Certification dans Isabelle d'un Algorithme d'Accessibilité pour les Systèmes à Pile

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Le contexte général

Les systèmes de transition à pile (Pushdown systems en anglais) sont une modélisation naturelle pour la sémantique des programmes, pas nécessairement déterministes, écrits dans des langages séquentiels (C ou java par exemple) dans lesquels les fonctions peuvent s'appeller mutuellement et récursivement et les variables prennent leurs valeurs dans un domaine fini.

Beaucoup de problèmes de vérification se ramènent au problème de l'accessibilité d'un ensemble (éventuellement infini) de configurations. Une approche efficace pour résoudre ce problème dans le cas des systèmes à piles consiste à raisonner en remontant les transitions : étant donné un ensemble de configurations cible C, on cherche à calculer (efficacement) l'ensemble **pre**^{*}(C) des configurations qui mènent, en suivant un nombre arbitraire de transitions, à un élément de C. C'est possible dans le cas où C est un ensemble rationnel de configurations donné par un automate [].

Le problème étudié

L'algorithme de calcul de $\mathbf{pre}^*(C)$ pour un langage rationnel C est implémenté dans des model-checkers tel que [], les utilisations de ce genre d'outils étant souvent très sensibles (médecine, aéronotique, spatial...), il est impératif que l'on ait totalement confiance dans cet algorithme. Les assistants de preuve comme Isabelle apportent la plus grande confiance possible aujourd'hui. Mon travail n'est pas totalement nouveau, Peter Lammich à Münster a travaillé sur des systèmes un peu plus généraux et certifié dans Isabelle la correction de l'algorithme de calcul de \mathbf{pre}^* pour ces systèmes mais n'a pas encore publié ses résultats.

La contribution proposée

Tout mon travail a été réalisé à l'intérieur du système Isabelle. J'ai écrit une formalisation des systèmes à pile et des automates reconnaissant des ensembles de configurations de système à pile, j'ai certifié l'algorithme abstrait non déterministe présenté dans [] et j'en ai déduit, toujours à l'intérieur d'Isabelle, le théorème suivant : "pour tout langage rationnel C, $\mathbf{pre}^*(C)$ est rationnel".

Les arguments en faveur de sa validité

Ma certification est entièrement vérifiable par Isabelle (version 2011), si le noyau logique d'Isabelle est correct alors ma certification l'est également. Mes résultats sont au niveau de confiance maximal possible par la science actuelle. Par ailleurs, pour faciliter la réutilisation de mes preuves, j'ai pris soin de toutes les écrire dans le langage **lsar** d'Isabelle qui les rend beaucoup plus lisibles et faciles à maintenir que des preuves écrites en "apply-style".

Enfin mes résultats sont très abstraits et généraux, je ne force presque aucun choix d'implémentation.

Le bilan et les perspectives

Il y a encore un trou important entre ma formalisation très abstraite et les algorithmes réellement utilisés dans les outils de Model-chacking comme [], c'est le domaine de raffinement de donnée qui est un sujet qui intéresse beaucoup Peter Lammich et l'équipe dans laquelle j'ai fait mon stage.

Il est aussi possible de symétriser le résultat en cherchant les configurations accessibles depuis un ensemble donné de configurations, c'est un peu plus technique car il faut ajouter des états aux automates et les marquer mais l'essentiel du travail est une adaptation de mes résultats.

Certifying in Isabelle an Automata-Based Reachability Algorithm for Pushdown Systems

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Abstract

Pushdown systems are used in Model-Checking to represent abstracted, non-determinist programs. For this class of infinite transition systems, reachability of regular sets of configurations is computable by automata transformation. I proved this in the proof assistant Isabelle.

Contents

1	Intr	roduction				
2	Scientific Context of my Internship					
	2.1	Isabelle	3			
		2.1.1 Proof Assistant	3			
		2.1.2 Isar Language	4			
2.2 Definition		Definitions	5			
		2.2.1 Pushdown Systems	5			
		2.2.2 Reachability, pre^* , $post^*$	6			
		2.2.3 \mathcal{P} -automata	7			
	2.3	Main Algorithm and Theorem	7			
		2.3.1 pre^* of a Regular Language	7			
		2.3.2 Saturation Procedure Computing pre^*	8			
3	My Formalization					
	3.1	Typing	8			
		3.1.1 Finite Sets	9			
		3.1.2 Records	9			
	3.2	Locales	9			
	3.3 Typeclass for Fresh Copy					

4	My	Certif	ication	12			
	4.1	Non-d	eterminist Abstract Algorithm	12			
	4.2	Contra	ast Between Proofs for Humans and Proofs for Computers	12			
		4.2.1	Inductive Principles	12			
		4.2.2	"Without loss of generality, we assume that \mathcal{A} has no				
			transition leading to an initial state"	13			
5	Conclusion 14						
6	Ack	nowled	dgement	14			
A	Source code						
	A.1	Fresh	Function and Copy	16			
	A.2	Pushd	own Systems	17			
	A.3	Transi	tions in a Pushdown System	17			
		A.3.1	Definition	18			
		A.3.2	Properties	18			
		A.3.3	The set $pre^* C \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots$	19			
	A.4	$\mathcal{P} ext{-}\operatorname{Aut}$	omata	19			
		A.4.1	Recognition and language	20			
	A.5	Satura	tion Procedure	21			
		A.5.1	Definition	22			
		A.5.2	Invariants	22			
		A.5.3	Saturated Automata	23			
	A.6	Certifi	cation of the saturation procedure	23			
		A.6.1	No Transition Should Lead to an Initial State	23			
		A.6.2	Main Lemmas	28			
		A.6.3	Correctness	32			
		A.6.4	Termination	32			
		A.6.5	regular $C \Longrightarrow$ regular (pre [*] C)	34			

1 Introduction

When proving properties of a program, one way to drastically reduce the domain of the variables (and so the size of the search space) is to abstract from the variable values to get an approximation of the behaviour of the original for which Model-Checking is easy to perform. For example, to prove mutual exclusion for a system using locks, it is usually OK to ignore the value of every thing but locks because for this precise problem, we are not interested in what computation is actually done in the critical section. Abstraction often leads to non-determinism because we abstract over the value of variables used in tests. For this we need good tools to handle non-deterministic transition systems.

Pushdown systems used in the Moped [2] model-checker are very good at modeling sequential programs once abstracted enough to get a reasonable domain size for variables. Despite their infinite space, reachability properties can be computed efficiently using finite automata [1, 6]. Computing reachability for some classes of infinite sets of configurations is even possible.

Because of their use in Model-Checking, we want to trust these reachability algorithms by certifying them in the most formal way possible: using a proof assistant.

Isabelle [5] is one of them, its main advantage is the readability of its proofs written in the declarative Isar language [7]. My internship happened in Technische Universität München in the German part of Isabelle development team, the Theorem Proving Group lead by Tobias Nipkow in collaboration with Javier Esparza, also professor at TUM, for the Model-Checking part.

2 Scientific Context of my Internship

2.1 Isabelle

2.1.1 Proof Assistant

Isabelle is a proof assistant. This means that Isabelle looks like a programming environment for a functional language like OCaml [3] but instead of producing programs, it produces proofs. Every step of every proof in Isabelle is verified according to a small logic kernel which we trust so all theorems proved in Isabelle are logical consequences of the axioms introduced in Isabelle libraries.

Working with a proof assistant is a way to increase the confidence we can have in a proof. Formalizing the results of a scientific article often reveals forgotten cases or even logical flaws (see for example [4] page 147).

Isabelle knows several logics but I only used the default one : Higher Order Logic [7]. HOL is a typed logic in which one can quantify over arbitrary (well typed) lambda terms.

In HOL one can define datatypes and recursive function pretty much like in a pure functional programming language but all functions must terminate. Most of the time, the termination proof is an obvious induction following a datatype induction principle but the user can also provide it's own complex termination proof if it is not found automatically by the system.

2.1.2 Isar Language

Any proof in Isabelle can be written either in so called apply-style (as a list of **apply** commands which reduce the current goal until it becomes *True*) or using the Isar language. Apply-style proofs are easy to write but very hard to read and maintain. Isar proofs on the other hand use usual English logic words (**assume**, **show**, **moreover**, **hence** ...) which make them easier to read for humans. Also increasing the readability is the use of the declarative style. This means that proofs in Isar progress from assumptions to goals and that the user writes each property he proves before actually providing a method or a subproof for it.

Let's look at an example from group theory : the characterization of the subgroup generated by a set of elements.

This theorem states that both definitions of the subgroup generated by a set S are equivalent.

$$grp \ S = grp' \ S$$

where grp is defined by $grp \ S = \bigcap \{A \mid subgroup \ A \land S \subseteq A\}$ and grp' is defined by $grp' \ S = \{\Pi \ as \mid pow-prod \ as \ S\}$

which pow-prod as $S \equiv \forall a \in as. \exists b \in S. \exists z. a = b^z$

theorem isar-example: $grp \ S = grp' \ S$ **proof**

— the keyword **proof** starts a proof by applying a standard method

- here it transforms the set equality into two inclusions have $S \subseteq grp' S$ - to prove the first one $grp S \subseteq grp' S$, we first prove this proof - $S \subseteq grp' S$ has been turned to $\bigwedge a. \ a \in S \implies a \in grp' S$ fix a assume $a \in S$ thus $a \in grp' S$ using grp'-def [of [a], OF pow-prod-singl] by simp

```
qed
 with subgroup-grp'[of S] show grp S \subseteq grp' S
   unfolding grp-def by blast
next
 show grp' S \subseteq grp S
 proof
   fix a
   assume a \in grp' S
   then obtain as where p: pow-prod as S and a: a = \Pi as
     unfolding original-grp'-def by blast
   have set as \subseteq grp S
   proof
    fix x
    assume x \in set as
     with p obtain b z where b: b \in S and [simp]: x = b^z
       — for later use, propositions can be explicitly named
      — or declared as simplification rules
      unfolding pow-prod-def by blast
     thus x \in grp \ S using pow-grp[OF b] by fast
   qed
   from subgroup-prod [of grp S as, OF - this] show a \in grp S
     by (simp \ add: a)
 qed
qed
```

2.2 Definitions

2.2.1 Pushdown Systems

Pushdown systems [1] are like pushdown automata ignoring their input. They are transition systems which use an unbounded stack so their set of configurations are usually infinite. Pushdown systems are good for modeling sequential programs written in language such as C or java where functions or procedures can call each other, sometimes recursively or mutually recursively because this is really how these programs are compiled. However, this model forces finiteness of the variable domain and the size of the pushdown system will be proportional to it.

