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> restart:
> with(OreModules):
> with(OreMorphisms);
> with(linalg):

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We consider a time-delay model of a flexible rod with a torque studied in H. Mounier, J. Rudolph, M. Petitot, M. Fliess, "A flexible rod as a linear delay system", in *Proceedings of 3rd European Control Conference*, Rome (Italy), 1995, and defined by the following system matrix:

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> A:=DefineOreAlgebra(diff=[d,t],dual_shift=[delta,s],polynom=[t,s]):
> R:=matrix(2,3,[d,-d*delta,-1,2*d*delta,-d*delta^2-d,0]);

```

$$R := \begin{bmatrix} d & -d\delta & -1 \\ 2d\delta & -d\delta^2 - d & 0 \end{bmatrix}$$

If we denote by  $A = \mathbb{Q}[d, \delta]$  the commutative polynomial ring of differential time-delay operators with rational constant coefficients,  $M = A^{1 \times 3} / (A^{1 \times 2} R)$  the  $A$ -module finitely presented by  $R$ , then we can compute the  $A$ -module structure of the endomorphism ring  $E = \text{end}_A(M)$  of  $M$ :

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> Endo:=MorphismsConstCoeff(R,R,A,mult_table):
> Endo[1];

```

$$\begin{bmatrix} d & 0 & 0 \\ 0 & d & 0 \\ 0 & 0 & d \end{bmatrix}, \begin{bmatrix} 0 & 0 & -1 - \delta^2 \\ 0 & 0 & -2\delta \\ 0 & 0 & d\delta^2 - d \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ -2\delta & 1 + \delta^2 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & d & -\delta \\ d & 0 & -1 \\ 0 & 0 & d\delta \end{bmatrix}, \\ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 + \delta^2 & 0 \\ 0 & 2\delta & 0 \\ 0 & 0 & 2\delta \end{bmatrix}, \begin{bmatrix} 0 & -d & \delta \\ -d & 0 & 1 \\ 0 & 0 & -d\delta \end{bmatrix}$$

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> Endo[2];

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$$\begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 & \delta \\ \delta & 0 & 0 & 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 & d & 0 & 0 \\ 0 & 0 & d & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & d & 2 \end{bmatrix}$$

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> Endo[3];

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$$\begin{bmatrix}
[1,1] & d & 0 & 0 & 0 & 0 & 0 & 0 \\
[1,2] & 0 & d & 0 & 0 & 0 & 0 & 0 \\
[1,3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
[1,4] & 0 & 0 & 0 & 0 & 0 & 0 & -d \\
[1,5] & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
[1,6] & 0 & 0 & 0 & 0 & 0 & 0 & -2 \\
[1,7] & 0 & 0 & 0 & 0 & 0 & 0 & d \\
[2,1] & 0 & d & 0 & 0 & 0 & 0 & 0 \\
[2,2] & 0 & d\delta^2 - d & 0 & 0 & 0 & 0 & 0 \\
[2,3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
[2,4] & 0 & d\delta & 0 & 0 & 0 & 0 & 0 \\
[2,5] & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
[2,6] & 0 & 2\delta & 0 & 0 & 0 & 0 & 0 \\
[2,7] & 0 & -d\delta & 0 & 0 & 0 & 0 & 0 \\
[3,1] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
[3,2] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
[3,3] & 0 & 0 & 1 + \delta^2 & 0 & 0 & 0 & 0 \\
[3,4] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
[3,5] & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
[3,6] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
[3,7] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
[4,1] & 0 & 0 & 0 & 0 & 0 & 0 & -d \\
[4,2] & 0 & d\delta & 0 & 0 & 0 & 0 & 0 \\
[4,3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
[4,4] & d & d & 0 & 0 & 0 & 0 & 0
\end{bmatrix}
\begin{bmatrix}
[4,5] & 0 & 0 & 0 & 0 & 0 & 0 & -1 \\
[4,6] & 2 & 2 & 0 & 0 & 0 & 0 & 0 \\
[4,7] & -d & -d & 0 & 0 & 0 & 0 & 0 \\
[5,1] & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
[5,2] & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
[5,3] & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\
[5,4] & 0 & 0 & 0 & 0 & 0 & 0 & -1 \\
[5,5] & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\
[5,6] & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\
[5,7] & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\
[6,1] & 0 & 0 & 0 & 0 & 0 & 0 & -2 \\
[6,2] & 0 & 2\delta & 0 & 0 & 0 & 0 & 0 \\
[6,3] & 0 & 0 & 2\delta & 0 & -2\delta - 2\delta^3 & 1 + \delta^2 & 0 \\
[6,4] & 2 & 2 & 0 & 0 & 0 & 0 & 0 \\
[6,5] & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\
[6,6] & 0 & 0 & 0 & 0 & 0 & 2\delta & 0 \\
[6,7] & -2 & -2 & 0 & 0 & 0 & 0 & 0 \\
[7,1] & 0 & 0 & 0 & 0 & 0 & 0 & d \\
[7,2] & 0 & -d\delta & 0 & 0 & 0 & 0 & 0 \\
[7,3] & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
[7,4] & -d & -d & 0 & 0 & 0 & 0 & 0 \\
[7,5] & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\
[7,6] & -2 & -2 & 0 & 0 & 0 & 0 & 0 \\
[7,7] & d & d & 0 & 0 & 0 & 0 & 0
\end{bmatrix}$$

