- > with(OreModules):
- > with(OreMorphisms):
- > with(Stafford):
- > with(linalg):

The next examples show that trivial reduction techniques can also be used to simplify the presentation of classical linear differential time-delay systems.

We first start with a wind tunnel model studied in A. Manitius, "Feedback controllers for a wind tunnel model involving a delay: analytical design and numerical simulations", IEEE Trans. Autom. Contr., 29 (1984), pp. 1058-1068.

Let us define the commutative polynomial ring $A = \mathbb{Q}(\zeta, \mathbf{k}, \mathbf{a}, \omega)[\mathbf{d}, \delta]$, where \mathbb{Q} is the field of rational numbers,

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> A := DefineOreAlgebra(diff=[d,t],dual_shift=[delta,s],polynom=[t,s],
> comm=[zeta,k,a,omega],shift_action=[delta,t,h]):
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where d y(t) = $\frac{d}{dt}$ y(t) is the differential operator and δ y(t) = y(t - h) is the time-delay operator.

Let us also consider the matrix P defining the wind tunnel model

> P := matrix(3,4,[d+a,k*a*delta,0,0,0,d,-1,0,0,omega^2,d+2*zeta*omega,-omega^2]);

$$P := \begin{bmatrix} d+a & k \, a \, \delta & 0 & 0 \\ 0 & d & -1 & 0 \\ 0 & \omega^2 & d+2 \, \zeta \, \omega & -\omega^2 \end{bmatrix}$$

and the A-module L finitely presented by P. We can use Stafford's reduction to try to simplify the presentation of L by removing trivial unimodular elements, namely, unimodular elements which are A-linear combinations of the generators of L but not $A_2(Q(\zeta, \mathbf{k}, \mathbf{a}, \omega))$ -linear ones.

$$S := \begin{bmatrix} d+a & -\frac{k a d \delta}{\omega^2} - \frac{2 k a \zeta \delta}{\omega} & k a \delta\\ 0 & \frac{d^2}{\omega^2} + \frac{2 \zeta d}{\omega} + 1 & -d \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 & 0\\ 0 & 0 & 1 & 0\\ 0 & 0 & 0 & 1 \end{bmatrix} \end{bmatrix}$$

We get that L is isomorphic to the A-module L_1 finitely presented by S[1], where the A-isomorphism γ from L_1 onto L is induced by S[2].

> TestIso(S[1],P,S[2],A);

true

We can try again to find a trivial reduction of the presentation of L_1 .

> T := StaffordReduction(S[1],A,"reduce_relations"=true);

$$T := \begin{bmatrix} d+a & -\frac{k a \delta}{\omega^2} \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0\\ 0 & d+2 \zeta \omega & -\omega^2 \end{bmatrix} \end{bmatrix}$$

Thus, L_1 is isomorphic to the A-module L_2 finitely presented by T[1], where the A-isomorphism β from L_2 onto L_1 is induced by T[2].

> TestIso(T[1],S[1],T[2],A);

true

If we define U = T[2] S[2], namely,

> U := Mult(T[2],S[2],A);

 $U := \left[\begin{array}{ccc} 1 & 0 & 0 & 0 \\ 0 & 0 & d + 2\,\zeta\,\omega & -\omega^2 \end{array} \right]$

then $\theta=\gamma$ o β is induced by U and is an A-isomorphism:

> TestIso(T[1],P,U,A);

Hence, we get that the linear differential time-delay system P = 0 defining the wind tunnel model is equivalent to the single differential time-delay equation:

$$\frac{d}{dt}\mathbf{x}(t) + a\mathbf{x}(t) - \frac{k\,a}{\omega^2}\,\mathbf{u}(t-h) = 0.$$

Finally, θ^{-1} is induced by Q[2], where Q[2] is the second entry of Q defined by

> Q := InverseMorphism(T[1],P,U,A);

$$Q := \begin{bmatrix} 1 & 0 & \\ 0 & -\frac{1}{\omega^2} & \\ 0 & -\frac{d}{\omega^2} & \\ 0 & -\frac{\omega^2 + d^2 + 2 \, d \, \zeta \, \omega}{\omega^4} \end{bmatrix}, \begin{bmatrix} 1 & \\ 0 & \\ 0 \end{bmatrix}$$

and we can finally check again that θ^{-1} is an A-isomorphism:

> TestIso(P,T[1],Q[1],A);