Definition 1 (Pushdown System) A pushdown system \mathcal{P} is formally defined by:

- A finite set Control \mathcal{P} of control states.
- An alphabet $\Sigma \mathcal{P}$ of stack symbols.
- An initial configuration Initial \mathcal{P} (which doesn't play any role for our purpose)

• A finite set $\Delta \mathcal{P}$ of transition rules of the following form:

$$(p, \gamma) \hookrightarrow (p', w)$$

where p and p' are control states, γ is a stack symbol and w is a string of stack symbols.

We fix a pushdown system \mathcal{P} .

Definition 2 (Configuration) Configurations of \mathcal{P} are couples of control states and stack contents (i.e. strings of stack symbols).

Definition 3 (Transition) Transitions of \mathcal{P} are defined by: $(p, \gamma u) \Rightarrow (p', w @ u)$ if and only if $(p, \gamma) \hookrightarrow (p', w)$ is a rule of the system where u is an arbitrary string of stack symbols.

As usual, we denote by \Rightarrow^* the reflexive transitive closure of the transition relation \Rightarrow .

2.2.2 Reachability, *pre*^{*}, *post*^{*}

In order to compute reachability properties for pushdown systems, two functions, pre^* and $post^*$ have proved to be very practical [1, 6]. They are defined by

 $pre^* \ C = \{c \mid \exists c' \in C. \ c \Rightarrow^* c'\}$

and symmetrically

 $post^* \ C = \{c \mid \exists c' \in C. \ c' \Rightarrow^* c\}$

The reachability problem

given two configurations c_1 and c_2 , do we have $c_1 \Rightarrow^* c_2$?

can be expressed in term of pre^* (resp. $post^*$) as

given two configurations c_1 and c_2 , do we have $c_1 \in pre^* \{c_2\}$ (resp. $c_2 \in post^* \{c_1\}$)?

So we are looking for ways to represent (possibly infinite) sets with the following requirements:

- one-element sets must be representable
- membership test must be computable (and preferably easy to perform)
- if a set C is representable, then $pre^* C$ is also representable and we have an algorithm transforming any representation of C into a representation of $pre^* C$

They are several way to solve this [1], I only worked on the most simple one: regular sets and automata.

2.2.3 \mathcal{P} -automata

So we are going to manipulate sets of configuration represented by automata. Since the configurations are not just strings but couples, we will slightly change the usual definition of automata and recognition by taking into account the initial state used to read the word.

Definition 4 (\mathcal{P} -automaton) A \mathcal{P} -automaton \mathcal{A} is defined by:

- a finite set Q A of states containing the set Control P of control states of P used as initial states
- a finite set Final \mathcal{A} of final states
- a finite set $\delta \mathcal{A}$ of transitions i.e. triples of state, stack symbol and state. $(p, \gamma, q) \in \delta \mathcal{A}$ is abbreviated by $p \xrightarrow{\gamma}_{\mathcal{A}} q$.

Since \mathcal{P} is fixed, we will simply call them automata. The transition relation $\delta \mathcal{A}$ is extended the usual way to strings.

Definition 5 (Language)

The language of \mathcal{A} is then defined by replacing the usual set of initial states by Control \mathcal{P} and taking the chosen control state into account.

$$\mathcal{L} \mathcal{A} \equiv \{(p, w) \mid \exists q \in Final \mathcal{A}. p \in Control \mathcal{P} \land p \xrightarrow{w}_{\mathcal{A}} q\}$$

2.3 Main Algorithm and Theorem

2.3.1 pre^* of a Regular Language

The main property of pre^* and $post^*$ for pushdown systems is that they preserve the regularity; for any regular set C of configurations (of \mathcal{P}), pre^* C and $post^* C$ are also regular [1].

2.3.2 Saturation Procedure Computing pre*

Even more, we actually have a procedure to transform an automaton recognizing C into an automaton recognizing $pre^* C$ (and also for $post^* C$ but this is a bit more complex). This work by saturating the following rule:

If $(p, \gamma) \hookrightarrow (p', w)$ is a rule of \mathcal{P} and $p' \xrightarrow{w}_{\mathcal{A}} q$, then add a transition $p \xrightarrow{\gamma}_{\mathcal{A}} q$.

3 My Formalization

3.1 Typing

Strings are simply represented by lists. This is a very reasonable typing choice for a lot of reasons:

- This is a very simple datatype for which inductive proofs are usually easy.
- It's also very easy to define recursive functions on lists and reason about them inductively.
- Isabelle provides a lot of theorems for lists in the standard library
- When they are used as stack values, it's reasonable to access only the head in constant time.

I tried not to force any other implementation choice so the choice of types is totally let to the user. I accomplished this by working with polymorphic datatypes using a type variable 's for stack symbols and automata letters and another type variable 'c for pushdown systems control symbols and automata states. So for example, given an automaton \mathcal{A} , it's transition table is so typed :

$$\delta$$
 (\mathcal{A} ::: ('c, 's) P-Automaton) ::: ('c * 's * 'c) set

However, for technical reasons that we will see later, I had to restrict the choice for c to an infinite type and my results are really only totally proved when c is the type of natural numbers.

3.1.1 Finite Sets

I formalized pushdown systems and automata using the built-in *set* type constructor and constraining them to be finite using the *finite* predicate. This level of abstraction permits to write implementation-independent proofs which are often easier to write and more general. The price to pay for it is the loss of computability at this level of abstraction. Automatically deriving for such theorems corresponding ones replacing all the finite sets by a real (usable for computation) datatype is the goal of a branch of theorem proving called Data Refinement and on which several Isabelle developers and contributors are currently working.

3.1.2 Records

Pushdown systems and automata are defined using the Isabelle record mechanism :

type-synonym ('c, 's) $config = 'c * 's \ list$

record ('c, 's) Pushdown-System = $\Delta :: ('c * 's * 'c * 's list) set$ Initial :: ('c, 's) config $\Sigma :: 's set$ Control :: 'c set

record ('c, 's) *P*-Automaton = $Q :: 'c \ set$ $\delta :: ('c \ s's \ s'c) \ set$ *Final* :: 'c set

I have chosen this mechanism because it gives explicit names to fields which makes proofs easier to read and maintain than defining them by tuples (which in Isabelle are just nested couples).

I did however not use the full power of records because I did not want nor need to cope with exstensibility; usually, fields can be added to records in a way similar to classe inheritance in object-oriented programming.

3.2 Locales

Locales are the way to define persistent contexts in Isabelle. I found them very useful.

I use locales to axiomatize structural constraints which defines my objects, especially finiteness constraints. For instance, here is the definition of the locale predicate for automata:

 $\mathit{PA} \ \mathcal{P} \ \mathcal{A} \equiv$

 $\begin{array}{l} (PS \ \mathcal{P} \land \textit{finite} \ (Q \ \mathcal{A})) \land \\ \Delta \ \mathcal{A} \subseteq \ Q \ \mathcal{A} \land \Sigma \ \mathcal{P} \times \ Q \ \mathcal{A} \land \textit{Final} \ \mathcal{A} \subseteq \ Q \ \mathcal{A} \land \textit{Control} \ \mathcal{P} \subseteq \ Q \ \mathcal{A} \end{array}$

For pushdown systems, I use the locale PS in order to fix a working pushdown system \mathcal{P} , this is easy because I have only one pushdown system to manage.

For automata on the other hand it would be harder to fix one because my important lemmas deal with several automata so I'm working outside from the locale PA but it nevertheless gives me a useful predicate PA which summarizes all finiteness constraints over the fields of my automata. For the small lemmas dealing with just one automaton, it would probably be cleaner to write everything in the locale itself.

The locale mechanism also surprisingly solved a typing problem: usually in abstract automata formalisations, it's quite hard to define what a regular set is. If we take the following definition

definition regular :: 'letter set \Rightarrow bool where regular $C \equiv (\exists (\mathcal{A} :: ('letter, 'state) automaton). C = \mathcal{L} \mathcal{A})$

then Isabelle complains because the type of the states of \mathcal{A} is unrelated to C so it cannot be inferred from the predicate argument.

Of course the type of the states of \mathcal{A} in this definition does not really matter unless it bounds the number of states, so a possible workaround is to impose a type in this definition of regular like this:

definition regular' :: 'letter set \Rightarrow bool where regular' $C \equiv (\exists (\mathcal{A} :: ('letter, nat) automaton). C = \mathcal{L} \mathcal{A})$

The difference between the two definitions is the use of *nat* instead of the type variable 'state. nat is not a type variable, it is the type of natural numbers defined in HOL standard library. This workaround however requires more work if we want to avoid forcing any implementation choice so we should prove a theorem like

theorem *arbitrary-state-type*:

 $\begin{array}{l} \forall \ (\mathcal{A} ::: ('letter, \ 'state) \ automaton). \\ \exists \ (\mathcal{A}' :: ('letter, \ nat) \ automaton). \\ \mathcal{L} \ \mathcal{A} = \mathcal{L} \ \mathcal{A}' \end{array}$

from which we finally can deduce simple facts like

corollary regular-language: $\forall (\mathcal{A} :: ('letter, 'state) automaton). regular' (<math>\mathcal{L} \mathcal{A}$) **by** (simp add: regular'-def arbitrary-state-type)

This is not very modular, it only works because there is a universal (independent of C) choice for the type variable 'state moreover an additionnal proof has to be supplied.

My definition of regularity is simply

definition myregular :: ('c, 's) config set \Rightarrow bool where myregular $C \equiv (\exists A. PA \mathcal{P} A \land C = \mathcal{L} A)$

It would work even if \mathcal{L} just returned a 's set as it usually does because all type variables of \mathcal{A} are fixed by those of \mathcal{P} , which is a constant in the locale context in which regularity is defined. In other words, I just define \mathcal{P} -regularity for which the typing issue of regularity does simply not exist.

Of course this magic is also limitating; the modelization of \mathcal{P} -automata in [1] does not force the set of states of \mathcal{P} -automata to be of the same type than *Control* \mathcal{P} but to provide for each \mathcal{P} -automaton \mathcal{A} a bijection between the set of initial states of \mathcal{A} and *Control* \mathcal{P} . This is not possible in my modelization.

3.3 Typeclass for Fresh Copy

I needed to be able to add fresh states to my automata so I formalized the notion of a type 'a together with a copy function which take two arguments of type 'a set, assumed to be finite, the source to copy source and a set of forbidden values forbidden and returns a function f of type ' $a \Rightarrow 'a$ such that f is injective on source and the image of source under f is disjoint from source \cup forbidden.