Hence, we obtain that the  $A$ -module  $E$  is generated by the  $A$ -endomorphisms  $f_i$ 's defined by the 7 matrices  $P_i$ 's of  $\text{Endo}[1]$ , i.e.,  $f_i(\pi(\lambda)) = \pi(\lambda P_i)$ , where  $\pi : D^{1 \times 3} \rightarrow M$  denotes the canonical projection onto  $M$  and  $\lambda$  is any element of  $A^{1 \times 3}$ . Moreover, the generators  $f_i$ 's of  $E$  satisfy the relations  $\text{Endo}[2] F = 0$ , where  $F = (f_1 \dots f_7)^T$ . Finally, the multiplication table  $T$  of the generators  $f_i$ 's is the matrix  $\text{Endo}[3]$  without the first column which corresponds to the indices  $(i, j)$  of the product  $f_i \circ f_j$ , namely, we have  $F \otimes F = T F$ , where  $\otimes$  denotes the Kronecker product, namely,  $F \otimes F = ((f_1 \circ F)^T \dots (f_7 \circ F)^T)^T$ . Using  $\text{Endo}[3]$ , we can rewrite any polynomial in the  $f_i$ 's with coefficients in  $A$  as an  $A$ -linear combination of the  $f_i$ 's.

Let us try to find idempotent elements of  $E$  defined by idempotent matrices  $P \in A^{3 \times 3}$  and  $Q \in A^{2 \times 2}$ , namely,  $e \in E$  satisfying  $e^2 = e$ , where  $e(\pi(\lambda)) = \pi(\lambda P)$ , for all  $\lambda \in A^{1 \times 3}$ , and  $RP = QR$ ,  $P^2 = P$ ,  $Q^2 = Q$ :

```
> Idem:=IdempotentsMatConstCoeff(R,Endo[1],A,2);
```

$Idem :=$

$$\left[ \begin{bmatrix} -\delta^2 & 1/2 \delta (1 + \delta^2) & 0 \\ -2\delta & 1 + \delta^2 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 + \delta^2 & -1/2 \delta (1 + \delta^2) & 0 \\ 2\delta & -\delta^2 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right],$$

$[Ore\_algebra, ["diff", dual\_shift], [t, s], [d, \delta], [t, s], [], 0, [], [], [t, s], [], [], [diff = [d, t], dual\_shift = [\delta, s]]]$

We obtain two non-trivial idempotent endomorphisms  $e_1$  and  $e_2$  of  $E$  respectively defined by the matrices  $Idem[1, 1]$  and  $Idem[1, 3]$ . We note that we have  $e_1 + e_2 = id_M$ . Let us consider  $e_1$  defined by the following matrices  $P = Idem[1, 1]$  and  $Q \in A^{2 \times 2}$  satisfying  $RP = QR$ :

$> P := Idem[1, 1]; Q := Factorize(Mult(R, P, A), R, A);$

$$P := \begin{bmatrix} -\delta^2 & 1/2 \delta (1 + \delta^2) & 0 \\ -2\delta & 1 + \delta^2 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad Q := \begin{bmatrix} 0 & 1/2 \delta \\ 0 & 1 \end{bmatrix}$$

