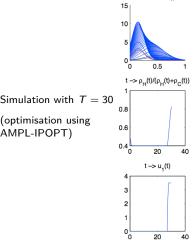
At the end of this long-time arc, we have

$$n_H(\cdot,t) \simeq
ho_H^\infty \delta_{\mathsf{X}_H^\infty}, \quad n_C(\cdot,t) \simeq
ho_C^\infty \delta_{\mathsf{X}_C^\infty} \qquad (\delta_{\mathsf{X}_{[H,C]}^\infty} \ \textit{unit Dirac masses})$$

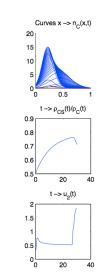
for some constant concentrations ρ_H^∞ and ρ_C^∞ at some given respective phenotypes x_H^∞ and x_C^∞ , i.e., healthy and tumour cell populations have concentrated and do not evolve neither in time nor w.r.t. phenotype.

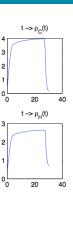
A last transient short-time arc: u₁ = u₁^{max}, u₂ = u₂^{max}, along which the population of healthy and of tumour cells is very quickly decreasing.

Simulations illustrating this theorem



Curves $x \rightarrow n_{LI}(x,t)$





Interpretation

Neglecting the first transient arc, in a first approximation the optimal trajectory is made of two parts, the first one with $u_1 = 0$ and the second one with $u_1 = u_1^{\text{max}}$.

Main idea:

- 1. Let the system naturally evolve to a phenotype concentration (long-time phase).
- Then, apply the maximal quantity of drugs, during a short-time phase, in order to eradicate as many tumour cells as possible.

The second short-time phase is all the more efficient as the phenotypes are more concentrated (hence, as the time T is large).

We have two facts to prove: 1) convergence and concentration; 2) optimality of the concentrated state to start the final drug delivery phase.

Looking for the proof of the theorem, beginning with the simpler case of constant controls, we investigated different tracks. The first attempt failed, but its main ingredients were used in the actual proof (still with constant controls), which relies on the design of a Lyapunov functional.

First attempt: constant controls, asymptotic behaviour

Lemma

Assume that $u_1 = \operatorname{Cst} = \overline{v}_1$ and that $u_2(t) = \operatorname{Cst} = \overline{v}_2$. Then there exist traits x_H^∞ and x_C^∞ such that for some constants ρ_H^∞ and ρ_C^∞ , $\forall (n_H(\cdot,0), n_C(\cdot,0))$ $n_H(\cdot,t) \xrightarrow{\to} \rho_H^\infty \delta_{x_H^\infty}$, $n_C(\cdot,t) \xrightarrow{\to} \rho_C^\infty \delta_{x_C^\infty}$.

Proof.
$$\frac{\partial}{\partial t} n_H(x,t) = \left[\frac{r_H(x)}{1 + k_H u_2(t)} - d_H(x) I_H(t) - u_1(t) \mu_H(x) \right] n_H(x,t)$$
$$\frac{\partial}{\partial t} n_C(x,t) = \left[\frac{r_C(x)}{1 + k_C u_2(t)} - d_C(x) I_C(t) - u_1(t) \mu_C(x) \right] n_C(x,t)$$

where we recall that $I_H(t) = a_{HH}.\rho_H(t) + a_{HC}.\rho_C(t), I_C(t) = a_{CH}.\rho_H(t) + a_{CC}.\rho_C(t),$ and $\rho_H(t) = \int_0^1 n_H(x,t) \, dx, \rho_C(t) = \int_0^1 n_C(x,t) \, dx$. Firstly, we tried to show, integrating in x and taking lower and upper bounds w.r.t. x, that $(\rho_H(t), \rho_C(t))$ satisfy integral *inequalities* with at each bound the solutions of a coupled system of non-explosive Riccati equations (aka Lotka-Volterra with competition and coexistence)

$$\dot{z}_1(t) = z_1(t)(a_1 - b_{11}z_1(t) - b_{12}z_2(t))$$

 $\dot{z}_2(t) = z_2(t)(a_2 - b_{22}z_2(t) - b_{21}z_1(t)).$

However, although this argument works in 1D [and in 2D in the case of mutualism, not competition], it implies only the convergence of sub- and supersolutions. $\bullet \equiv \bullet$



Asymptotic behaviour, first attempt to the proof (1)

Unfortunately, even if we had such boundaries for the solutions, oscillatory behaviour between boundaries could not be excluded! Note that if nevertheless convergence of $(\rho_H(t),\rho_C(t))$ were granted, then concentration would then follow from the exponential behaviour of $n_H(\cdot,t)$ and $n_C(\cdot,t)$, as we will show next.