Isabelle provides a mecanism to define types together with constants and specifications, it is borrowed from Haskell and called a typeclass.

class copy =fixes copy-function :: 'a set \Rightarrow 'a set \Rightarrow ('a \Rightarrow 'a) assumes finite-copy: [finite forbidden; finite source]] \Rightarrow ((copy-function forbidden source) 'source \cap (source \cup forbidden) = \emptyset) \land inj-on (copy-function forbidden source) source

A typeclasses is simultaneously a kind of type for types together with a locale; it is possible to work in a context named *copy* exactly as if *copy* had been defined as a locale and it is enough to mark a type variable by the typeclass like this: a :: copy to assume that a is an instance of the typeclass and get access to the defined constants, assumptions and lemmas proved in the context. so in fact the real definition of the record for automata is

record ('c :: copy, 's) P-automaton = Q :: 'c set δ :: ('c * 's * 'c) set Final :: 'c set

For practical use, typeclasses are instanciated. When defining a typeclass in Isabelle, it is good to provide one explicit instatiation or to prove it to be a superclass of some nonempty typeclass.

The typeclass *copy* can be instanciated by any infinite type but I only proved *nat* to be an instance of it. This does not force the user to implement automata which use *nat* for state type, he just has to provide a proof that his state type is an instance of the typeclass *copy* i.e. to give an explicit *copy-function* for his type and to prove it to be conform to the corresponding *finite-copy* specification.

4 My Certification

My certification of the algorithm for computing pre^* for regular sets of configurations is essentially an adaptation of Stefan Swoon's proof [6].

4.1 Non-determinist Abstract Algorithm

There are to main limitations to the computability of my algorithm which explain why I can not run it on an example (which would nicely decorate this report but also be very interesting for a practical point of view for applications of my certification).

The first reason is that I use Isabelle built-in *set* types to represent sets and taking an element of a set is not a deterministic action.

The second reason is that my algorithm (the saturation procedure) is in essence not deterministic. Let's look at the rule again:

If
$$(p, \gamma) \hookrightarrow (p', w)$$
 is a rule of \mathcal{P} and $p' \xrightarrow{w}_{\mathcal{A}} q$,
then add a transition $p \xrightarrow{\gamma}_{\mathcal{A}} q$.

It does not tell us in what order new transitions should be added and in fact efficiency of the different implementations is very dependent on the way matching (p, γ, p', w, q) tuples are found.

The way I defined it should be compatible with all possible implementations; I defined it as a transition $\mathcal{A} \mapsto \mathcal{A}'$ if and only if \mathcal{A}' can be obtain from \mathcal{A} by applying the saturation rule exactly once:

$$\begin{array}{c} \mathcal{A} \mapsto \mathcal{A} \ (\!\!| \delta := \textit{insert} \ (p, \ \gamma, \ q) \ (\delta \ \mathcal{A}) |\!\!| \equiv \\ \exists \ p \ p' \ q \ \gamma \ w. \ PA \ \mathcal{P} \ \mathcal{A} \land p \in \textit{Control} \ \mathcal{P} \land \gamma \in \Sigma \ \mathcal{P} \land q \in Q \ \mathcal{A} \land p' \in \\ \textit{Control} \ \mathcal{P} \land (p, \ \gamma) \hookrightarrow (p', \ w) \land p' \xrightarrow{w}_{\mathcal{A}} q \land (p, \ \gamma, \ q) \notin \delta \ \mathcal{A} \end{array}$$

4.2 Contrast Between Proofs for Humans and Proofs for Computers

4.2.1 Inductive Principles

In Isabelle, every inductive definition automatically produces a set of inductive principles which are in practise more convenient to use than comming back to induction on the size (or length) of the object we are studying. This contrasts with pen-and-paper proofs for which inductions are often done on natural numbers. For example, the following piece of proof from [6]:

Lemma 3.1 For every configuration $(p, v) \in \mathcal{L} \mathcal{A}$, if $(p', w) \Rightarrow^* (p, v)$ then $p' \xrightarrow{w}_{\mathcal{A}'} q$ for some final state q of \mathcal{A}' . **Proof:** Assume $(p', w) \Rightarrow^k (p, v)$. We proceed by induction on k.

becomes

```
lemma Lemma3-1:

assumes PA \mathcal{P} \mathcal{A}

assumes \mathcal{A} \mapsto * \mathcal{A}'

assumes sat \mathcal{A}'

assumes (p', w) \Rightarrow * (p, v)

assumes (p, v) \in \mathcal{L} \mathcal{A}

shows \exists q \in PA-rec. Final \mathcal{A}'. \mathcal{A}' \vdash p' - w \rightarrow * q

using assms(4)

proof (induct rule: converse-rtrancl-induct2)
```

in my Isabelle formalisation. This means that I am doing a proof using the following induction principle (defined in Isabelle library):

$$\frac{a \Rightarrow^* b \qquad P b \qquad \bigwedge y \ z. \ \frac{y \Rightarrow z \qquad z \Rightarrow^* b \qquad P \ z}{P \ y}}{P \ y}$$

from assumption number $4: (p', w) \Rightarrow^* (p, v)$.

4.2.2 "Without loss of generality, we assume that \mathcal{A} has no transition leading to an initial state"

This sentence (from [6], page 32), is perfectly fine in a scientific article, this assumption sounds very reasonable and I think it is despite I spent one month proving it.

"Without loss of generality"-properties are evil for theorem proving. For this one, I had to write an algorithm for converting any automaton \mathcal{A} to an automaton \mathcal{A}' recognizing the same language and having no transition leading to an initial state. Once again, this is not very hard to find and prove with pen and paper but it takes one third of my code file (see the appendix). The idea is to get a copy of all initial states, use the read letter as a bridge to this parallel universe and stay in it until the end of input. Formally, I do this by this function: $\begin{array}{l} \textit{double-init } \mathcal{A} = \\ (|Q = Q \ \mathcal{A} \cup \textit{fcopy } \mathcal{A} \ `\textit{Control } \mathcal{P}, \\ \Delta = \{(p, \ \gamma, \ \textit{gcopy } \mathcal{A} \ q) \mid (p, \ \gamma, \ q) \in \delta \ \mathcal{A} \land p \in \textit{Control } \mathcal{P}\} \cup \\ \{(\textit{gcopy } \mathcal{A} \ q, \ \gamma, \ \textit{gcopy } \mathcal{A} \ q') \mid (q, \ \gamma, \ q') \in \delta \ \mathcal{A}\}, \\ \textit{Final} = \textit{Final } \mathcal{A} \cup \textit{gcopy } \mathcal{A} \ `\textit{Final } \mathcal{A}| \end{array}$

The first line extends the set of states by a fresh copy of initial states (this is the reason why I needed to formalize the notion of fresh copy), *fcopy* is the fresh function injective on *Control* \mathcal{P} and avoiding $Q \mathcal{A}$: *fcopy* $\mathcal{A} = fresh-copy$ ($Q \mathcal{A}$) (*Control* \mathcal{P}). The function *gcopy* is *fcopy* extended to all $Q \mathcal{A}$ by identity on non initial states, this is the translation the parallel universe.

The second line is the "bridge" part and the third line the "parallel" part. The last line is not simply $Final = gcopy \mathcal{A}$ ' $Final \mathcal{A}$ as one could think because we have to deal with the empty word which is too short to access the parallel universe.

And then the real proofs begin... By the way, avoiding to have to add knew states (even one by one which gives simpler proofs) is exactly what makes the certification (termination and correctness) of the algorithm computing pre^* easier than the one computing $post^*$ so at least all this work can help adapting my work to the certification for $post^*$.

5 Conclusion

A lot of work is still to be done on this subject. To adapt it to $post^*$ should not be very difficult now I have formalised the notion of fresh copy and research on data refinement is very active so I'm sure that my code will soon be able to certify real implementations without too much efforts. It then could be generalized to a lot of other classes of sets of configurations for cases where the set we want to compute reachability for is not regular because proofs for other classes of sets are seldom very different from the one for regular sets.

6 Acknowledgement

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A Source code

theory Pushdown-systems imports Main begin

type-synonym 'a rel = ('a * 'a) set — relation type synonym

abbreviation epsilon :: 'a list (ε) **where** $\varepsilon \equiv []$ — strings are implemented by lists, the empty word is denoted by ε

A.1 Fresh Function and Copy

We will need to add fresh states to automata, for this purpose we define a class of types enriched with a copy functions wich returns finitely many fresh elements.

class fresh = fixes fresh-copy :: 'a set \Rightarrow 'a set \Rightarrow ('a \Rightarrow 'a) assumes finite-fresh-copy: [finite forbidden-set; finite B] \Longrightarrow ((fresh-copy forbidden-set B) 'B \cap (B \cup forbidden-set) = {}) \wedge inj-on (fresh-copy forbidden-set B) B

begin end

Any infinite type is a member of this class but for our purpose, using *nat* will be enough.

instantiation nat :: freshbegin definition $supnat :: nat set \Rightarrow nat$ where supnat A = fold max 0 A

lemma sup: finite $A \Longrightarrow x \in A \Longrightarrow x \leq$ supnat A unfolding supnat-def max-def by (induct A rule: Finite-Set.finite-induct) auto

definition fresh-copy-def: fresh-copy forbidden-set $B \ k = 1 + supnat$ (forbidden-set $\cup B$) + k

instance proof

fix forbidden-set B :: nat set assume finite: finite forbidden-set finite Blet ?n = 1 + supnat (forbidden-set $\cup B$) have $[simp]: \bigwedge k$. fresh-copy forbidden-set $B \ k = ?n + k$

by (*auto simp*: *fresh-copy-def*) **show** fresh-copy forbidden-set $B \, B \cap (B \cup forbidden-set) = \{\} \land$ inj-on (fresh-copy forbidden-set B) B **proof** (*auto simp: inj-on-def*) fix kassume Suc (supnat (forbidden-set $\cup B$) + k) $\in B$ hence $?n + k \in B$ by simp hence ?n + k < ?n using finite $sup[of forbidden-set \cup B ?n + k]$ by simp thus False by simp next fix kassume Suc (supnat (forbidden-set $\cup B$) + k) \in forbidden-set hence $?n + k \in forbidden$ -set by simp hence ?n + k < ?n using finite $sup[of forbidden-set \cup B ?n + k]$ by simpthus False by simp qed qed end

A.2 Pushdown Systems

Pushdown systems are transition systems over a finite set of control symbols using an unbounded stack. A configuration of a pushdown systemm is given by a control symbol and a string of stack symbols.

type-synonym ('c, 's) $config = 'c * 's \ list$

Without loss of generality, we consider pushdown systems which pop one symbol and push at most two symbols; this would be useful for $post^*$.

c stands for control symbol and s for stack symbol.

record ('c :: fresh, 's) PS-rec = $\Delta_0 :: ('c * 's * 'c) set$ $\Delta_1 :: ('c * 's * 'c * 's) set$ $\Delta_2 :: ('c * 's * 'c * 's * 's) set$ Initial :: ('c, 's) config $\Sigma :: 's set$ Control :: 'c set