As we have  $P^2 = P$  and  $Q^2 = Q$ , we know that the  $A$ -modules  $\ker_A(.P)$ ,  $\text{im}_A(.P) = \ker_A(. (I_3 - P))$ ,  $\ker_A(.Q)$  and  $\text{im}_A(.Q) = \ker_A(. (I_2 - Q))$  are projective, and thus, free by the Quillen-Suslin theorem. Let us compute bases of the corresponding modules. We try heuristic methods implemented in OREMODULES which do not require the use of the package QUILLENSUSLIN:

$> U1 := SyzygyModule(P, A); U2 := SyzygyModule(evalm(1-P), A);$   
 $> U := stackmatrix(U1, U2);$   
 $> V1 := SyzygyModule(Q, A); V2 := SyzygyModule(evalm(1-Q), A);$   
 $> V := stackmatrix(V1, V2);$

$$U := \begin{bmatrix} -2 & \delta & 0 \\ 0 & 0 & 1 \\ -2\delta & 1 + \delta^2 & 0 \end{bmatrix} \quad V := \begin{bmatrix} -2 & \delta \\ 0 & 1 \end{bmatrix}$$

We obtain that the two unimodular matrices  $U$  and  $V$ , i.e.,  $U \in GL_3(A)$  and  $V \in GL_2(A)$ , satisfy that the matrix  $VRU^{-1}$  is block-diagonal:

$> R\_dec := Mult(V, R, LeftInverse(U, A), A);$

$$R\_dec := \begin{bmatrix} d - d\delta^2 & 2 & 0 \\ 0 & 0 & -d \end{bmatrix}$$

We can also use the command *HeuristicDecomposition* to directly obtain the previous result:

$> HeuristicDecomposition(R, P, A)[1];$

$$\begin{bmatrix} d - d\delta^2 & 2 & 0 \\ 0 & 0 & -d \end{bmatrix}$$

We can simplify  $R\_dec$  by introducing the unimodular matrix  $X$  defined by:

$> X := diag(evalm([[0, 1], [1/2, -(d-d*\delta^2)/2]]), -1);$

$$X := \begin{bmatrix} 0 & 1 & 0 \\ 1/2 & -1/2 d + 1/2 d\delta^2 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

Indeed, we have:

$> Mult(R\_dec, X, A);$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & d \end{bmatrix}$$

Therefore, if we consider the new matrix  $W = X^{-1}U \in \text{GL}_3(A)$  defined by

> `W:=Mult(LeftInverse(X,A),U,A);`

$$W := \begin{bmatrix} -2d + 2d\delta^2 & d\delta - d\delta^3 & 2 \\ -2 & \delta & 0 \\ 2\delta & -1 - \delta^2 & 0 \end{bmatrix}$$

we then have the following simple decomposition of the matrix  $R$ :

> `S:=Mult(V,R,LeftInverse(W,A),A);`

$$S := \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & d \end{bmatrix}$$

Hence, we obtain that  $M \cong A^{1 \times 3}/(A^{1 \times 2}S) \cong A \oplus A/(Ad)$ . Moreover, the linear system of differential time-delay equations  $\ker_{\mathcal{F}}(R)$ , where  $\mathcal{F}$  is an  $A$ -module (e.g.,  $\mathcal{F} = C^\infty(\mathbb{R})$ ) is equivalent to  $\ker_{\mathcal{F}}(S)$ . In particular, an element  $\zeta = (\zeta_1 \ \zeta_2 \ \zeta_3)^T \in \ker_{\mathcal{F}}(S)$  satisfies  $\zeta_1 = 0$ ,  $\zeta_2$  is arbitrary function of  $\mathcal{F}$  and  $\zeta_3 = c$  an arbitrary constant. Then,  $\eta = W^{-1}\zeta$  is the general solution of the linear system  $\ker_{\mathcal{F}}(R)$ .

We point out that the previous simple equivalent matrix  $S$  cannot be obtained by just noticing that the first row of  $R$  contains the invertible element  $-1$  and post-multiplying  $R$  by the following elementary matrix  $Y$

> `Y:=matrix(3,3,[1,0,0,0,1,0,d,d*delta,-1]);`

$$Y := \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ d & -d\delta & -1 \end{bmatrix}$$

as we then obtain:

> `L:=Mult(R,Y,A);`

$$L := \begin{bmatrix} 0 & 0 & 1 \\ 2d\delta & -d\delta^2 - d & 0 \end{bmatrix}$$