1. Convergence towards what? Assume that $u_1(t)=\mathrm{Cst}=\bar{u}_1$, $u_2(t)=\mathrm{Cst}=\bar{u}_2$ and that for any initial population of healthy and of tumour cells, convergence of $(\rho_H(t),\rho_C(t))$ when $t\to+\infty$ is taken for granted. Then the equilibrium point $(\rho_H^\infty,\rho_C^\infty)$ towards which $(\rho_H(t),\rho_C(t))$ converges can be exactly computed as follows. Let $a_1\geq 0$ and $a_2\geq 0$ be the smallest nonnegative real numbers such that

$$(\forall x) \quad \frac{r_H(x)}{1+\alpha_H \overline{\mathbf{u}}_2} - \overline{\mathbf{u}}_1 \mu_H(x) \leq d_H(x) a_1 \quad \text{and} \quad \frac{r_C(x)}{1+\alpha_C \overline{\mathbf{u}}_2} - \overline{\mathbf{u}}_1 \mu_C(x) \leq d_C(x) a_2.$$

(Remark: for $\bar{\mathbf{u}}_1$, $\bar{\mathbf{u}}_2$ fixed, call $R_{H,C}(x_0,a_{1,2}) \leq 0$ the two inequalities above and assume ab absurdo that $\forall a \in \mathbb{R}_+, \exists x_0 \text{ s.t. } R_{H,C}(x_0,a) > 0$, then by continuity, this would be true on a whole interval around x_0 , hence there would be exponential blow-up of the population, which is excluded by the convergence hypothesis.)

Then $(\rho_H^\infty, \rho_C^\infty)$ is the unique solution of the system (invertible as a consequence of the fact that intraspecific competition is assumed higher than interspecific competition)

$$\begin{aligned} &a_{HH}\rho_H^\infty + a_{HC}\rho_C^\infty = a_1,\\ &a_{CH}\rho_H^\infty + a_{CC}\rho_C^\infty = a_2.\end{aligned}$$

Asymptotic behaviour, first attempt to the proof (2)

2. Concentration. Furthermore, if $A_H \subset [0,1]$ (resp., $A_C \subset [0,1]$) is the set of all points such that equalities hold in (1), then the supports of the probability measures $\nu_H(t) = \frac{n_H(x,t)}{\rho_H(t)} dx$ and $\nu_C(t) = \frac{n_C(x,t)}{\rho_C(t)} dx$ converge respectively to A_H and A_C . In particular, if A_H is reduced to a singleton x_C^∞ , and if A_C is reduced to a singleton x_C^∞ (cases of our simulations), then $\nu_H(t)$ and $\nu_C(t)$ converge for the vague topology respectively to the Dirac masses $\delta_{x_H^\infty}$ and $\delta_{x_C^\infty}$ for some $x_H^\infty \in [0,1]$ and $x_C^\infty \in [0,1]$ as t tends to $+\infty$.

This theorem (that still remains to be proved) asserts that, under generic conditions that are satisfied here with the numerical data that we have chosen and under a constant drug treatment, the populations of healthy and of tumour cells concentrate to some respective phenotypes that can be exactly computed.