A.3 Transitions in a Pushdown System

Membership and finiteness constraints are expressed by the following locale in wich all interesting work is going to be done.

locale PS = **fixes** $\mathcal{P} :: ('c :: fresh, 's) PS$ -rec **assumes** finite ($\Sigma \mathcal{P}$) **and** finite (Control \mathcal{P}) **and** $\Delta_0 \mathcal{P} \subseteq Control \mathcal{P} \times \Sigma \mathcal{P} \times Control \mathcal{P}$ **and** $\Delta_1 \mathcal{P} \subseteq Control \mathcal{P} \times \Sigma \mathcal{P} \times Control \mathcal{P} \times \Sigma \mathcal{P}$ and $\Delta_2 \mathcal{P} \subseteq Control \mathcal{P} \times \Sigma \mathcal{P} \times Control \mathcal{P} \times \Sigma \mathcal{P} \times \Sigma \mathcal{P}$ begin

fun PS-rule :: $('c * 's) \Rightarrow ('c, 's) \text{ config} \Rightarrow \text{bool}$ (infix $\hookrightarrow 100$) where $(p, \gamma) \hookrightarrow (p', \varepsilon) = ((p, \gamma, p') \in \Delta_0 \mathcal{P})$ $\mid (p, \gamma) \hookrightarrow (p', [\gamma']) = ((p, \gamma, p', \gamma') \in \Delta_1 \mathcal{P})$ $\mid (p, \gamma) \hookrightarrow (p', [\gamma_1, \gamma_2]) = ((p, \gamma, p', \gamma_1, \gamma_2) \in \Delta_2 \mathcal{P})$ $\mid (p, \gamma) \hookrightarrow (p', -) = False$

lemma *PS*-rule-mem-constraints[intro, dest]: **assumes** $(p, \gamma) \hookrightarrow (p', w)$ **shows** $p \in Control \mathcal{P} \ \gamma \in \Sigma \mathcal{P} \ p' \in Control \mathcal{P} \ set \ w \subseteq \Sigma \mathcal{P}$ using assms and *PS*-axioms

by (cases rule: PS-rule.cases[of $((p, \gamma), (p', w))$], auto simp: PS-def)+

A.3.1 Definition

 $\begin{array}{l} \textbf{definition} \ PS\text{-}transition\text{-}rel :: ('c, \ 's) \ config \ rel\\ \textbf{where}\\ PS\text{-}transition\text{-}rel \equiv\\ \{((p, \ \gamma \ \# \ w), \ (p', \ w' \ @ \ w)) \ | \ p \ \gamma \ w \ p' \ w'.\\ set \ w \subseteq \Sigma \ \mathcal{P} \ \land \ set \ w' \subseteq \Sigma \ \mathcal{P} \ \land \ (p, \ \gamma) \hookrightarrow \ (p', \ w') \} \end{array}$

abbreviation *PS-transition-frel* :: ('c, 's) $config \Rightarrow ('c, 's) config \Rightarrow bool$ (infix $\Rightarrow 100$) where

 $c \Rightarrow c' \equiv (c, c') \in PS$ -transition-rel

A.3.2 Properties

lemma *PS*-transition-append[intro]: $(p, w) \Rightarrow (p', w') \Longrightarrow set \ u \subseteq \Sigma \ \mathcal{P} \Longrightarrow (p, w @ u) \Rightarrow (p', w' @ u)$ **by** (auto simp: *PS*-transition-rel-def)

lemma *PS*-transition-rel-mem-constraints[intro]: **assumes** $(p, w) \Rightarrow (p', w')$ **shows** $p \in Control \mathcal{P}$ set $w \subseteq \Sigma \mathcal{P} \ p' \in Control \mathcal{P}$ set $w' \subseteq \Sigma \mathcal{P}$ using assms **by** (auto simp: PS-transition-rel-def)

abbreviation *PS*-transition-tr :: ('c, 's) config \Rightarrow ('c, 's) config \Rightarrow bool (infix $\Rightarrow * 100$) where $c \Rightarrow * c' \equiv (c, c') \in PS$ -transition-rel ^*

notation *PS*-transition-tr (infixl $\Rightarrow^* 100$)

lemma *rtrancl-f*[*intro*]: **assumes** $\bigwedge a \ b. \ (a, \ b) \in r \implies (f \ a, \ f \ b) \in r$ **shows** $(a, \ b) \in r^* \implies (f \ a, \ f \ b) \in r^**$ **apply** (*induct rule: rtrancl-induct*) **using** assms **by** simp-all fastsimp

lemma rtrancl-f-2[intro]: **assumes** $\bigwedge a \ a' \ b \ b'$. ((a, a'), (b, b')) $\in r \implies ((f \ a, f' \ a'), (f \ b, f' \ b')) \in r$ **shows** ((a, a'), (b, b')) $\in r^* \implies ((f \ a, f' \ a'), (f \ b, f' \ b')) \in r^*$ **using** assms and rtrancl-f[where $f = \lambda \ (a, a')$. (f a, f' a')] by auto

lemma *PS*-transition-tr-append[intro]: **assumes** set $u \subseteq \Sigma \mathcal{P}$ **shows** $(p, w) \Rightarrow * (p', w') \Longrightarrow (p, w @ u) \Rightarrow * (p', w' @ u)$ **using** assms **by** auto

```
lemma PS-transition-tr-mem-constraints[intro]:

assumes (p, w) \Rightarrow * (p', w')

and p \in Control \mathcal{P}

shows p' \in Control \mathcal{P} using assms

by (induct rule: rtrancl-induct2) auto
```

```
lemma PS-transition-tr-rev-mem-constraints[intro]:

assumes (p, w) \Rightarrow * (p', w')

and p' \in Control \mathcal{P}

shows p \in Control \mathcal{P} using assms

by (induct rule: rtrancl-induct2) auto
```

A.3.3 The set $pre^* C$

 $\begin{array}{l} \textbf{definition } prestar :: ('c, 's) \ config \ set \Rightarrow ('c, \ 's) \ config \ set \\ (pre* - [101] \ 100) \\ \textbf{where } pre* \ C = \{c. \ (\exists \ c' \in C. \ c \Rightarrow * \ c')\} \end{array}$

notation prestar (pre* 1000)

definition poststar :: ('c, 's) config set \Rightarrow ('c, 's) config set (post* - [101] 100) where post* $C = \{c. (\exists c' \in C. c' \Rightarrow * c)\}$

notation poststar (post* 1000)

 \mathbf{end}

A.4 \mathcal{P} -Automata

 $\mathcal P\text{-}automata$ are word automata which recognize sets of configuations of the fixed pushdown system $\mathcal P$

record ('c :: fresh, 's) PA-rec = Q :: 'c set Δ :: ('c * 's * 'c) set Final :: 'c set **locale** PA = **fixes** $\mathcal{P} :: ('c :: fresh, 's) PS$ -rec **fixes** $\mathcal{A} :: ('c, 's) PA$ -rec **assumes** $PS \mathcal{P}$ **assumes** finite $(Q \mathcal{A})$ **assumes** $\Delta \mathcal{A} \subseteq Q \mathcal{A} \times \Sigma \mathcal{P} \times Q \mathcal{A}$ **assumes** Final $\mathcal{A} \subseteq Q \mathcal{A}$ **assumes** Control $\mathcal{P} \subseteq Q \mathcal{A}$

lemma *PA-Control*[*intro*]: $[\![PA \ \mathcal{P} \ \mathcal{A}; p \in Control \ \mathcal{P}]\!] \Longrightarrow p \in Q \ \mathcal{A}$ by (*auto simp*: *PA-def*) **lemma** *PA-Final*[*intro*]: $[\![PA \ \mathcal{P} \ \mathcal{A}; q \in Final \ \mathcal{A}]\!] \Longrightarrow q \in Q \ \mathcal{A}$ by (*auto simp*: *PA-def*)

A.4.1 Recognition and language

abbreviation delta1 :: ('c :: fresh, 's) PA-rec \Rightarrow 'c \Rightarrow 's \Rightarrow 'c \Rightarrow bool (- \vdash - -- \Rightarrow - [101, 0, 0, 101] 100) where $\mathcal{A} \vdash q - a \rightarrow q' \equiv (q, a, q') \in \Delta \mathcal{A}$

lemma delta1-mem-constraints[intro, dest]: **assumes** $PA \mathcal{P} \mathcal{A}$ **and** $\mathcal{A} \vdash q - a \rightarrow q'$ **shows** $q \in Q \mathcal{A} \ a \in \Sigma \mathcal{P} \ q' \in Q \mathcal{A}$ **using** assms **by** (auto simp: PA-def)

inductive delta :: ('c :: fresh, 's) PA-rec \Rightarrow 'c \Rightarrow 's list \Rightarrow 'c \Rightarrow bool where base[iff]: $q \in Q \ A \Longrightarrow$ delta $\ A \ q \ \varepsilon \ q \ |$ step[intro]: [[delta1 $\ A \ q \ a \ q'$; delta $\ A \ q' \ w \ q''$] \Longrightarrow delta $\ A \ q \ (a \# w) \ q''$

notation delta $(- \vdash - - \rightarrow * - [101, 0, 0, 101] 100)$

lemma delta-mem-constraints[rule-format, intro]: $\mathcal{A} \vdash q - w \rightarrow * q' \Longrightarrow PA \mathcal{P} \mathcal{A} \longrightarrow (q \in Q \mathcal{A} \land q' \in Q \mathcal{A})$ **by** (induct rule: delta.induct) auto **lemma** delta-word-mem-constraints[rule-format, intro]: $\mathcal{A} \vdash q - w \rightarrow * q' \Longrightarrow PA \mathcal{P} \mathcal{A} \longrightarrow set w \subseteq \Sigma \mathcal{P}$ **by** (induct rule: delta.induct) auto

inductive-cases delta-epsilon[elim]: $\mathcal{A} \vdash q -\varepsilon \rightarrow * q'$ lemma delta-epsilon-iff[iff]: $(\mathcal{A} \vdash q -\varepsilon \rightarrow * q') = (q \in Q \ \mathcal{A} \land q = q')$ by blastinductive-cases delta-single[elim]: $\mathcal{A} \vdash q - [a] \rightarrow * q'$