We refer the reader to A. Fabiańska, A. Quadrat, “Applications of the Quillen-Suslin theorem in multidimensional systems theory”, chapter of the book *Gröbner Bases in Control Theory and Signal Processing*, H. Park and G. Regensburger (Eds.), Radon Series on Computation and Applied Mathematics 3, de Gruyter publisher, 2007, 23-106, for different algorithms which simplify the presentation matrices. Indeed, the previous computation only shows that we have:

$$M \cong A^{1 \times 3}/(A^{1 \times 2}L) \cong A^{1 \times 2}/(A(2d\delta \quad -d(\delta^2 + 1))).$$

Using the equivalent presentation matrix  $L$  of  $M$ , we then need to compute  $t(M)$  and  $M/t(M)$  as explained in F. Chyzak, A. Quadrat, D. Robertz, “Effective algorithms for parametrizing linear control systems over Ore algebras”, *Appl. Algebra Engrg. Comm. Comput.*, 16 (2005), 319-376, to get that  $t(M) \cong A/(Ad)$  and  $M/t(M) \cong A$  and to combine these results with the particular fact that  $M \cong t(M) \oplus M/t(M)$  to find again that  $M \cong A \oplus A/(Ad)$ . However, all these information are obtained in one step using the previous decomposition approach.

Let us study the  $A$ -module structure  $A^{1 \times 7}/(A^{1 \times 6} \text{Endo}[2])$  of the endomorphism ring  $E$ .

> `ext1:=Exti(Involution(Endo[2],A),A,1);`

$$ext1 := \left[ \begin{array}{cccccccc} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & d & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & d & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right], \left[ \begin{array}{cccccccc} 1 & 1 & 0 & 0 & 0 & 0 & \delta & 0 \\ \delta & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 & d & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 2\delta & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & d & 2 & 0 \end{array} \right], \left[ \begin{array}{c} -d \\ d - d\delta^2 \\ 0 \\ -d\delta \\ -1 \\ -2\delta \\ d\delta \end{array} \right]$$

We obtain that the endomorphisms  $t_1 = f_3$  and  $t_2 = 2\delta f_5 - f_6$  generate the torsion  $A$ -module  $t(E)$ . We note that  $f_5 = \text{id}_M$ , a fact showing that  $t_2 = 2\delta \text{id}_M - f_6$ . In particular, we obtain that every element in  $t_1(M)$  or in  $t_2(M)$  define a torsion element of  $M$ . Moreover, the  $A$ -module  $E/t(E)$  is finitely presented by the second matrix  $ext1[2]$  of  $ext1$ , i.e.,  $E/t(E) = A^{1 \times 7}/(A^{1 \times 7} ext1[2])$ . We also have  $E/t(E) \cong A^{1 \times 7} ext1[3]$ .

> `T:=LeftInverse(ext1[3],A);`

$$T := \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & -1 & 0 \end{bmatrix}$$

As the matrix  $ext1[3]$  admits a left-inverse of  $A$ , we obtain that  $E/t(E) \cong A$ , i.e.,  $E/t(E)$  is a free  $A$ -module of rank 1. In particular, the short exact sequence of  $A$ -modules

$$0 \longrightarrow t(E) \xrightarrow{\iota} E \xrightarrow{\rho} E/t(E) \longrightarrow 0 \quad (1)$$

splits and we obtain  $E \cong t(E) \oplus E/t(E) \cong t(E) \oplus A$ . Let us now study the  $A$ -module  $t(E)$ :

> `K:=stackmatrix(Factorize(Endo[2],ext1[2],A),SyzygyModule(ext1[2],A));`

$$K := \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & d & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & -2 & -2\delta & 0 & 0 & d & 1 \end{bmatrix}$$

We obtain that  $t(E) \cong A^{1 \times 7}/(A^{1 \times 7} K)$ . Using the special structure of the matrix  $K$ , we get that  $t(E) \cong A/(Ad) \oplus A/(Ad)$ , which shows that:

$$E \cong [A/(Ad)]^2 \oplus A. \quad (2)$$

(2) is consistent with the fact that  $M \cong A^{1 \times 3}/(A^{1 \times 2} S) \cong A \oplus A/(Ad)$  which implies that:

$$\begin{aligned} E &= \text{end}_A(M) \cong \text{hom}_A(A \oplus A/(Ad), A \oplus A/(Ad)) \\ &\cong \text{end}_A(A) \oplus \text{hom}_A(A, A/(Ad)) \oplus \text{hom}_A(A/(Ad), A) \oplus \text{end}_A(A/(Ad)). \end{aligned}$$

We have  $\text{end}_A(A) \cong A$ ,  $\text{hom}_A(A, A/(Ad)) \cong A/(Ad)$  and  $\text{hom}_A(A/(Ad), A) = 0$  because  $A/(Ad)$  is a torsion  $A$ -module and  $A$  is torsion-free. Moreover, we have  $\text{end}_A(A/(Ad)) \cong A/(Ad)$ , which proves (2).