Asymptotic behaviour, first attempt to the proof (3)

Indeed, by integration, we have

$$\begin{split} n_H(x,t) &= n_H^0(x) \exp \left(\left(\frac{r_H(x)}{1 + \alpha_H \bar{\mathbf{u}}_2} - \bar{\mathbf{u}}_1 \mu_H(x) \right) t \right. \\ &\qquad \qquad - d_H(x) \left(a_{HH} \int_0^t \rho_H(s) \, ds + a_{HC} \int_0^t \rho_C(s) \, ds \right) \right), \\ n_C(x,t) &= n_C^0(x) \exp \left(\left(\frac{r_C(x)}{1 + \alpha_C \bar{\mathbf{u}}_2} - \bar{\mathbf{u}}_1 \mu_C(x) \right) t \right. \\ &\qquad \qquad - d_C(x) \left(a_{CH} \int_0^t \rho_H(s) \, ds + a_{CC} \int_0^t \rho_C(s) \, ds \right) \right). \end{split}$$

Then, since for large t, we have $\int_0^t \rho_H(s) ds \sim \rho_H^{\infty} t$ and $\int_0^t \rho_C(s) ds \sim \rho_C^{\infty} t$, the asymptotic behaviour of $n_H(x,t)$ and of $n_C(x,t)$ depends on the functions

$$b_H(x) = \frac{r_H(x)}{1 + \alpha_H \overline{\nu}_2} - \overline{\nu}_1 \mu_H(x) - d_H(x) (a_{HH} \rho_H^{\infty} + a_{HC} \rho_C^{\infty}),$$

$$b_C(x) = \frac{r_C(x)}{1 + \alpha_C \overline{\nu}_2} - \overline{\nu}_1 \mu_C(x) - d_C(x) (a_{CH} \rho_H^{\infty} + a_{CC} \rho_C^{\infty}),$$

whose maxima on [0,1] may be shown to be both zero. The points at which these maxima are attained (A_H and A_C , generically singletons x_μ^∞ and x_C^∞) are the supports of the announced Dirac masses.

Proof with constant controls, using a Lyapunov functional

However, convergence was hitherto only taken for granted! We will in the sequel prove at the same time convergence and concentration by designing a Lyapunov functional.

Theorem

Assume that u_1 and u_2 are constant: $u_1 \equiv \bar{u}_1$, and $u_2 \equiv \bar{u}_2$. Then, for any positive initial population of healthy and of tumor cells, $(\rho_H(t), \rho_C(t))$ converges to the equilibrium point $(\rho_H^\infty, \rho_C^\infty)$, which can be exactly computed as follows. Let $a_1 \geq 0$ and $a_2 \geq 0$ be the smallest nonnegative real numbers such that

$$\frac{r_H(x)}{1+\alpha_H\bar{u}_2} - \bar{u}_1\mu_H(x) \leq d_H(x)a_1 \quad \text{and} \quad \frac{r_C(x)}{1+\alpha_C\bar{u}_2} - \bar{u}_1\mu_C(x) \leq d_C(x)a_2.$$

Then $(\rho_H^{\infty}, \rho_C^{\infty})$ is the unique solution of the (invertible) system

$$a_{HH}\rho_H^{\infty} + a_{HC}\rho_C^{\infty} = a_1,$$

 $a_{CH}\rho_H^{\infty} + a_{CC}\rho_C^{\infty} = a_2.$

Let $A_H \subset [0,1]$ (resp., $A_C \subset [0,1]$) be the set of all points $x \in [0,1]$ such that equality hold in one of the inequalities above. Then the supports of the probability measures

$$u_H(t) = \frac{n_H(t,x)}{\rho_H(t)} dx$$
 and $u_C(t) = \frac{n_C(t,x)}{\rho_C(t)} dx$

converge respectively to A_H and A_C as t tends to $+\infty$.



Basis of proof (constant controls): a Lyapunov functional

Firstly, the correspondence $(a_1,a_2)\mapsto (\rho_M^\infty,\rho_C^\infty)$ being bijective and controls $\bar{u_1},\ \bar{u_2}$ being constant and omitted in the sequel, one can write the two inequalities above as

$$\forall x \in [0,1], \quad R_H(x,\rho_H^\infty,\rho_C^\infty) \leq 0 \quad \text{and} \quad \forall x \in [0,1], \quad R_C(x,\rho_C^\infty,\rho_H^\infty) \leq 0$$

with, furthermore

$$\forall x \in A_H, \quad R_H(x, \rho_H^{\infty}, \rho_C^{\infty}) = 0 \quad \text{and} \quad \forall x \in A_C, \quad R_C(x, \rho_C^{\infty}, \rho_H^{\infty}) = 0$$