 $\textbf{lemma} \ \textit{delta-single2[simp]: PA } \mathcal{P} \ \mathcal{A} \Longrightarrow \mathcal{A} \vdash q \ -[a] \rightarrow * q' \longleftrightarrow \mathcal{A} \vdash q \ -a \rightarrow q'$

by *auto* inductive-cases delta-cons[elim]: $\mathcal{A} \vdash q - a \# w \rightarrow * q'$ lemma delta-cons-dest[dest]: $\mathcal{A} \vdash q - a \# w \rightarrow * q'' \Longrightarrow (\exists q'. \mathcal{A} \vdash q - a \rightarrow q' \land \mathcal{A}$ $\vdash q' - w \rightarrow \ast q'')$ **by** blast **lemma** delta-append[intro]: $[\mathcal{A} \vdash q - u \rightarrow * q'; \mathcal{A} \vdash q' - v \rightarrow * q''] \implies \mathcal{A} \vdash q$ $-u@v \rightarrow * q''$ **by** (*induct u arbitrary: q*) (*auto, fast*) **lemma** *delta-append-elim*[*elim*]: $\llbracket \mathcal{A} \vdash q - u @v \to * q''; \land q'. \llbracket \mathcal{A} \vdash q - u \to * q'; \mathcal{A} \vdash q' - v \to * q'' \rrbracket \Longrightarrow P; PA \mathcal{P} \mathcal{A};$ $q \in Q \mathcal{A} \implies P$ **proof** (*induct* u *arbitrary*: q P) fix q'**case** (Cons a u) then obtain qa where $\mathcal{A} \vdash q - a \rightarrow qa$ and $\mathcal{A} \vdash qa - u@v \rightarrow *q''$ by *auto* with Cons obtain q' where $\mathcal{A} \vdash qa - u \rightarrow *q'$ and $\mathcal{A} \vdash q' - v \rightarrow *q''$ by auto from $\langle \mathcal{A} \vdash q \ -a \rightarrow qa \rangle \langle \mathcal{A} \vdash qa \ -u \rightarrow qa' \rangle$ have $\mathcal{A} \vdash q \ -a \# u \rightarrow qa'$. with $\langle \mathcal{A} \vdash q' - v \rightarrow * q'' \rangle$ Cons(3) show ?case by auto qed simp

context PS begin

definition language ::: ('c :: fresh, 's) $PA\text{-}rec \Rightarrow$ ('c, 's) config set (\mathcal{L}) where $\mathcal{L} \ \mathcal{A} \equiv \{(p, w). \exists q \in Final \ \mathcal{A}. \ p \in Control \ \mathcal{P} \land \mathcal{A} \vdash p - w \rightarrow * q\}$

lemma language-intro[intro]: $[p \in Control \mathcal{P}; \mathcal{A} \vdash p - w \rightarrow * q; q \in Final \mathcal{A}]] \Longrightarrow (p, w) \in \mathcal{L} \mathcal{A}$ **by** (auto simp: language-def) **lemma** language-elim[elim]: **fixes** \mathcal{A} **assumes** $(p, w) \in \mathcal{L} \mathcal{A}$ **obtains** q where $p \in Control \mathcal{P}$ and $\mathcal{A} \vdash p - w \rightarrow * q$ and $q \in Final \mathcal{A}$ **using** assms by (auto simp: language-def)

definition regular :: ('c, 's) config set \Rightarrow bool **where** regular (C :: ('c, 's) config set) $\equiv \exists \mathcal{A} :: ('c, 's) PA$ -rec. PA $\mathcal{P} \mathcal{A} \land C = \mathcal{L} \mathcal{A}$

A.5 Saturation Procedure

This is the saturation procedure to transform an automaton \mathcal{A} recognizing a language C into an automaton recognizing $pre^* C$: For every rule (p, γ) $\hookrightarrow (p', w)$, take q such that $\mathcal{A} \vdash p' - w \rightarrow * q$ and add a transition (p, γ, q) if it's not already present.

A.5.1 Definition

 $\begin{array}{l} \textbf{definition } pre\text{-sat-rel} :: ('c, 's) \ PA\text{-rec rel} \\ \textbf{where } pre\text{-sat-rel} = \{(\mathcal{A}, \ \mathcal{A} \ (|\Delta := \textit{insert} \ (p, \ \gamma, \ q) \ (\Delta \ \mathcal{A})|)) \mid \mathcal{A} \ p \ p' \ q \ \gamma \ w. \\ PA \ \mathcal{P} \ \mathcal{A} \land p \in \textit{Control} \ \mathcal{P} \land \gamma \in \Sigma \ \mathcal{P} \land q \in Q \ \mathcal{A} \land p' \in \textit{Control} \ \mathcal{P} \land \\ (p, \ \gamma) \hookrightarrow (p', \ w) \land \\ \mathcal{A} \vdash p' - w \rightarrow \ast q \land \\ \neg \ \mathcal{A} \vdash p \ -\gamma \rightarrow q \} \end{array}$

abbreviation pre-sat-frel :: ('c, 's) PA-rec \Rightarrow ('c, 's) PA-rec \Rightarrow bool (infix \mapsto 100) where $\mathcal{A} \mapsto \mathcal{A}' \equiv (\mathcal{A}, \mathcal{A}') \in pre\text{-sat-rel}$

lemma pre-sat-PA[intro]: **assumes** $\mathcal{A} \mapsto \mathcal{A}'$ **shows** PA \mathcal{P} \mathcal{A} and PA \mathcal{P} \mathcal{A}' **using** assms and PS-axioms **by** (auto simp: pre-sat-rel-def PA-def)

abbreviation pre-sat-tr :: ('c, 's) PA-rec \Rightarrow ('c, 's) PA-rec \Rightarrow bool (infix $\mapsto *$ 100)

where $\mathcal{A} \mapsto \mathcal{A}' \equiv (\mathcal{A}, \mathcal{A}') \in pre\text{-sat-rel}^*$

notation pre-sat-tr (infix $\mapsto^* 100$)

A.5.2 Invariants

lemma pre-sat-tr-PA[rule-format, dest]: $\mathcal{A} \mapsto * \mathcal{A}' \Longrightarrow PA \mathcal{P} \mathcal{A} \longrightarrow PA \mathcal{P} \mathcal{A}'$ **by** (induct rule: rtrancl-induct) auto **lemma** pre-sat-Q[dest]: $\mathcal{A} \mapsto \mathcal{A}' \Longrightarrow Q \mathcal{A} = Q \mathcal{A}'$ **by** (auto simp: pre-sat-rel-def) **lemma** pre-sat-delta1: $[\mathcal{A} \vdash q - a \rightarrow q'; \mathcal{A} \mapsto \mathcal{A}'] \Longrightarrow \mathcal{A}' \vdash q - a \rightarrow q'$ **by** (auto simp: pre-sat-rel-def) **lemma** pre-sat-delta: $[\mathcal{A} \vdash q - w \rightarrow * q'; \mathcal{A} \mapsto \mathcal{A}'] \Longrightarrow \mathcal{A}' \vdash q - w \rightarrow * q'$ **by** (induct rule: delta.induct) (auto elim: pre-sat-delta1) **lemma** pre-sat-final: $\mathcal{A} \mapsto \mathcal{A}' \Longrightarrow Final \mathcal{A} = Final \mathcal{A}'$ **by** (auto simp: pre-sat-rel-def)

lemma pre-sat-Delta: **assumes** $\mathcal{A} \mapsto \mathcal{A}'$ **obtains** $p \ \gamma \ q$ where $\Delta \ \mathcal{A}' = insert \ (p, \ \gamma, \ q) \ (\Delta \ \mathcal{A}) \ \neg \ \mathcal{A} \vdash p \ -\gamma \rightarrow q$ using assms by (auto simp: pre-sat-rel-def)

lemma pre-sat-L: $\mathcal{A} \mapsto \mathcal{A}' \Longrightarrow \mathcal{L} \ \mathcal{A} \subseteq \mathcal{L} \ \mathcal{A}'$ by (auto elim: pre-sat-delta simp: pre-sat-final language-def)

lemma pre-sat-tr-final[dest]: $\mathcal{A} \mapsto \mathcal{A}' \Longrightarrow$ Final $\mathcal{A} =$ Final \mathcal{A}' by (induct rule: rtrancl-induct) (auto dest: pre-sat-final) **lemma** pre-sat-tr-L[dest]: $\mathcal{A} \mapsto \mathcal{A}' \Longrightarrow \mathcal{L} \mathcal{A} \subseteq \mathcal{L} \mathcal{A}'$ apply (induct rule: rtrancl-induct) apply simp using pre-sat-L by blast

A.5.3 Saturated Automata

definition sat where sat $\mathcal{A} \equiv (PA \mathcal{P} \mathcal{A} \land \neg (\exists \mathcal{A}'. \mathcal{A} \mapsto \mathcal{A}'))$ lemma sat-iff: sat $\mathcal{A} = (PA \mathcal{P} \mathcal{A} \land ($ $\forall p \in Control \mathcal{P}.$ $\forall \gamma \in \Sigma \mathcal{P}.$ $\forall p' \in Control \mathcal{P}.$ $\forall q \in Q \mathcal{A}.$ $\forall w.$ $(p, \gamma) \hookrightarrow (p', w) \land \mathcal{A} \vdash p' - w \rightarrow * q \longrightarrow \mathcal{A} \vdash p - \gamma \rightarrow q))$ unfolding sat-def pre-sat-rel-def by blast

lemma sat-iff-nomem[iff]: PA $\mathcal{P} \ \mathcal{A} \Longrightarrow$ sat $\mathcal{A} = (\forall p \ \gamma p' w. \forall q \in Q \ \mathcal{A}. (p, \gamma)$ $<math>\hookrightarrow (p', w) \land \mathcal{A} \vdash p' - w \rightarrow * q \longrightarrow \mathcal{A} \vdash p - \gamma \rightarrow q)$ using sat-iff by blast — same lemma but without all implicit membership constraints

A.6 Certification of the saturation procedure

A.6.1 No Transition Should Lead to an Initial State

definition init-no-income :: ('c, 's) PA-rec \Rightarrow bool **where** init-no-income $\mathcal{A} \equiv (\forall q \in Q \ \mathcal{A}. \forall \gamma \in \Sigma \ \mathcal{P}. \forall p \in Control \ \mathcal{P}. \neg \mathcal{A} \vdash q \ -\gamma \rightarrow p)$

lemma init-no-income-elim: **assumes** $\mathcal{A} \vdash q - \gamma \rightarrow p$ $PA \mathcal{P} \mathcal{A}$ $p \in Control \mathcal{P}$ init-no-income \mathcal{A} **shows** P **using** assms **by** (auto simp: init-no-income-def PA-def)