Using the following notations  $F = (f_1 \dots f_7)^T$  and  $G = (g_1 \dots g_7)^T$

> `F:=evalm([seq([f[i]],i=1..nops(Endo[1]))]);`  
> `G:=evalm([seq([g[i]],i=1..rowdim(ext1[2]))]);`

$$F := \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \\ f_5 \\ f_6 \\ f_7 \end{bmatrix} \quad G := \begin{bmatrix} g_1 \\ g_2 \\ g_3 \\ g_4 \\ g_5 \\ g_6 \\ g_7 \end{bmatrix}$$

the generators  $f_i$ 's of the  $A$ -module  $E$  satisfy the relations  $\text{Endo}[2] F = 0$ , namely,

$$> \text{evalm}(\text{Endo}[2] \& * F) = \text{evalm}([\text{rowdim}(\text{Endo}[2])]);$$

$$\begin{bmatrix} f_1 + f_2 + \delta f_7 \\ \delta f_1 + f_7 \\ -f_1 + d f_5 \\ d f_3 \\ f_4 + f_7 \\ d f_6 + 2 f_7 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

and the generators  $g_i$ 's of  $E/t(E)$  satisfy the equation  $\text{ext1}[2] G = 0$ :

$$> \text{evalm}(\text{ext1}[2] \& * G) = \text{evalm}([\text{rowdim}(\text{ext1}[2])]);$$

$$\begin{bmatrix} g_1 + g_2 + \delta g_7 \\ \delta g_1 + g_7 \\ -g_1 + d g_5 \\ g_3 \\ g_4 + g_7 \\ 2 \delta g_5 - g_6 \\ d g_6 + 2 g_7 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Using the split exact sequence of  $A$ -modules  $A^{1 \times 7} \xrightarrow{\text{ext1}[2]} A^{1 \times 7} \xrightarrow{\text{ext1}[3]} A \rightarrow 0$ , we obtain the following injective parametrization of the generators  $g_i$ 's of  $E/t(E)$

$$> \text{evalm}(G) = \text{evalm}(\text{ext1}[3] * h);$$

$$\begin{bmatrix} g_1 \\ g_2 \\ g_3 \\ g_4 \\ g_5 \\ g_6 \\ g_7 \end{bmatrix} = \begin{bmatrix} -d h \\ (d - d \delta^2) h \\ 0 \\ -d \delta h \\ -h \\ -2 \delta h \\ d \delta h \end{bmatrix}$$

where  $h$  is defined by

$$> h = \text{evalm}(T \& * G)[1, 1];$$

$$h = -g_5$$

i.e., we have  $E/t(E) \cong A g_5$  and  $\text{ann}_A(g_5) = 0$ . Moreover, we have  $t(E) \cong A t_1 \oplus A t_2$ , where  $\text{ann}_A(t_1) = \text{ann}_A(t_2) = A d$ , which shows that  $E \cong A g_5 \oplus A t_1 \oplus A t_2$ .

To finish, we can explicitly describe the previous isomorphism. In order to do that, we first compute a generalized inverse  $Z$  of  $\text{ext1}[2]$  over  $A$ :

>  $Z := \text{GeneralizedInverse}(\text{ext1}[2], A);$

$$Z := \begin{bmatrix} 0 & 0 & -1 & 0 & 0 & 0 & 0 \\ 1 & -\delta & 1 - \delta^2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & -1 & -\delta & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 1 & \delta & 0 & 0 & 0 & 0 \end{bmatrix}$$

We can check that we have  $\text{ext1}[2] Z \text{ext1}[2] = \text{ext1}[2]$ . Let us denote by  $H = I_7 - Z \text{ext1}[2]$ :

>  $H := \text{evalm}(1 - \text{Mult}(Z, \text{ext1}[2]), A);$

$$H := \begin{bmatrix} 0 & 0 & 0 & 0 & d & 0 & 0 \\ 0 & 0 & 0 & 0 & d(\delta^2 - 1) & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & d\delta & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2\delta & 0 & 0 \\ 0 & 0 & 0 & 0 & -d\delta & 0 & 0 \end{bmatrix}$$