Then, for $m_{H,C}:=rac{1}{d_{H,C}}$, define the Lyapunov functional $V(t):=V_H(t)+V_C(t)$ where

$$V_{H,C}(t) = \lambda_{H,C} \int_0^1 m_{H,C}(x) \left[n_{H,C}^{\infty}(x) \ln \left(\frac{1}{n_{H,C}(t,x)} \right) + \left(n_{H,C}(t,x) - n_{H,C}^{\infty}(x) \right) \right] dx.$$

where $n_{H,C}^{\infty}(x)$ are measures with support in $A_{H,C}$ such that $\int_0^1 n_{H,C}^{\infty}(x) dx = \rho_{H,C}^{\infty}$,

the positive constants λ_H and λ_C being adequately chosen later to make V decreasing along trajectories.

... Next: see Camille Pouchol's presentation tomorrow!

Non-constant controls, towards optimality

See also Camille Pouchol's presentation tomorrow

Second fact: an alternative optimal control problem

Conjecture

Consider the following optimal control problem on the short-time interval $[t_1, T]$:

Find the best possible distribution $n_C(\cdot, t_1)$ such that, applying along $[t_1, T]$ the maximal quantity of drugs, we minimise the quantity $\rho_C(T)$.

The answer is (likely) a Dirac mass:

$$n_{\mathcal{C}}(\cdot,t_1)=\delta_{x_{\mathcal{C}}^{\infty}}.$$

This conjectured lemma, that 'looks true on simulations', implies that, in order to kill as many tumour cells as possible, the drugs are most efficient when the tumour cells are concentrated on a given phenotype.

These two facts, combined with other remarks (showing for instance that T must be large, that the controls must be almost constant, etc.), allow to prove the theorem.

About the 'cooking recipes' used in the simulations (1)

In this version of the simulations (used throughout in the sequel)

$$r_H(x) = \frac{1.5}{1+x^2}, \quad r_C(x) = \frac{3}{1+x^2},$$
 $d_H(x) = \frac{1}{2}(1-0.1x), \quad d_C(x) = \frac{1}{2}(1-0.3x),$
 $u_1^{\text{max}} = 3.5, \quad u_2^{\text{max}} = 7,$

and the initial data are

$$n_H(0,x) = C_0 \exp(-(x-0.5)^2/\varepsilon), \quad n_C(0,x) = C^0 \exp(-(x-0.5)^2/\varepsilon),$$

with $\varepsilon>0$ small (typically, we will take either $\varepsilon=0.1$ or $\varepsilon=0.01$), and where $C_0>0$ is such that

$$\rho_H(0) + \rho_C(0) = 1.$$

About the 'cooking recipes' used in the simulations (2)

The closer to 1 is the variable x, the more resistant are the tumour cells. The choice done in *Lorz et al. 2013* (where no optimal control is considered) is

$$\mu_H(x) = \frac{0.2}{0.7^2 + x^2}, \quad \mu_C(x) = \frac{0.4}{0.7^2 + x^2}.$$

Note that, with this choice of functions, if we take constant controls u_1 and u_2 , with

$$u_1(t) = \text{Cst} = u_1^{\text{max}} = 3.5, \qquad u_2(t) = \text{Cst} = 2,$$

then we can kill all tumour cells (at least, they decrease exponentially to 0), and no optimisation is necessary - not clinically realistic.

So that function μ_C was modified to be zero for x close to the maximum value of the drug resistance phenotype (namely 1), becoming $\mu_C(x) = \max\left(\frac{0.9}{0.7^2 + 0.6x^2} - 1, 0\right)$.

About the 'cooking recipes' used in the simulations (3)