We now show that this further assumption doesn't limit the power of the automata, given an automaton \mathcal{A} , we construct an equivalent automaton \mathcal{A}' satisfying this condition

```
definition fcopy \mathcal{A} = fresh-copy (Q \ \mathcal{A}) (Control \mathcal{P})

lemma fsimp:

fixes q

assumes q \in Control \ \mathcal{P}

and fcopy \mathcal{A} \ q \in Control \ \mathcal{P}

and PA \ \mathcal{P} \ \mathcal{A}

shows False

proof -

from assms(1,2) have fcopy \mathcal{A} \ q \in fresh-copy (Q \ \mathcal{A}) (Control \mathcal{P}) ' Control \mathcal{P}

\cap (Control \mathcal{P} \cup Q \ \mathcal{A})

by (auto simp: fcopy-def)

with assms(3) finite-fresh-copy show False by (auto simp: PA-def PS-def)

qed
```

definition gcopy $\mathcal{A} q = (if q \in Control \mathcal{P} then fcopy \mathcal{A} q else q)$

lemma gsimp: fixes q assumes $q \in Q \ A$ and gcopy $A \ q \in Control \ P$ and $PA \ P \ A$ shows False using assms by (cases $q \in Control \ P$) (auto simp: gcopy-def dest: fsimp)

 $\begin{array}{l} \textbf{definition } \textit{double-init } \mathcal{A} = (\\ Q = Q \ \mathcal{A} \cup \textit{fcopy } \mathcal{A} \ `(\textit{Control } \mathcal{P}), \\ \Delta = \\ \{(p, \gamma, \textit{gcopy } \mathcal{A} \ q) \mid p \ \gamma \ q. \ (p, \gamma, q) \in \Delta \ \mathcal{A} \land p \in \textit{Control } \mathcal{P}\} \cup \\ \{(\textit{gcopy } \mathcal{A} \ q, \gamma, \textit{gcopy } \mathcal{A} \ q') \mid q \ \gamma \ q'. \ (q, \gamma, q') \in \Delta \ \mathcal{A}\}, \\ \textit{Final} = \textit{Final } \mathcal{A} \cup \textit{gcopy } \mathcal{A} \ `(\textit{Final } \mathcal{A})) \end{array}$

lemma *double-init-Q-sub*: $Q \mathcal{A} \subseteq Q$ (double-init \mathcal{A}) by (auto simp: double-init-def) **lemma** g-copy-Q: $q \in Q \ \mathcal{A} \Longrightarrow gcopy \ \mathcal{A} \ q \in Q \ (double-init \ \mathcal{A})$ **by** (*auto simp: double-init-def gcopy-def fcopy-def*) **lemma** inj-on-f: PA $\mathcal{P} \ \mathcal{A} \Longrightarrow$ inj-on (fcopy \mathcal{A}) (Control \mathcal{P}) **by** (*auto simp: finite-fresh-copy fcopy-def PA-def PS-def*) lemma *fsimp2*: fixes $\mathcal{A} p$ assumes $A: PA \mathcal{P} \mathcal{A}$ assumes $p: p \in Control \mathcal{P}$ assumes $f: fcopy \ \mathcal{A} \ p \in Q \ \mathcal{A}$ shows False proof **from** p f have fcopy $\mathcal{A} p \in fcopy \mathcal{A}$ 'Control $\mathcal{P} \cap (Q \mathcal{A} \cup Control \mathcal{P})$ by simp with finite-fresh-copy A show False by (auto simp: PA-def PS-def fcopy-def) qed **lemma** inj-on-g: PA $\mathcal{P} \mathcal{A} \Longrightarrow$ inj-on (gcopy \mathcal{A}) (Q \mathcal{A}) **by** (*auto simp: inj-on-def gcopy-def dest: inj-on-f fsimp2*) lemma PA-double-init: fixes \mathcal{A} assumes $PA \mathcal{P} \mathcal{A}$ shows $PA \mathcal{P}$ (double-init \mathcal{A}) using assms by (auto simp: double-init-def gcopy-def fcopy-def PA-def PS-def) **lemma** *double-init-no-income*:

fixes \mathcal{A} assumes $PA \mathcal{P} \mathcal{A}$ assumes double-init $\mathcal{A} \vdash p - \gamma \rightarrow q$ shows $q \notin Control \mathcal{P}$

using assms **by** (*auto simp: double-init-def dest: gsimp*) lemma delta1-double-init: fixes \mathcal{A} assumes $\mathcal{A} \vdash q - \gamma \rightarrow q'$ shows double-init $\mathcal{A} \vdash gcopy \ \mathcal{A} \ q \ -\gamma \rightarrow gcopy \ \mathcal{A} \ q'$ using assms by (auto simp: double-init-def) lemma delta-double-init: fixes \mathcal{A} assumes $PA \mathcal{P} \mathcal{A}$ assumes $\mathcal{A} \vdash p - w \rightarrow * q$ **shows** double-init $\mathcal{A} \vdash gcopy \ \mathcal{A} \ p - w \rightarrow \ast gcopy \ \mathcal{A} \ q$ using assms(2)**proof** (*induct rule: delta.induct*) case (base $q \mathcal{A}$) thus ?case by (auto simp: g-copy-Q) next case (step $\mathcal{A} q a q' w q''$) with delta1-double-init show ?case by fast qed **lemma** *delta-double-init-rev*: fixes Aassumes $PA \mathcal{P} \mathcal{A}$ assumes double-init $\mathcal{A} \vdash gcopy \ \mathcal{A} \ q \ -w \rightarrow \ast gcopy \ \mathcal{A} \ q'$ assumes $q \in Q \mathcal{A}$ and $q' \in Q \mathcal{A}$ — probably a consequence of the other assumptions but I find it easier like this shows $\mathcal{A} \vdash q - w \rightarrow \ast q'$ using assms(2,3,4)**proof** (*induct* w *arbitrary*: q) case Nil hence eq: gcopy $\mathcal{A} q = gcopy \mathcal{A} q'$ by simp with $\langle PA \ \mathcal{P} \ \mathcal{A} \rangle \langle q \in Q \ \mathcal{A} \rangle \langle q' \in Q \ \mathcal{A} \rangle$ have q = q' using *inj-on-g* unfolding inj-on-def by simp thus $\mathcal{A} \vdash q - \varepsilon \rightarrow q'$ using $\langle q \in Q \mathcal{A} \rangle$ by blast next case (Cons γ u) then obtain gq1 where γ : double-init $\mathcal{A} \vdash gcopy \ \mathcal{A} \ q \ -\gamma \rightarrow gq1$ and u: double-init $\mathcal{A} \vdash gq1 - u \rightarrow \ast gcopy \mathcal{A} q'$ by blast from $\gamma \langle q \in Q | A \rangle \langle PA | P | A \rangle$ obtain q1 where [simp]: gq1 = gcopy | A | q1 and $\gamma A: \mathcal{A} \vdash q - \gamma \rightarrow q1$ unfolding double-init-def **proof** (*auto dest: gsimp*) fix qq q'assume H [of q', simplified]: $\bigwedge q1$. [gcopy $\mathcal{A} q' = gcopy \mathcal{A} q1$; $\mathcal{A} \vdash q -\gamma \rightarrow$ $q1 \implies thesis$ and $q: q \in Q \mathcal{A}$ and $A: PA \mathcal{P} \mathcal{A}$

and $\gamma: \mathcal{A} \vdash qq - \gamma \rightarrow q'$ and eq: gcopy \mathcal{A} q = gcopy \mathcal{A} qq from eq A q γ inj-on-g have [simp]: q = qq unfolding inj-on-def by blast from $H \gamma$ show thesis by simp ged hence $[simp]: q1 \in Q \ \mathcal{A}$ using $\langle PA \ \mathcal{P} \ \mathcal{A} \rangle$ by blast from u[simplified] Cons have $\mathcal{A} \vdash q1 - u \rightarrow *q'$ by simp with γA show ?case by auto qed lemma double-init-L-1: fixes \mathcal{A} assumes $A: PA \mathcal{P} \mathcal{A}$ assumes $w: \mathcal{A} \vdash p - w \rightarrow * q$ assumes $p: p \in Control \mathcal{P}$ assumes $q: q \in Final \mathcal{A}$ **shows** $\exists q' \in Final (double-init A). double-init <math>A \vdash p - w \rightarrow * q'$ **proof** (cases w) case Nil note [simp] = thisfrom A q have $q \in Q \mathcal{A}$ by (auto simp: PA-def) hence $q \in Q$ (double-init A) by (auto simp: double-init-def) with A w p q show ?thesis by (simp add: double-init-def) \mathbf{next} case (Cons γ u) note [simp] = this { from w obtain q1 where $q: \mathcal{A} \vdash p - \gamma \rightarrow q1$ and $u: \mathcal{A} \vdash q1 - u \rightarrow q$ by auto from q have double-init $\mathcal{A} \vdash p - \gamma \rightarrow gcopy \mathcal{A}$ q1 using p unfolding double-init-def **by** (*auto simp*: *gcopy-def fcopy-def*) moreover from u delta-double-init A have double-init $\mathcal{A} \vdash gcopy \ \mathcal{A} \ q1 \ -u \rightarrow \ast gcopy \ \mathcal{A}$ q by simpultimately have double-init $\mathcal{A} \vdash p - \gamma \# u \rightarrow \ast gcopy \mathcal{A} q$ by fast } moreover from q have $q copy \mathcal{A} q \in Final$ (double-init \mathcal{A}) by (simp add: double-init-def) ultimately show ?thesis by auto qed **lemma** *double-init-g-inv*: fixes $\mathcal{A} q q'$ assumes $A: PA \mathcal{P} \mathcal{A}$ assumes double-init $\mathcal{A} \vdash gcopy \ \mathcal{A} \ q \ -w \rightarrow *q'$ assumes $q: q \in Q \mathcal{A}$ shows $\exists q'' \in Q \ A. q' = gcopy \ A q'' using assms(2,3)$ **proof** (*induct w arbitrary*: q) case Nil hence $q' = gcopy \mathcal{A} q$ by simp

```
with Nil(2) show ?case by blast
next
  case (Cons \gamma u)
  then obtain gq1 where
   \gamma: double-init \mathcal{A} \vdash gcopy \ \mathcal{A} \ g \neg \gamma \rightarrow gq1 and
   u: double-init \mathcal{A} \vdash gq1 - u \rightarrow * q' by blast
  from \gamma obtain q1 where [simp]: gq1 = gcopy \ \mathcal{A} \ q1 \ q1 \in Q \ \mathcal{A} unfolding
double-init-def
   using A by auto
  from u[simplified] Cons show ?case by simp
qed
lemma double-init-L-2:
 fixes \mathcal{A}
 assumes A: PA \mathcal{P} \mathcal{A}
 assumes w: double-init \mathcal{A} \vdash p - w \rightarrow * q
  assumes p: p \in Control \mathcal{P}
 assumes q: q \in Final (double-init A)
  shows \exists q' \in Final \mathcal{A}. \mathcal{A} \vdash p - w \rightarrow * q'
proof (cases w)
  case Nil note [simp] = this
  from A w p have q2: q \in Control \mathcal{P} q \in Q \mathcal{A} by (auto simp: PA-def)
  with A q gsimp[of q A] have q \in Final A
  proof (cases q \in Final \mathcal{A})
   case True thus ?thesis by assumption
  next
   case False then obtain q' where q = gcopy \mathcal{A} q' q' \in Final \mathcal{A}
      using q unfolding double-init-def by auto
   with w p A PA-Final have gcopy A q' \in Control \mathcal{P} q' \in Q A by auto
   hence False using A by (auto dest: gsimp)
   thus ?thesis by simp
  qed
  with w A show ?thesis by auto
\mathbf{next}
  case (Cons \gamma u) note [simp] = this
  from w obtain qq1 where \gamma: double-init \mathcal{A} \vdash p - \gamma \rightarrow qq1 and u: double-init
\mathcal{A} \vdash gq1 \quad -u \rightarrow * q
   by auto
  from \gamma A p gsimp obtain q1 where \gamma A: A \vdash p - \gamma \rightarrow q1 and [simp]: qq1 =
gcopy \mathcal{A} q1
   unfolding double-init-def by auto
  hence [simp]: q1 \in Q \ \mathcal{A} using A by blast
 from double-init-g-inv[OF A u[simplified]] obtain q' where [simp]: q' \in Q \ A \ q
= gcopy \mathcal{A} q' by auto
  from delta-double-init-rev[OF A u[simplified]] have uA: \mathcal{A} \vdash q1 - u \rightarrow *q' by
simp
  moreover
  have q' \in Final \mathcal{A}
 proof –
```

```
{
      assume q \in Final \mathcal{A}
      hence q \in Q \mathcal{A} using A by auto
      with A have q' \notin Control \mathcal{P} by (auto simp: gcopy-def dest: fsimp2)
      hence q = q' by (simp add: gcopy-def)
      hence q' \in Final \ \mathcal{A} using \langle q \in Final \ \mathcal{A} \rangle by simp
    }
    moreover
    {
      assume q \in gcopy \mathcal{A} 'Final \mathcal{A}
      then obtain q'' where gcopy \mathcal{A} q' = gcopy \mathcal{A} q'' q'' \in Final \mathcal{A} by auto
      with A \langle q' \in Q | A \rangle inj-on-g have q' = q'' unfolding inj-on-def by blast
      with \langle q'' \in Final \ A \rangle have q' \in Final \ A by blast
    }
    ultimately show ?thesis using q unfolding double-init-def by fastsimp
  qed
  ultimately show ?thesis using \gamma A by auto
qed
lemma init-no-income-wlog:
  fixes \mathcal{A}
 assumes PA \mathcal{P} \mathcal{A}
 shows PA \mathcal{P} (double-init \mathcal{A}) init-no-income (double-init \mathcal{A}) \mathcal{L} \mathcal{A} = \mathcal{L} (double-init
\mathcal{A})
proof -
  from PA-double-init assms show PA \mathcal{P} (double-init \mathcal{A}) by simp
 from double-init-no-income assms show init-no-income (double-init \mathcal{A}) unfold-
ing init-no-income-def by blast
  from double-init-L-1 double-init-L-2 assms show \mathcal{L} \mathcal{A} = \mathcal{L} (double-init \mathcal{A})
```

```
unfolding language-def by auto
```