Using the fact that  $\text{ext1}[2] H = 0$ , we obtain that the  $A$ -morphism  $\sigma : E/t(E) \rightarrow E$  defined by  $\sigma(\pi'(\lambda)) = \pi(\lambda H)$ , where  $\pi' : A^{1 \times 7} \rightarrow E/t(E)$  denotes the projection onto  $E/t(E)$  and  $\lambda$  is an element of  $A^{1 \times 7}$ , satisfies  $\rho \circ \sigma = \text{id}_{E/t(E)}$ . For more details, see Theorem 4 of A. Quadrat, D. Robertz, "Parametrizing all solutions of uncontrollable multidimensional linear systems", *Proceedings of 16<sup>th</sup> IFAC World Congress*, Prague (Czech Republic), 04-08/07/05. We find again that the short exact sequence (1) splits. The  $A$ -morphism  $\sigma$  is defined by:

$$\begin{cases} \sigma(g_1) = d f_5, \\ \sigma(g_2) = d(\delta^2 - 1) f_5, \\ \sigma(g_3) = 0, \\ \sigma(g_4) = d\delta f_5, \\ \sigma(g_5) = f_5, \\ \sigma(g_6) = 2\delta f_5, \\ \sigma(g_7) = -d\delta f_5. \end{cases}$$

Using the relations between the generators  $f_i$ 's of the  $A$ -module  $E$ , we obtain that the  $A$ -morphism  $\chi : \text{id}_E - \sigma \circ \rho : E \rightarrow E$  is defined by:

$$\begin{cases} \chi(f_1) = f_1 - d f_5 = 0, \\ \chi(f_2) = f_2 - d(\delta^2 - 1) f_5 = 0, \\ \chi(f_3) = f_3 = t_1, \\ \chi(f_4) = f_4 - d\delta f_5 = 0, \\ \chi(f_5) = f_5 - f_5 = 0, \\ \chi(f_6) = f_6 - 2\delta f_5 = -t_2, \\ \chi(f_7) = f_7 - d\delta f_5 = 0. \end{cases}$$

Hence, if we define the  $A$ -morphism  $\kappa : E \longrightarrow t(E)$  by

$$\left\{ \begin{array}{l} \kappa(f_1) = 0, \\ \kappa(f_2) = 0, \\ \kappa(f_3) = t_1, \\ \kappa(f_4) = 0, \\ \kappa(f_5) = 0, \\ \kappa(f_6) = -t_2, \\ \kappa(f_7) = 0, \end{array} \right.$$

we then get that  $\text{id}_E = \sigma \circ \rho + \iota \circ \kappa$ . Therefore, using the fact that  $f_5 = \text{id}_M$ , we obtain

$$\left\{ \begin{array}{l} f_1 = d \text{id}_M, \\ f_2 = d(\delta^2 - 1) \text{id}_M, \\ f_3 = t_1, \\ f_4 = d\delta \text{id}_M, \\ f_5 = \text{id}_M, \\ f_6 = 2\delta \text{id}_M - t_2, \\ f_7 = -d\delta \text{id}_M, \end{array} \right. \quad (3)$$

a fact showing that the generators  $f_i$ 's of  $E$  can be expressed in terms of  $\text{id}_M$  and  $t_1 = f_3$  and  $t_2 = 2\delta \text{id}_M - f_6$  and  $\{\text{id}_M, t_1, t_2\}$  generates the  $A$ -module  $E$ . In particular, using the multiplication table  $\text{Endo}[3]$  and (3), we can easily obtain the following small multiplication table for the new family of generators  $\{\text{id}_M, t_1, t_2\}$  (compare with  $\text{Endo}[3]$ ):

$$\left\{ \begin{array}{l} t_1 \circ t_1 = (1 + \delta^2) t_1 \\ t_1 \circ t_2 = 2\delta t_1, \\ t_2 \circ t_1 = (1 + \delta^2) t_2, \\ t_2 \circ t_2 = 4\delta t_2 - 2\delta(2\delta - 1) \text{id}_M, \\ t_i \circ \text{id}_M = \text{id}_M \circ t_i = t_i, \quad i = 1, 2, \end{array} \right.$$

Using it, we can rewrite any polynomial in the  $f_i$ 's with coefficients in  $A$  in terms of an  $A$ -linear combination of  $\text{id}_M, t_1$  and  $t_2$ .