The environment variables $I_{[H,C]}(t)$ defined by

$$I_{H}(t) = a_{HH}\rho_{H}(t) + a_{HC}\rho_{C}(t),$$

$$I_{C}(t) = a_{CH}\rho_{H}(t) + a_{CC}\rho_{C}(t),$$
(1)

and

$$\rho_H(t) = \int_0^1 n_H(x,t) dx, \qquad \rho_C(t) = \int_0^1 n_C(x,t) dx.$$

have been chosen such that

$$a_{HH} = 1$$
, $a_{CC} = 1$, $a_{HC} = 0.07$, $a_{CH} = 0.01$, $\alpha_H = 0.01$, $\alpha_C = 1$,

which means in particular that in the limiting logistic terms in the model, intraspecific competition is overwhelmingly higher than interspecific competition, i.e., cell growth is mainly limited by access to resources, and very little by frontal competition between cancer and healthy cells, a choice done on biological grounds (cancer cells and healthy cells are not thriving on the same metabolic niche, e.g., aerobic vs. glycolytic metabolisms). As a consequence, as in classical Lotka-Volterra models with competition, the choice of these parameters will lead in the simulations to asymptotic coexistence of the two species, healthy and cancer, in a non-trivial equilibrium state.

Comparison with "almost periodic" therapeutic strategies

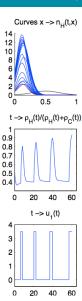
On the right: drugs given almost periodically, within T=60. \rightarrow Far less efficient!!

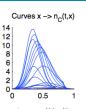
$$\rho_C(T) \simeq 0.03$$

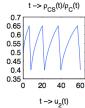
whereas using the previous strategy we had

$$\rho_C(T) \simeq 10^{-6}$$

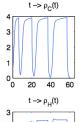
(optimisation using AMPL-IPOPT)







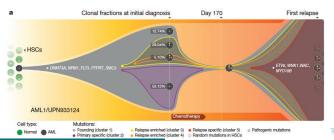






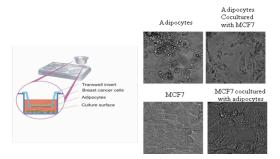
Limitations of this optimisation procedure, owing to the fact that the trait represents resistance to only one drug

- The model assumes one trait of resistance corresponding to one cytotoxic drug.
- However, overcoming resistance using such strategy may not be successful if too many types of resistance coexist, due to high phenotype heterogeneity.
- Phenotype heterogeneity (e.g., multiclonality) within the tumour may reduce such strategy to nothing, unless a multidimensional phenotype is considered.
- ... Unless also one could act very early to avoid the development of transient drug-resistant cell clones by epigenetic drugs or metabolism-modifying strategies.



Extension of the IDE model: tumour micro-environment

Breast cancer cell line MCF7 co-cultured with adipocytes (work 2015)



Control by drugs: cytostatic $v_r(t)$, cytotoxic $v_d(t)$, plus blockade of receptors to intercellular soluble factors $\varphi_A(t), \varphi_C(t)$ by other drugs, e.g., oestrogen receptor blockers $w_{sC}(t)$, antiinflammatory molecules $w_{sA}(t)$

$$\frac{\partial}{\partial t} n_{C}(u,t) = \left[\frac{r_{C}}{1 + v_{r}(t)} + \varphi_{A}(t) \frac{s_{C}(u)}{1 + w_{sC}(t)} - (1 + v_{d}(t)) d_{C}(u) \rho_{C}(t) \right] n_{C}(u,t),$$

$$\frac{\partial}{\partial t} n_{A}(x,t) = \left[r_{A} + \varphi_{C}(t) \frac{s_{A}(x)}{1 + w_{sA}(t)} - d_{A}\rho_{A}(t) \right] n_{A}(x,t).$$

(Camille Pouchol's PhD thesis 2015-...)

Other extensions: dealing with the immune response

- Remarkable recent and longlasting therapeutic results have been obtained in various cancers by using immune checkpoint inhibitors (anti-CTLA-4, anti-PD1, anti-PDL1), monoclonal antibodies that *inhibit inhibition* of immune effector cells, see, e.g., Naidoo et al. in Br J Cancer 2014
- However, remarkable though they are, these results remain limited, long survivors (18 months) in melanoma passing from 0 to 25-40 % in the best cases (Nivolumab in melanoma without BRAF mutation, C. Robert NEJM 2015)
- Using chemotherapies to decrease cancer cell populations, not to eradicate them, but to make them amenable to be kept in check by the immune system, raises reasonable hopes to increase these (already remarkable) results
- This calls for models of the immune response in cancer to optimise cancer treatments by combining chemo- and immunotherapies (another ongoing PhD thesis at LJLL)

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- ...See also https://www.rocq.inria.fr/bang/JC/JCarticles.html