qed

A.6.2 Main Lemmas

```
First lemma

lemma Lemma1:

assumes PA \mathcal{P} \mathcal{A}

assumes A \mapsto \mathcal{A}'

assumes sat \mathcal{A}'

assumes (p, w) \Rightarrow (p, v)

assumes (p, v) \in \mathcal{L} \mathcal{A}

shows \exists q \in Final \mathcal{A}'. \mathcal{A}' \vdash p' - w \rightarrow * q

using assms(4)

proof (induct rule: converse-rtrancl-induct2)

case refl

from assms(2,5) show ?case by blast

next

case (step p' w p'' u)

show ?case
```

```
proof -
  from assms(1,2) have [simp]: PA \mathcal{P} \mathcal{A}' by auto
  with step (1) have [simp]: p'' \in Q \ \mathcal{A}' by blast
  from step(1) obtain \gamma w1 u1 where
    [simp]: w = \gamma \# w1 and [simp]: u = u1 @ w1
    and [simp]: (p', \gamma) \hookrightarrow (p'', u1)
    by (auto simp: PS-transition-rel-def)
  from step(3) obtain q where
    [simp]: q \in Final \ \mathcal{A}' \text{ and } \mathcal{A}' \vdash p'' - u \rightarrow * q
    by blast
  then obtain q1 where
    Split: \mathcal{A}' \vdash p'' - u1 \rightarrow * q1 \quad \mathcal{A}' \vdash q1 \quad -w1 \rightarrow * q
    by (auto elim: delta-append-elim[where \mathcal{P} = \mathcal{P}])
  hence [simp]: q1 \in Q \mathcal{A}'
    by (auto simp: delta-mem-constraints [where \mathcal{P} = \mathcal{P}])
  from Split(1) assms step have \mathcal{A}' \vdash p' - \gamma \rightarrow q1
    using sat-iff-nomem[of \mathcal{A}']
    by fastsimp
  from this Split(2) show \exists q \in Final \mathcal{A}'. \mathcal{A}' \vdash p' - w \rightarrow *q by auto
```

```
\mathbf{qed}
```

 \mathbf{qed}

second lemma

special induction lemma

This lemma is used to do induction on the number of times a new rule is used

lemma new-rule-induct: assumes [simp]: PA \mathcal{P} \mathcal{A} and Next: $\mathcal{A}' = \mathcal{A}(|\Delta := insert (p1, \gamma, q') (\Delta \mathcal{A})|)$ assumes $A: \mathcal{A}' \vdash p - w \rightarrow * q$ and $[simp]: p \in Control \mathcal{P}$ assumes Base-case: $\bigwedge p \ w$. $\llbracket p \in Control \ \mathcal{P}; \ \mathcal{A} \vdash p - w \rightarrow * q \rrbracket \implies P \ p \ w$ assumes *Step-case*: $\bigwedge u \ v \ p$. $\mathcal{A} \vdash p - u \rightarrow * p1;$ $p \in Control \mathcal{P};$ $\mathcal{A}' \vdash q' - v \rightarrow * q;$ $\land p2 w2. A \vdash p2 - w2 \rightarrow * q' \Longrightarrow p2 \in Control \mathcal{P} \Longrightarrow P p2 (w2@v)$ $\implies P \ p \ (u@\gamma \# v)$ shows P p wproof -{ fix vhave $\bigwedge qm \ u \ p$. $\llbracket p \in Control \ \mathcal{P}; \ \mathcal{A} \vdash p \ -u \rightarrow * qm; \ \mathcal{A}' \vdash qm \ -v \rightarrow * q \rrbracket \Longrightarrow P$ p(u@v)**proof** (*induct* v) case (Nil qh u) with Base-case show ?case by simp \mathbf{next} case (Cons e v qm u) note IHP=this

then obtain qh where $Split: \mathcal{A}' \vdash qm - e \rightarrow qh \mathcal{A}' \vdash qh - v \rightarrow *q$ by (auto intro: delta1-mem-constraints [where $\mathcal{P} = \mathcal{P}$]) show ?case proof (cases $(qm,e,qh) = (p1,\gamma,q')$) case False with Split(1) Next have $\mathcal{A} \vdash qm - e \rightarrow qh$ by auto hence $\mathcal{A} \vdash qm - [e] \rightarrow * qh$ by (simp add: delta-single2[where $\mathcal{P} = \mathcal{P}$]) with IHP(3) have $\mathcal{A} \vdash p - u@[e] \rightarrow * qh$ by blast with IHP(1,2) Split have P p ((u@[e])@v) by blast thus ?thesis by simp \mathbf{next} **case** True **note** CASE=this with Split IHP have $\mathcal{A} \vdash p - u \rightarrow p \neq p \land \mathcal{A}' \vdash q' - v \rightarrow q$ and $\bigwedge uu$. $\mathcal{A} \vdash p - uu \rightarrow * q' \Longrightarrow P p (uu@v)$ by auto with Step-case CASE Cons show ?thesis by auto qed qed **note**C=this**from** A C[of p [] p w] **show** ?thesis **by** (auto simp: delta.base[of p A] PA-Control[of $\mathcal{P} \mathcal{A} p])$



lemma ex-monotonic: $[\exists x. P x; \land x. P x \Longrightarrow P' x] \Longrightarrow \exists x. P' x$ by blast

```
lemma Lemma2:
  assumes \mathcal{A} \mapsto * \mathcal{A}'
  and init-no-income \mathcal{A}
  and \mathcal{A}' \vdash p - w \rightarrow * q
  and [simp]: PA \mathcal{P} \mathcal{A}
  and p \in Control \mathcal{P}
  shows \exists p' w'. (p, w) \Rightarrow (p', w') \land \mathcal{A} \vdash p' - w' \rightarrow q \land (q \in Control \mathcal{P} \longrightarrow q)
w' = \varepsilon) using assms
proof (induct arbitrary: p w q rule: rtrancl-induct)
  case base
  thus ?case
  proof (cases w = \varepsilon)
    from base(4)[simp] have [simp]: p \in Q \ A by (simp \ add: PA-Control] where
\mathcal{P} = \mathcal{P}])
    case False
    hence [simp]: butlast w @ [last w] = w by simp
    from base(2) obtain q1 where \mathcal{A} \vdash p -butlast w \rightarrow * q1
      and \mathcal{A} \vdash q1 -last w \rightarrow q
      using delta-append-elim[of \mathcal{A} p butlast w [last w] - - \mathcal{P}]
      by auto
   with (init-no-income \mathcal{A}) have \neg q \in Control \mathcal{P} by (auto intro: init-no-income-elim)
         - I don't understand why but it has to be used as an intro rule...
    with \langle \mathcal{A} \vdash p - w \rightarrow * q \rangle show ?thesis by blast
  ged auto — case w = \varepsilon is trivial
\mathbf{next}
  let ?P = \lambda \ p \ w \ q. \exists p' \ w'.
```

 $(p, w) \Rightarrow * (p', w') \land$ $\mathcal{A} \vdash \ p' - w' \!\! \to \!\! \ast \ q \ \wedge$ $(q \in Control \ \mathcal{P} \longrightarrow w' = \varepsilon)$ case (step $\mathcal{B} \mathcal{A}'$) from step(1) have [simp]: PA $\mathcal{P} \mathcal{B}$ by auto from $\langle \mathcal{B} \mapsto \mathcal{A}' \rangle$ obtain *p1* γ *q' p2 w2* where [simp]: $p1 \in Control \ \mathcal{P} \ \gamma \in \Sigma \ \mathcal{P} \ q' \in Q \ \mathcal{B} \ p2 \in Control \ \mathcal{P}$ and [simp]: $\mathcal{A}' = \mathcal{B}(\Delta := insert \ (p1, \ \gamma, \ q') \ (\Delta \ \mathcal{B}))$ and $(p1, \gamma) \hookrightarrow (p2, w2)$ and Bw2: $\mathcal{B} \vdash p2 - w2 \rightarrow * q'$ and $\mathcal{A}' \vdash p1 - \gamma \rightarrow q'$ **by** (*auto simp: pre-sat-rel-def*) let $?A' = \mathcal{B}(\Delta := insert \ (p1, \gamma, q') \ (\Delta \mathcal{B}))$ from step(2) have [simp]: PA \mathcal{P} ?A' by auto with step show ?case **proof** (induct rule: new-rule-induct [of \mathcal{B} ?A' p1 γ q' p w q], simp-all) fix u v passume $A'v: ?A' \vdash q' - v \rightarrow *q$ hence $[simp]: set v \subseteq \Sigma \mathcal{P}$ by (auto simp: delta-word-mem-constraints of $A' q' v q \mathcal{P}$) assume $\bigwedge p \ w \ q$. $\llbracket \mathcal{B} \vdash p \ -w \rightarrow * q$; $p \in Control \ \mathcal{P} \rrbracket \Longrightarrow ?P \ p \ w \ q$ $\mathcal{B} \vdash p - u \rightarrow * p1$ $p \in Control \mathcal{P}$ hence Pu: ?P p u p1 by blast assume IH: $\bigwedge p2 \ w2$. $[\mathcal{B} \vdash p2 \ -w2 \rightarrow * q'; \ \bigwedge p \ w \ q$. $[\mathcal{B} \vdash p \ -w \rightarrow * q; p \in$ Control \mathcal{P} \implies True; $?A' \vdash p2 - w2 @ v \rightarrow * q; p2 \in Control \mathcal{P}$ \implies ?P p2 (w2 @ v) q { from Pu have $(p, u) \Rightarrow * (p1, \varepsilon)$ by simp hence $(p, u @ \gamma \# v) \Rightarrow * (p1, \gamma \# v)$ using PS-transition-tr-append [of $\gamma \# v p u p 1 \varepsilon$] by simp moreover from $\langle (p1, \gamma) \hookrightarrow (p2, w2) \rangle$ have $(p1, \gamma \# v) \Rightarrow (p2, w2 @ v)$ by (auto simp: PS-transition-rel-def) ultimately have $(p, u @ \gamma \# v) \Rightarrow (p2, w2 @ v)$ by simp } moreover { from $Bw2 \langle \mathcal{B} \mapsto \mathcal{A}' \rangle$ have $?A' \vdash p2 - w2 \rightarrow *q'$ **by** (*auto dest: pre-sat-delta*) with A'v have $?A' \vdash p2 - w2 @ v \rightarrow *q$ by blast moreover have $\bigwedge p \ w \ q$. $\llbracket \mathcal{B} \vdash p \ -w \rightarrow * q$; $p \in Control \ \mathcal{P} \rrbracket \implies True \ by \ simp$ ultimately have P p2 (w2 @ v) qusing IH Bw2 by simp }

```
ultimately
show ?P p (u @ \gamma \# v) q
by (auto elim!: ex-monotonic)
qed
qed
```

A.6.3 Correctness

theorem *sat-correct*: assumes init-no-income Aand $\mathcal{A} \mapsto \mathcal{A}'$ and sat \mathcal{A}' and $PA \mathcal{P} \mathcal{A}$ shows $\mathcal{L} \mathcal{A}' = pre * (\mathcal{L} \mathcal{A})$ proof auto fix p wassume $(p,w) \in pre* (\mathcal{L} \mathcal{A})$ then obtain p'w' where $(p, w) \Rightarrow * (p', w') (p', w') \in \mathcal{L} \mathcal{A}$ and $[simp]: p \in Control \mathcal{P}$ **by** (*auto simp*: *prestar-def*) thus $(p, w) \in \mathcal{L} \mathcal{A}'$ unfolding language-def using Lemma1 and assms by blast \mathbf{next} fix p wfrom $\langle \mathcal{A} \mapsto \ast \mathcal{A}' \rangle$ have [simp]: Final $\mathcal{A}' = Final \mathcal{A}$ by blast assume $(p, w) \in \mathcal{L} \mathcal{A}'$ then obtain q where $\mathcal{A}' \vdash p - w \rightarrow * q$ and $[simp]: p \in Control \mathcal{P}$ and $[simp]: q \in Final \mathcal{A}'$ unfolding language-def by blast with Lemma2 assms obtain p' w' where $(p, w) \Rightarrow (p', w') \mathcal{A} \vdash p' - w' \rightarrow q$ by *metis* thus $(p, w) \in pre * \mathcal{L} \mathcal{A}$ unfolding language-def prestar-def using $\langle q \in Final \ \mathcal{A}' \rangle$ by (subgoal-tac $p' \in Control \mathcal{P}, auto)$ qed

A.6.4 Termination

lemma wf-bounded-measure: **fixes** ub :: 'a \Rightarrow nat and f :: 'a \Rightarrow nat **assumes** $\bigwedge a \ b. \ (b,a) : r \Longrightarrow ub \ b \le ub \ a \land ub \ a \ge f \ b \land f \ b > f \ a$ **shows** wf r **apply** (rule wf-subset[OF wf-measure[of $\lambda a. \ ub \ a - f \ a]])$ **apply**(auto dest: assms)**done** **lemma** wf-bounded-set: **fixes** ub :: 'a \Rightarrow 'b set **and** f :: 'a \Rightarrow 'b set **assumes** $\bigwedge a \ b. \ (b,a) : r \implies$ finite(ub a) \land ub b \subseteq ub a \land ub a \supseteq f b \land f b \supset f a **shows** wf r **apply** (rule wf-bounded-measure[of r $\lambda a. \ card(ub \ a) \ \lambda a. \ card(f \ a)])$ **apply** (drule assms) **apply** (blast intro: card-mono finite-subset psubset-card-mono dest: psubset-eq[THEN iffD2]) **done**

theorem insert-new: $x \notin A \implies A \neq insert \ x \ A$ by blast

```
theorem wf-sat-rel: wf \{(\mathcal{A}', \mathcal{A}), \mathcal{A} \mapsto \mathcal{A}'\}
proof (intro wf-bounded-set[of - \lambda A. Q A \times \Sigma P \times Q A \Delta], simp)
  fix \mathcal{A} \mathcal{A}'
  assume \mathcal{A} \mapsto \mathcal{A}'
  with pre-sat-PA pre-sat-Q pre-sat-delta1 pre-sat-Delta insert-new show
     finite (Q \ \mathcal{A} \times \Sigma \ \mathcal{P} \times Q \ \mathcal{A}) \land
       Q \ \mathcal{A}' \times \Sigma \ \mathcal{P} \times \ Q \ \mathcal{A}' \subseteq \ Q \ \mathcal{A} \times \Sigma \ \mathcal{P} \times \ Q \ \mathcal{A} \land
       \Delta \mathcal{A}' \subseteq \mathcal{Q} \mathcal{A} \times \Sigma \mathcal{P} \times \mathcal{Q} \mathcal{A} \wedge
       \Delta \ \mathcal{A} \subset \Delta \ \mathcal{A}'
     unfolding PA-def PS-def
     apply auto
     by (metis \langle \mathcal{A} \mapsto \mathcal{A}' \rangle in-measures(1) insert-new)
qed
corollary saturation:
  fixes \mathcal{A}
  assumes PA \mathcal{P} \mathcal{A}
  shows \exists \mathcal{A}'. PA \mathcal{P} \mathcal{A}' \land \mathcal{A} \mapsto * \mathcal{A}' \land sat \mathcal{A}'
unfolding sat-def using assms
proof (induct rule: wf-induct[OF wf-sat-rel], auto)
  fix x
  assume H0: PA \mathcal{P} x
  assume H1: \forall y. x \mapsto y \longrightarrow PA \mathcal{P} y \longrightarrow (\exists \mathcal{A}'. PA \mathcal{P} \mathcal{A}' \land y \mapsto \mathcal{A}' \land PA \mathcal{P}
\mathcal{A}' \land (\forall z. \neg \mathcal{A}' \mapsto z))
  show \exists \mathcal{A}'. PA \mathcal{P} \ \mathcal{A}' \land x \mapsto \mathcal{A}' \land PA \ \mathcal{P} \ \mathcal{A}' \land (\forall z. \neg \mathcal{A}' \mapsto z)
  proof (cases \forall z. \neg x \mapsto z)
     case True with H0 show ?thesis by blast
   next
     case False
     then obtain y where H3: x \mapsto y by blast
     with H0 have PA \mathcal{P} y by auto
     from H1[rule-format, where y = y, OF H3 this] obtain z
        where PA \mathcal{P} z and y \mapsto z and \bigwedge w. \neg z \mapsto w
        by blast
     with H3 show ?thesis by auto
  qed
qed
```

A.6.5 regular $C \implies regular (pre^* C)$

corollary regular $C \Longrightarrow$ regular (pre* C) proof assume regular C then obtain \mathcal{A} where $PA \mathcal{P} \mathcal{A}$ and $\mathcal{L} \mathcal{A} = C$ unfolding regular-def by blast then obtain \mathcal{A}' where $PA \mathcal{P} \mathcal{A}'$ and $\mathcal{L} \mathcal{A} = \mathcal{L} \mathcal{A}'$ and *init-no-income* \mathcal{A}' using *init-no-income-wlog* by *metis* from $\langle PA \ \mathcal{P} \ \mathcal{A}' \rangle$ obtain \mathcal{A}'' where $\mathcal{A}' \mapsto * \mathcal{A}''$ and sat $\mathcal{A}'' \ PA \ \mathcal{P} \ \mathcal{A}''$ using saturation by blast with $(PA \mathcal{P} \mathcal{A}')$ and $(init-no-income \mathcal{A}')$ and sat-correct have $\mathcal{L} \mathcal{A}'' = pre* (\mathcal{L} \mathcal{A})$ \mathcal{A}') by simp with $\langle \mathcal{L} | \mathcal{A} = C \rangle$ and $\langle \mathcal{L} | \mathcal{A} = \mathcal{L} | \mathcal{A}' \rangle$ have $\mathcal{L} | \mathcal{A}'' = pre * C$ by simp with $\langle PA \ \mathcal{P} \ \mathcal{A}'' \rangle$ show regular (pre* C) $\mathbf{unfolding} \ regular\text{-}def \ \mathbf{by} \ blast$ \mathbf{qed} \mathbf{end}

 \mathbf{end}

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